# NORMAL OPERATORS FOR MOMENTUM RAY TRANSFORMS, I: THE INVERSION FORMULA 

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#### Abstract

The momentum ray transform $I_{m}^{k}$ integrates a rank $m$ symmetric tensor field $f$ on $\mathbb{R}^{n}$ over lines with the weight $t^{k}, I_{m}^{k} f(x, \xi)=\int_{-\infty}^{\infty} t^{k}\left\langle f(x+t \xi), \xi^{m}\right\rangle \mathrm{d} t$. We compute the normal operator $N_{m}^{k}=\left(I_{m}^{k}\right)^{*} I_{m}^{k}$ and present an inversion formula recovering a rank $m$ tensor field $f$ from the data $\left(N_{m}^{0} f, \ldots, N_{m}^{m} f\right)$.


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## 1. Introduction

Let $\langle\cdot, \cdot\rangle$ be the standard dot product on $\mathbb{R}^{n}$ and $|\cdot|$, the corresponding norm.
For Schwartz class functions, the ray transform (also called the X-ray transform) is defined by

$$
\begin{equation*}
I f(x, \xi)=\int_{-\infty}^{\infty} f(x+t \xi) \mathrm{d} t \tag{1.1}
\end{equation*}
$$

for all $(x, \xi) \in \mathbb{R}^{n} \times \mathbb{R}^{n}$ satisfying $|\xi|=1$ and $\langle x, \xi\rangle=0$. For a Schwartz class symmetric $m$-tensor field $f=\left(f_{i_{1} \ldots i_{m}}\right)$, the ray transform is defined by

$$
\begin{align*}
I_{m} f(x, \xi) & =\int_{-\infty}^{\infty} f_{i_{1} \ldots i_{m}}(x+t \xi) \xi^{i_{1}} \ldots \xi^{i_{m}} \mathrm{~d} t \\
& =\int_{-\infty}^{\infty}\left\langle f(x+t \xi), \xi^{m}\right\rangle \mathrm{d} t \tag{1.2}
\end{align*}
$$

We use the Einstein summation rule to sum from 1 to $n$ over every repeated index in lower and upper positions in a monomial. In particular, when $m=0$, the definition (1.2) coincides with (1.1) and when $m=1$, (1.2) represents the ray transform of vector fields which is also called the Doppler transform.

In the case of $m=0$, the ray transform $I f$ uniquely determines a function $f$ and there is an explicit inversion formula. However, if $m \geq 1$, the ray transform $I_{m}$ has a nontrivial kernel. In particular, $I(\sigma \nabla h)=0$ whenever $h$ is a smooth symmetric $(m-1)$-tensor field on $\mathbb{R}^{n}$ decaying at infinity, $\nabla$ is the total covariant derivative, and $\sigma$ denotes the symmetrization of a tensor. A symmetric $m$-tensor field $f$ sufficiently fast decaying at infinity can be uniquely decomposed

$$
f=f^{s}+\sigma \nabla h, \quad h(x) \rightarrow 0 \text { as }|x| \rightarrow \infty
$$

to the solenoidal ( $=$ divergence-free) part $f^{s}$ and potential part $\sigma \nabla h$; see [Sha94, Theorem 2.6.2] and [PSU23, Theorem 6.4.7] for the detailed explanation in the Euclidean case as well as in the case of Riemannian manifolds. The solenoidal part of a symmetric $m$-tensor field $f$ can be uniquely determined from $I_{m} f$ and there is an explicit inversion formula [Sha94, Theorem 2.12.2].

It is natural to ask: what additional information required along with $I_{m} f$ so that one could recover the entire tensor field $f$. This leads to the notion of the momentum ray transform $I_{m}^{k}$ introduced in [Sha94, Section 2.17] by

$$
\begin{aligned}
I_{m}^{k} f(x, \xi) & =\int_{-\infty}^{\infty} t^{k} f_{i_{1} \ldots i_{m}}(x+t \xi) \xi^{i_{1}} \ldots \xi^{i_{m}} \mathrm{~d} t \\
& =\int_{-\infty}^{\infty} t^{k}\left\langle f(x+t \xi), \xi^{m}\right\rangle \mathrm{d} t \quad(k=0,1,2 \ldots)
\end{aligned}
$$

for all $(x, \xi) \in \mathbb{R}^{n} \times \mathbb{R}^{n}$ satisfying $|\xi|=1$ and $\langle x, \xi\rangle=0$. In particular $I_{m}^{0}=I_{m}$.
We restrict ourselves by considering the data ( $I_{m}^{0} f, \ldots, I_{m}^{m} f$ ) since, for $k>m$, the function $I_{m}^{k} f$ can be easily expressed through $I_{m}^{0} f, \ldots, I_{m}^{m} f$.

A rank $m$ symmetric tensor field $f$ is uniquely determined by the data $\left(I_{m}^{0} f, \ldots, I_{m}^{m} f\right)$. This was proved in [Sha94, Theorem 2.17.2]. Later this result was extended to a Helgason type support theorem for tensor fields on a simple real analytic Riemannian manifold [AM19]. An algorithm for recovering $f$ from the data $\left(I_{m}^{0} f, \ldots, I_{m}^{m} f\right)$ is presented in [KMSS19] as well as a stability estimate in (generalized) Sobolev norms. A range characterization for the operator $f \mapsto\left(I_{m}^{0} f, \ldots, I_{m}^{m} f\right)$ on the Schwartz space was established in [KMSS20].

Let us introduce the normal operator $N_{m}^{k}=\left(I_{m}^{k}\right)^{*} I_{m}^{k}$, where $\left(I_{m}^{k}\right)^{*}$ is the $L^{2}$-adjoint of the momentum ray transform $I_{m}^{k}$. Since $N_{m}^{k}$ is an averaging operator, the data $N_{m}^{k} f$ could represent a better measurement model rather than $I_{m}^{k} f$. We present an algorithm of recovering a rank $m$ tensor field $f$ from the data $\left(N_{m}^{0} f, \ldots, N_{m}^{m} f\right)$. In terms of Fourier transforms $\widehat{f}$ and $\left(\widehat{N_{m}^{0} f}, \ldots, \widehat{N_{m}^{m} f}\right)$, we derive the inversion formula

$$
\widehat{f}(y)=|y| \sum_{k=0}^{m} P_{m}^{k}\left(\widehat{N_{m}^{k} f}\right)
$$

with some linear operators $P_{m}^{k}$ on the space of rank $m$ symmetric tensor fields. Given $m$, the operators $P_{m}^{k}(k=0, \ldots, m)$ are calculated by explicit recurrent formulas; but the volume of calculations grows fast with $m$. We perform the calculations for $m=1,2,3$.

The ray transform has several important applications that include X-ray computer tomography (CT) in medical imaging when $m=0$. In the case of $m=1$, the ray transform is used in Doppler tomography to analyze vector fields. In cases where $m=2$ or $m=4$, the ray transform and its variants are applied to tomography problems in anisotropic media regarding the elasticity and Maxwell systems, see [Sha94] and [LS09, SW12]. Recently, the momentum ray transform has been adopted as a solution tool for the classical Calderón problem for the bi-Laplace model and other higher-order operators [BKS23, SS23, BK23]. The unique continuation principle for $I_{m}$ and $I_{m}^{k}$ is proved in [AKS22]. See also [IKS23] for a related work involving a fractional momentum operator.

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## 2. BASIC DEFINITIONS

First of all, mostly following [Sha94, Chapter 2], we introduce some notation and definitions concerning tensor algebra and analysis which will be used throughout the article.
2.1. Tensor algebra over $\mathbb{R}^{n}$. Let $T^{m} \mathbb{R}^{n}$ be the $n^{m}$-dimensional complex vector space of $m$-tensors on $\mathbb{R}^{n}$. In particular, $T^{0} \mathbb{R}^{n}=\mathbb{C}$ and $T^{1} \mathbb{R}^{n}=C^{n}$. We need complex tensors since we are going to use the Fourier transform. Assuming $n$ to be fixed, the notation $T^{m} \mathbb{R}^{n}$ will be mostly abbreviated to $T^{m}$. For a fixed orthonormal basis $\left(e_{1}, \ldots, e_{n}\right)$ of $\mathbb{R}^{n}$, by $u_{i_{1} \ldots i_{m}}=u^{i_{1} \ldots i_{m}}=u\left(e_{i_{1}}, \ldots, e_{i_{m}}\right)$ we denote coordinates ( $=$ components) of a tensor $u \in T^{m}$ with respect to the basis. There is no difference between covariant and contravariant tensors since we use orthonormal bases only. Given $u \in T^{m}$ and $v \in T^{k}$, the tensor product $u \otimes v \in T^{m+k}$ is defined by $(u \otimes v)_{i_{1} \ldots i_{m+k}}=u_{i_{1} \ldots i_{m}} v_{i_{m+1} \ldots i_{m+k}}$. The standard dot product on $\mathbb{R}^{n}$ extends to $T^{m}$ by $\langle u, v\rangle=u^{i_{1} \ldots i_{m}} \overline{v_{i_{1} \ldots i_{m}}}$. Throughout the article, the Einstein summation convention is used.

Let $S^{m}=S^{m} \mathbb{R}^{n}$ be the $\binom{n+m-1}{m}$-dimensional subspace of $T^{m}$ consisting of symmetric tensors. The partial symmetrization $\sigma\left(i_{1} \ldots i_{m}\right): T^{m+k} \rightarrow T^{m+k}$ in the indices $\left(i_{1}, \ldots, i_{m}\right)$ is defined by

$$
\sigma\left(i_{1} \ldots i_{m}\right) u_{i_{1} \ldots i_{m} j_{1} \ldots j_{k}}=\frac{1}{m!} \sum_{\pi \in \Pi_{m}} u_{i_{\pi(1)}, \ldots, i_{\pi(m)} j_{1} \ldots j_{k}}
$$

where the summation is performed over the group $\Pi_{m}$ of all substitutions of the set $\{1, \ldots, m\}$. In particular, $\sigma: T^{m} \rightarrow S^{m}$ is the symmetrization in all indices. Given $u \in S^{m}$ and $v \in S^{k}$, the symmetric product $u v \in S^{m+k}$ is defined by $u v=\sigma(u \otimes v)$. Being furnished with the symmetric product, $S^{*} \mathbb{R}^{n}=\bigoplus_{m=0}^{\infty} S^{m} \mathbb{R}^{n}$ becomes a commutative graded algebra that is called the algebra of symmetric tensors over $\mathbb{R}^{n}$. The algebra $S^{*} \mathbb{R}^{n}$ is canonically isomorphic to the algebra of polynomials on $\mathbb{R}^{n}$. Every statement on symmetric tensors can be translated to the langauge of polynomials, and vice versa.

Given $u \in S^{m}$, let $i_{u}: S^{k} \rightarrow S^{m+k}$ be the operator of symmetric multiplication by $u$ and let $j_{u}: S^{m+k} \rightarrow S^{k}$ be the adjoint of $i_{u}$. These operators are written in coordinates as

$$
\begin{aligned}
\left(i_{u} v\right)_{i_{1} \ldots i_{m+k}} & =\sigma\left(i_{1} \ldots i_{m+k}\right) u_{i_{1} \ldots i_{m}} v_{i_{m+1} \ldots i_{m+k}} \\
\left(j_{u} v\right)_{i_{1} \ldots i_{k}} & =v_{i_{1} \ldots i_{m+k}} u^{i_{k+1} \ldots i_{m+k}} .
\end{aligned}
$$

The tensor $j_{u} v$ will be also denoted by $v / u$. For the Kronecker tensor $\delta$, the notations $i_{\delta}$ and $j_{\delta}$ will be abbreviated to $i$ and $j$ respectively.
2.2. Tensor fields. Recall that the Schwartz space $\mathcal{S}\left(\mathbb{R}^{n}\right)$ is the topological vector space consisting of $C^{\infty}$-smooth complex-valued functions on $\mathbb{R}^{n}$ fast decaying at infinity together with all derivatives, furnished with the standard topology. Let $\mathcal{S}\left(\mathbb{R}^{n} ; S^{m}\right)=$ $\mathcal{S}\left(\mathbb{R}^{n}\right) \otimes S^{m}$ be the topological vector space of smooth fast decaying symmetric $m$-tensor fields, defined on $\mathbb{R}^{n}$, whose components belong to the Schwartz space. In Cartesian coordinates, such a tensor field is written as $f=\left(f_{i_{1} \ldots i_{m}}\right)$ with coordinates (= components) $f_{i_{1} \ldots i_{m}}=f^{i_{1} \ldots i_{m}} \in \mathcal{S}\left(\mathbb{R}^{n}\right)$ symmetric in all indices. We again emphasize that there is no difference between covariant and contravariant coordinates since we use Cartesian coordinates only.

We use the Fourier transform $\mathcal{F}: \mathcal{S}\left(\mathbb{R}^{n}\right) \rightarrow \mathcal{S}\left(\mathbb{R}^{n}\right), f \mapsto \widehat{f}$ in the form (hereafter $i$ is the imaginary unit)

$$
\mathcal{F} f(y)=\frac{1}{(2 \pi)^{n / 2}} \int_{\mathbb{R}^{n}} e^{-i(y, x\rangle} f(x) \mathrm{d} x .
$$

The Fourier transform $\mathcal{F}: \mathcal{S}\left(\mathbb{R}^{n} ; S^{m}\right) \rightarrow \mathcal{S}\left(\mathbb{R}^{n} ; S^{m}\right), f \mapsto \widehat{f}$ of symmetric tensor fields is defined component-wise: $\widehat{f}_{i_{1} \ldots i_{m}}=\widehat{f_{i_{1} \ldots i_{m}}}$.

Besides $\mathcal{S}\left(\mathbb{R}^{n} ; S^{m}\right)$, we use some other spaces of tensor fields. In particular, $C^{\infty}\left(U ; T^{m}\right)$ is the space of smooth $m$-tensor fields on an open set $U \subset \mathbb{R}^{n}$.See details in [Sha94, Section 2.1].

The $L^{2}$-product on $C_{0}^{\infty}\left(\mathbb{R}^{n} ; T^{m}\right)$ is defined by

$$
\begin{equation*}
(f, g)_{L^{2}\left(\mathbb{R}^{n} ; T^{m}\right)}=\int_{\mathbb{R}^{n}}\langle f(x), g(x)\rangle d x . \tag{2.1}
\end{equation*}
$$

### 2.3. Inner derivative and divergence. The first order differential operator

$$
d: C^{\infty}\left(\mathbb{R}^{n} ; S^{m}\right) \rightarrow C^{\infty}\left(\mathbb{R}^{n} ; S^{m+1}\right)
$$

defined by

$$
(d f)_{i_{1} \ldots i_{m+1}}=\sigma\left(i_{1} \ldots i_{m+1}\right) \frac{\partial f_{i_{1} \ldots i_{m}}}{\partial x^{i_{m+1}}}=\frac{1}{m+1}\left(\frac{\partial f_{i_{2} \ldots i_{m+1}}}{\partial x^{i_{1}}}+\cdots+\frac{\partial f_{i_{1} \ldots i_{m}}}{\partial x^{i_{m+1}}}\right)
$$

is called the inner derivative.

## The divergence

$$
\operatorname{div}: C^{\infty}\left(\mathbb{R}^{n} ; S^{m+1}\right) \rightarrow C^{\infty}\left(\mathbb{R}^{n} ; S^{m}\right)
$$

is defined by

$$
(\operatorname{div} f)_{i_{1} \ldots i_{m}}=\delta^{j k} \frac{\partial f_{i_{1} \ldots i_{m} j}}{\partial x^{k}} .
$$

The operators $d$ and -div are formally adjoint to each other with respect to the $L^{2}$ product (2.1). The divergence is denoted by $\delta$ in [Sha94]. But we will always use the notation div since some our formulas involve the divergence and Kronecker tensor simultaneously.
2.4. The space $\mathcal{S}\left(T \mathbb{S}^{n-1}\right)$. The Schwartz space $\mathcal{S}(E)$ is well defined for a smooth vector bundle $E \rightarrow M$ over a compact manifold with the help of a finite atlas and partition of unity subordinate to the atlas.

In particular, the Schwartz space $\mathcal{S}\left(T \mathbb{S}^{n-1}\right)$ is well defined for the tangent bundle

$$
T \mathbb{S}^{n-1}=\left\{(x, \xi) \in \mathbb{R}^{n} \times \mathbb{S}^{n-1}:\langle x, \xi\rangle=0\right\} \rightarrow \mathbb{S}^{n-1}, \quad(x, \xi) \mapsto \xi
$$

of the unit sphere $\mathbb{S}^{n-1}=\left\{x \in \mathbb{R}^{n}:|x|=1\right\}$.
The Fourier transform $\mathcal{F}: \mathcal{S}\left(T \mathbb{S}^{n-1}\right) \rightarrow \mathcal{S}\left(T \mathbb{S}^{n-1}\right), \varphi \mapsto \widehat{\varphi}$ is defined by

$$
\mathcal{F} \varphi(y, \xi)=\frac{1}{(2 \pi)^{(n-1) / 2}} \int_{\xi^{\perp}} e^{-i(y, x\rangle} \varphi(x, \xi) \mathrm{d} x,
$$

where $\mathrm{d} x$ is the $(n-1)$-dimensional Lebesgue measure on the hyperplane $\xi^{\perp}=\left\{x \in \mathbb{R}^{n}\right.$; $\langle\xi, x\rangle=0\}$. Notice that it is the standard Fourier transform in the ( $n-1$ )-dimensional variable $x$ while $\xi \in \mathbb{S}^{n-1}$ is considered as a parameter.
The $L^{2}$-product on $\mathcal{S}\left(T \mathbb{S}^{n-1}\right)$ is defined by

$$
\begin{equation*}
(\varphi, \psi)_{L^{2}\left(T \mathbb{S}^{n-1}\right)}=\int_{\mathbb{S}^{n-1}} \int_{\xi^{\perp}} \varphi(x, \xi) \overline{\psi(x, \xi)} \mathrm{d} x \mathrm{~d} \xi, \tag{2.2}
\end{equation*}
$$

where $\mathrm{d} \xi$ is the $(n-1)$-dimensional Euclidean volume form on the unit sphere $\mathbb{S}^{n-1}$.
2.5. Ray transforms. It is convenient to parameterize the family of oriented lines in $\mathbb{R}^{n}$ by points of the manifold $T \mathbb{S}^{n-1}$. Namely, a point $(x, \xi) \in T \mathbb{S}^{n-1}$ determines the line $\{x+t \xi: t \in \mathbb{R}\}$ through $x$ in the direction $\xi$.

The ray transform

$$
I_{m}: \mathcal{S}\left(\mathbb{R}^{n} ; S^{m}\right) \rightarrow \mathcal{S}\left(T \mathbb{S}^{n-1}\right)
$$

is the linear continuous operator defined by

$$
I_{m} f(x, \xi)=\int_{\mathbb{R}} f_{i_{1} \ldots i_{m}}(x+t \xi) \xi^{i_{1}} \ldots \xi^{i_{m}} \mathrm{~d} t=\int_{\mathbb{R}}\left\langle f(x+t \xi), \xi^{m}\right\rangle \mathrm{d} t .
$$

The ray transform is related to the Fourier transform by the important formula [Sha94, formula 2.1.15].

$$
\begin{equation*}
\widehat{I_{m} f}(y, \xi)=(2 \pi)^{1 / 2}\left\langle\widehat{f}(y), \xi^{m}\right\rangle \quad\left((y, \xi) \in T \mathbb{S}^{n-1}\right) . \tag{2.3}
\end{equation*}
$$

For $0 \leq k \leq m$, the momentum ray transform

$$
I_{m}^{k}: \mathcal{S}\left(\mathbb{R}^{n} ; S^{m}\right) \rightarrow \mathcal{S}\left(T \mathbb{S}^{n-1}\right)
$$

is the linear continuous operator defined by

$$
\begin{equation*}
I_{m}^{k} f(x, \xi)=\int_{\mathbb{R}} t^{k} f_{i_{1} \ldots i_{m}}(x+t \xi) \xi^{i_{1}} \ldots \xi^{i_{m}} \mathrm{~d} t=\int_{\mathbb{R}} t^{k}\left\langle f(x+t \xi), \xi^{m}\right\rangle \mathrm{d} t . \tag{2.4}
\end{equation*}
$$

The formula (2.3) is generalized as follows [KMSS19, formula (2.9)]:

$$
\widehat{I_{m}^{k} f}(y, \xi)=(2 \pi)^{1 / 2} i^{k}\left\langle d^{k} \widehat{f}(y), \xi^{m+k}\right\rangle \quad\left((y, \xi) \in T \mathbb{S}^{n-1}\right)
$$

As we will see later, $I_{m}^{k}$ should be considered together with lower degree operators $I_{m}^{0}, \ldots, I_{m}^{k-1}$, i.e., the collection $\left(I_{m}^{0} f, \ldots, I_{m}^{k} f\right)$ represents more convenient information about $f$ than $I_{m}^{k} f$ alone.
2.6. Normal operators. The formal adjoint of the ray transform $I_{m}$ with respect to $L^{2}$-products (2.1) and (2.2)

$$
I_{m}^{*}: \mathcal{S}\left(T \mathbb{S}^{n-1}\right) \rightarrow C^{\infty}\left(\mathbb{R}^{n} ; S^{m}\right)
$$

is expressed by

$$
\left(I_{m}^{*} \varphi\right)_{i_{1} \ldots i_{m}}(x)=\int_{\mathbb{S}^{n-1}} \xi_{i_{1}} \ldots \xi_{i_{m}} \varphi(x-\langle x, \xi\rangle \xi, \xi) \mathrm{d} \xi .
$$

We emphasize that, for $\varphi \in \mathcal{S}\left(T \mathbb{S}^{n-1}\right)$, the tensor field $I_{m}^{*} \varphi$ does not need fast decay at infinity.

Similarly, the formal $L^{2}$-adjoint of the momentum ray transform $I_{m}^{k}$

$$
\left(I_{m}^{k}\right)^{*}: \mathcal{S}\left(T \mathbb{S}^{n-1}\right) \rightarrow C^{\infty}\left(\mathbb{R}^{n} ; S^{m}\right)
$$

is expressed by

$$
\begin{equation*}
\left(\left(I_{m}^{k}\right)^{*} \varphi\right)_{i_{1} \ldots i_{m}}(x)=\int_{\mathbb{S}^{n-1}}\langle x, \xi\rangle^{k} \xi_{i_{1}} \ldots \xi_{i_{m}} \varphi(x-\langle x, \xi\rangle \xi, \xi) \mathrm{d} \xi \tag{2.5}
\end{equation*}
$$

Let

$$
N_{m}=I_{m}^{*} I_{m}: \mathcal{S}\left(\mathbb{R}^{n} ; S^{m}\right) \rightarrow C^{\infty}\left(\mathbb{R}^{n} ; S^{m}\right)
$$

be the normal operator for the ray transform $I_{m}$. Similarly, let

$$
N_{m}^{k}=\left(I_{m}^{k}\right)^{*} I_{m}^{k}: \mathcal{S}\left(\mathbb{R}^{n} ; S^{m}\right) \rightarrow C^{\infty}\left(\mathbb{R}^{n} ; S^{m}\right)
$$

be the normal operator for the momentum ray transform $I_{m}^{k}$.

Given $f \in \mathcal{S}\left(\mathbb{R}^{n} ; S^{m}\right)$, the tensor field $N_{m}^{k} f$ does not grow too fast at infinity, i.e., the estimate

$$
\left|N_{m}^{k} f(x)\right| \leq C(1+|x|)^{N}
$$

holds with some constants $C$ and $N$. In particular, $N_{m}^{k} f$ can be considered as a tempered tensor field-distribution, i.e., $N_{m}^{k} f \in \mathcal{S}^{\prime}\left(\mathbb{R}^{n} ; S^{m}\right)$. Hence the Fourier transform $\widehat{N_{m}^{k} f} \in$ $\mathcal{S}^{\prime}\left(\mathbb{R}^{n} ; S^{m}\right)$ is well defined at least in the distribution sense. We will show that, for $f \in \mathcal{S}\left(\mathbb{R}^{n} ; S^{m}\right)$, the restriction of $\widehat{N_{m}^{k} f}$ to $\mathbb{R}^{n} \backslash\{0\}$ belongs to $C^{\infty}\left(\mathbb{R}^{n} \backslash\{0\} ; S^{m}\right)$.

The operator $N_{m}$ was computed in [Sha94, formula 2.11.3] where the notation $\mu^{m}$ was used instead of $I_{m}^{*}$. In Section 4, we will derive a similar formula for $N_{m}^{k}$. In [AKS22], a similar expression for the normal operator is considered to study the unique continuation principle for momentum ray transforms.

## 3. Main Results

We start with inversion formulas for vector fields and for second rank symmetric tensor fields.

Theorem 3.1. A vector field $f \in \mathcal{S}\left(\mathbb{R}^{n} ; \mathbb{C}^{n}\right)(n \geq 2)$ is recovered from the data $\left(N_{1}^{0} f, N_{1}^{1} f\right)$ by the inversion formula

$$
\begin{equation*}
f(x)=\frac{2^{n / 2-1} \Gamma\left(\frac{n+1}{2}\right)}{\sqrt{\pi}}(-\Delta)^{1 / 2}\left[N_{1}^{0} f-\frac{1}{n-1} d j_{x} N_{1}^{0} f-\frac{1}{n-1} d \operatorname{div} N_{1}^{1} f\right] \tag{3.1}
\end{equation*}
$$

where $\Gamma$ is Euler's Gamma function and the operator $(-\Delta)^{1 / 2}$ is defined with the help of the Fourier transform by $|y| \mathcal{F}=\mathcal{F}(-\Delta)^{1 / 2}$. The vector field in brackets belongs to the domain of $(-\Delta)^{1 / 2}$.
Theorem 3.2. A tensor field $f \in \mathcal{S}\left(\mathbb{R}^{n} ; S^{2}\right)$ is recovered from the data $\left(N_{2}^{0} f, N_{2}^{1} f, N_{2}^{2} f\right)$ by the inversion formula

$$
\begin{align*}
f(x)=\frac{2^{n / 2-1} \Gamma\left(\frac{n+3}{2}\right)}{\sqrt{\pi}}(-\Delta)^{1 / 2}[ & N_{2}^{0} f-\frac{1}{n+1} i j N_{2}^{0} f  \tag{3.2}\\
& -\frac{2}{n+1} d\left(j_{x} N_{2}^{0} f+\operatorname{div} N_{2}^{1} f\right) \\
& \left.+\frac{1}{(n-1)(n+1)} d^{2}\left(j_{x}^{2} N_{2}^{0} f-2 j_{x} \operatorname{div} N_{2}^{1} f+\frac{1}{2} \operatorname{div}^{2} N_{2}^{2} f\right)\right]
\end{align*}
$$

The tensor field in brackets belongs to the domain of $(-\Delta)^{1 / 2}$.
We use the definition

$$
(2 l+1)!!=1 \cdot 3 \cdots(2 l+1), \quad(-1)!!=1
$$

For tensor fields of arbitrary rank, our result is as follows.
Theorem 3.3. Given integers $m \geq 0$ and $n \geq 2$, the Fourier transform of a tensor field $f \in \mathcal{S}\left(\mathbb{R}^{n} ; S^{m}\right)$ is recovered from the data $\left(\widehat{N_{m}^{0} f}, j_{y} \widehat{N_{m}^{0} f}, \ldots, j_{y}^{m} \widehat{N_{m}^{m} f}\right)$ by the algorithm consisting of three steps.

1. Compute tensor fields $F^{(m, k)} \in C^{\infty}\left(\mathbb{R}^{n} \backslash\{0\} ; S^{m-k}\right)(0 \leq k \leq m)$ by

$$
\begin{equation*}
F^{(m, k)}(y)=\frac{c_{m, n}}{k!} j_{y}^{k} \widehat{N_{m}^{k} f}(y), \quad c_{m, n}=\pi^{-1 / 2}(2 m-1)!!2^{m+n / 2-2} \Gamma\left(\frac{2 m+n-1}{2}\right) . \tag{3.3}
\end{equation*}
$$

2. Compute tensor fields $H^{(m, k)} \in C^{\infty}\left(\mathbb{R}^{n} \backslash\{0\} ; S^{m-k}\right)(0 \leq k \leq m)$ by

$$
\begin{equation*}
H^{(m, k)}=\frac{(2 m-2 k-1)!!(n+2 m-2 k-3)!!}{(2 m-1)!!(n+2 m-3)!!} \sum_{p=0}^{k}(-1)^{p}\binom{k}{p} \operatorname{div}^{k-p} F^{(m, p)} \tag{3.4}
\end{equation*}
$$

3. Recover $\widehat{f}$ by the formula

$$
\begin{align*}
\widehat{f}(y)=\frac{|y|}{m!} & {\left[\frac{1}{(2 m-1)!!} H^{(m, 0)}(y)\right.} \\
& \left.+\sum_{k=1}^{m} \frac{(-1)^{k}}{(2 m-2 k-1)!!}\binom{m}{k} \sum_{p=0}^{\min (k, m-k)} \frac{(-1)^{p}}{2^{p}}\binom{m-k}{p} i^{p} i_{y}^{k-p} j_{y}^{p} H^{(m, k)}(y)\right] . \tag{3.5}
\end{align*}
$$

Of course, (3.3)-(3.5) can be combined to give a formula that expresses the rank $m$ symmetric tensor field $\widehat{f}$ through ( $\left.\widehat{N_{m}^{0} f}, j_{y} \widehat{N_{m}^{0} f}, \ldots, j_{y}^{m} \widehat{N_{m}^{m} f}\right)$ that does not involve $F^{(m, k)}$ and $H^{(m, k)}$. We will present the latter formula for $m=1,2,3$ in the last section. The proof of Theorems 3.1 and 3.2 is also presented in the last section. Formulas (3.1) and (3.2) are obtained from (3.5) just by applying the inverse Fourier transform; nevertheless, some commutator formulas for the Fourier transform and operators participating in (3.5) should be used.

The rest of the article is mostly devoted to the proof of Theorem 3.3. Now, we discuss the scheme of the proof.

We introduce the tensor fields

$$
\begin{equation*}
A^{(m, k)} \in C^{\infty}\left(\mathbb{R}^{n} \backslash\{0\} ; S^{2 m-k}\right) \quad(0 \leq k \leq m) \tag{3.6}
\end{equation*}
$$

by

$$
\begin{equation*}
A^{(m, k)}(y)=d^{2 m-k}|y|^{2 m-2 k-1} . \tag{3.7}
\end{equation*}
$$

These tensor fields play an important role in all our arguments.
In the next section, we compute the normal operators $N_{m}^{k}(0 \leq k \leq m)$ and prove that a tensor field $f \in \mathcal{S}\left(\mathbb{R}^{n} ; S^{m}\right)$ satisfies $A^{(m, 0)} /\left(d^{k} \widehat{f}\right)=F^{(m, k)}$, where $F^{(m, k)}$ is defined by
 equation in the form

$$
\begin{equation*}
A^{(m, 0)} /\left(d^{k} g\right)=F^{(m, k)} \quad(0 \leq k \leq m) \tag{3.8}
\end{equation*}
$$

Given the data $\left(F^{(m, 0)}, \ldots, F^{(m, m)}\right)$, we consider (3.8) as a system of linear equations for the unknown tensor field $g$.

The first equation of the system (3.8)

$$
A^{(m, 0)}(y) / g(y)=F^{(m, 0)}(y) \quad\left(y \in \mathbb{R}^{n} \backslash\{0\}\right)
$$

is a pure algebraic equation. More precisely, being written in coordinates, it constitutes a system of linear algebraic equations in the components of the tensor field $g(y)$ with coefficients depending on $y$. The system was considered in [Sha94, Theorem 2.12.1] where the tensor field $\varepsilon^{m}(y)=\frac{|y|}{\left((2 m-1)!!^{2}\right.} d^{2 m}|y|^{2 m-1}$ was used instead of $A^{(m, 0)}$. It allows to determine the tangential part of the tensor field $g$ which corresponds to the solenoidal part of $f=\mathcal{F}^{-1} g$ (see [Sha94, Section 2.6] for the definition of the tangential part).

The second equation of the system (3.8), $A^{(m, 1)} /(d g)=F^{(m, 1)}$, constitutes a system of linear first order PDEs in components of the tensor field $g$, the third equation constitutes a system of linear second order PDEs, and so on.

At first sight, the following statement may seem incredible. The system (3.8) can be reduced to the purely algebraic system

$$
\begin{equation*}
A^{(m, k)} / g=H^{(m, k)} \quad(0 \leq k \leq m) \tag{3.9}
\end{equation*}
$$

with right-hand side defined by (3.4). The reduction is presented in Section 5. The precise sense of the reduction is expressed by Proposition 5.3 below; see also the paragraph after Proposition 5.3.

Some consistency conditions should be imposed on right-hand side $H^{(m, k)}$ for solvability of the system (3.9). In the case of a general $m$, it is not easy to write down the consistency conditions explicitly. Fortunately, we do not need to know the consistency conditions; in our setting, the system (3.9) has a solution by Propositions 4.3 and 5.3 presented below. If the system (3.9) has a solution, then the solution is unique and is expressed by (3.5) with $\widehat{f}=g$. This fact is proved in Section 6 .

## 4. Normal operator

We start with the proof of (2.5). For $f \in \mathcal{S}\left(\mathbb{R}^{n} ; S^{m}\right)$ and $\varphi \in \mathcal{S}\left(T \mathbb{S}^{n-1}\right)$,

$$
\begin{align*}
\left(I_{m}^{k} f, \varphi\right)_{L^{2}\left(T \mathbb{S}^{n-1}\right)} & =\int_{\mathbb{S}^{n-1}} \int_{\xi^{\perp}}\left(I_{m}^{k} f\right)(x, \xi) \overline{\varphi(x, \xi)} \mathrm{d} x \mathrm{~d} \xi \\
& =\int_{\mathbb{S}^{n-1}} \int_{\xi^{\perp}} \int_{-\infty}^{\infty} t^{k}\left\langle f\left(x^{\prime}+t \xi\right), \xi^{m}\right\rangle \overline{\varphi\left(x^{\prime}, \xi\right)} \mathrm{d} t \mathrm{~d} x^{\prime} \mathrm{d} \xi . \tag{4.1}
\end{align*}
$$

We transform the inner integral by the change $x=x^{\prime}+t \xi$ of integration variables

$$
\begin{aligned}
\int_{\xi^{\perp}} \int_{-\infty}^{\infty} t^{k}\left\langle f\left(x^{\prime}+t \xi\right), \xi^{m}\right\rangle \overline{\varphi\left(x^{\prime}, \xi\right)} \mathrm{d} t \mathrm{~d} x^{\prime} & =\int_{\mathbb{R}^{n}}\langle x, \xi\rangle^{k}\left\langle f(x), \xi^{m}\right\rangle \overline{\varphi(x-\langle x, \xi\rangle \xi, \xi)} \mathrm{d} x \\
& =\int_{\mathbb{R}^{n}} f^{i_{1} \ldots i_{m}}(x) \xi_{i_{1}} \ldots \xi_{i_{m}} \overline{\varphi(x-\langle x, \xi\rangle \xi, \xi)} \mathrm{d} x .
\end{aligned}
$$

Substituting this expression into (4.1), we obtain

$$
\begin{aligned}
\left(I_{m}^{k} f, \varphi\right)_{L^{2}\left(T \mathbb{S}^{n-1}\right)} & =\int_{\mathbb{R}^{n}} f^{i_{1} \ldots i_{m}}(x) \overline{\int_{\mathbb{S}^{n-1}} \xi_{i_{1}} \ldots \xi_{i_{m}} \varphi(x-\langle x, \xi\rangle \xi, \xi) \mathrm{d} \xi \mathrm{~d} x} \\
& =\left(f,\left(I_{m}^{k}\right)^{*} \varphi\right)_{L^{2}\left(\mathbb{R}^{n} ; S^{m}\right)} .
\end{aligned}
$$

This proves (2.5).
Recall that $N_{m}^{k}=\left(I_{m}^{k}\right)^{*} I_{m}^{k}$ is the normal operator for the momentum ray transform.
Proposition 4.1. Let $0 \leq k \leq m$ and $n \geq 2$. For a tensor field $f \in \mathcal{S}\left(\mathbb{R}^{n} ; S^{m}\right)$,

$$
\begin{equation*}
\left(N_{m}^{k} f\right)_{i_{1} \ldots i_{m}}(x)=2 \sum_{l=0}^{k}\binom{k}{l}\left(x^{k+l} f\right)^{j_{1} \ldots j_{m} p_{1} \ldots p_{k+l}} * \frac{\left(x^{2 m+k+l}\right)_{i_{1} \ldots i_{m} j_{1} \ldots j_{m} p_{1} \ldots p_{k+l}}^{|x|^{2 m+2 l+n-1}}, ~}{\text { and }} \tag{4.2}
\end{equation*}
$$

where $*$ denotes the convolution.
The right-hand side of (4.2) needs the following comment. For $x \in \mathbb{R}^{n}$, according to our definition of the symmetric product, $x^{k+l} \in S^{k+l}$ with coordinates $\left(x^{k+l}\right)^{p_{1} \ldots p_{k+l}}=$ $x^{p_{1}} \ldots x^{p_{k+l}}$. Therefore, for $f \in S^{m}$,

$$
\left(x^{k+l} f\right)^{j_{1} \ldots j_{m} p_{1} \ldots p_{k+l}}=\sigma\left(j_{1} \ldots j_{m} p_{1} \ldots p_{k+l}\right)\left(x^{p_{1}} \ldots x^{p_{k+l}} f^{j_{1} \ldots j_{m}}\right)
$$

Before proving Proposition 4.1, we observe that it implies some regularity of the tensor field $N_{m}^{k} f$. Indeed, the first factor $\left(x^{k+l} f\right)^{j_{1} \ldots j_{m} p_{1} \ldots p_{k+l}}$ on the right-hand side of (4.2) belongs to $\mathcal{S}\left(\mathbb{R}^{n}\right)$. The second factor is a function locally summable over $\mathbb{R}^{n}$ and bounded for $|x| \geq 1$. Hence the second factor can be considered as an element of the space $\mathcal{S}^{\prime}\left(\mathbb{R}^{n}\right)$ of tempered distributions. As is well known [Vla79], for $u \in \mathcal{S}\left(\mathbb{R}^{n}\right)$ and $v \in \mathcal{S}^{\prime}\left(\mathbb{R}^{n}\right)$, the convolution $u * v$ is defined and belongs to the space of smooth functions whose every derivative increases at most as a polynomial at infinity. In this case, the standard formula is valid: $\widehat{u * v}=\widehat{u v}$. Thus, we can state that

$$
N_{m}^{k}: \mathcal{S}\left(\mathbb{R}^{n} ; S^{m}\right) \rightarrow C^{\infty}\left(\mathbb{R}^{n} ; S^{m}\right)
$$

is a continuous operator.
To prove Proposition 4.1 we need the following
Lemma 4.2. Let $k \geq 0$ be an integer, $0 \neq a \in \mathbb{R}$, and $b \in \mathbb{R}$. Then

$$
\sum_{l=0}^{k}(-1)^{l}\binom{k}{l} \frac{\left(a^{2}+b\right)^{2 k-l}}{a^{2 k-2 l}}=\sum_{l=0}^{k}\binom{k}{l} \frac{b^{k+l}}{a^{2 l}}
$$

Proof. By the binomial formula,

$$
\begin{aligned}
\sum_{l=0}^{k}(-1)^{l}\binom{k}{l} \frac{\left(a^{2}+b\right)^{2 k-l}}{a^{2 k-2 l}} & =\frac{1}{a^{2 k}} \sum_{l=0}^{k}\binom{k}{l}\left(-a^{2}\right)^{l}\left(a^{2}+b\right)^{2 k-l} \\
& =\frac{1}{a^{2 k}} \sum_{l=0}^{k}\binom{k}{l}\left(-a^{2}+b-b\right)^{l}\left(a^{2}+b\right)^{2 k-l} \\
& =\frac{\left(a^{2}+b\right)^{k}}{a^{2 k}} \sum_{l=0}^{k}\binom{k}{l}\left(-a^{2}+b-b\right)^{l}\left(a^{2}+b\right)^{k-l} \\
& =\frac{b^{k}\left(a^{2}+b\right)^{k}}{a^{2 k}}=\sum_{l=0}^{k}\binom{k}{l} \frac{b^{k+l}}{a^{2 l}}
\end{aligned}
$$

Proof of Proposition 4.1. Using (2.4) and (2.5), we first compute

$$
\begin{aligned}
\left(N_{m}^{k} f\right)_{i_{1} \ldots i_{m}}(x) & =\left(I_{m}^{k}\right)_{i_{1} \ldots i_{m}}^{*} I_{m}^{k} f(x) \\
& =\int_{\mathbb{S}^{n-1}}\langle x, \xi\rangle^{k} \xi_{i_{1}} \ldots \xi_{i_{m}}\left(I_{m}^{k} f\right)(x-\langle x, \xi\rangle \xi, \xi) \mathrm{d} \xi \\
& =\int_{\mathbb{S}^{n}-1} \int_{\mathbb{R}} t^{k}\langle x, \xi\rangle^{k} f^{j_{1} \ldots j_{m}}(x-\langle x, \xi\rangle \xi+t \xi) \xi_{j_{1}} \ldots \xi_{j_{m}} \xi_{i_{1}} \ldots \xi_{i_{m}} \mathrm{~d} t \mathrm{~d} \xi \\
& =2 \int_{\mathbb{S}^{n}-1} \int_{0}^{\infty} t^{k}\langle x, \xi\rangle^{k} f^{j_{1} \ldots j_{m}}(x-\langle x, \xi\rangle \xi+t \xi)\left(\xi^{2 m}\right)_{i_{1} \ldots i_{m} j_{1} \ldots j_{m}} \mathrm{~d} t \mathrm{~d} \xi .
\end{aligned}
$$

Replacing $t-\langle x, \xi\rangle$ by $t$ in the last integral, we have

$$
\begin{aligned}
\left(N_{m}^{k} f\right)_{i_{1} \ldots i_{m}}(x) & =2 \int_{\mathbb{S}^{n-1}} \int_{0}^{\infty}(t+\langle x, \xi\rangle)^{k}\langle x, \xi\rangle^{k} f^{j_{1} \ldots j_{m}}(x+t \xi)\left(\xi^{2 m}\right)_{i_{1} \ldots i_{m} j_{1} \ldots j_{m}} \mathrm{~d} t \mathrm{~d} \xi \\
& =2 \sum_{l=0}^{k}\binom{k}{l} \int_{\mathbb{S}^{n-1}} \int_{0}^{\infty} t^{l}\langle x, \xi\rangle^{2 k-l} f^{j_{1} \ldots j_{m}}(x+t \xi)\left(\xi^{2 m}\right)_{i_{1} \ldots i_{m} j_{1} \ldots j_{m}} \mathrm{~d} t \mathrm{~d} \xi
\end{aligned}
$$

Changing integration variables by

$$
x+t \xi=z, \quad t=|z-x|, \quad \xi=\frac{z-x}{|z-x|}, \quad \mathrm{d} t \mathrm{~d} \xi=|z-x|^{1-n} \mathrm{~d} z
$$

we obtain

$$
\left(N_{m}^{k} f\right)_{i_{1} \ldots i_{m}}(x)=2 \sum_{l=0}^{k}\binom{k}{l} \int_{\mathbb{R}^{n}}\langle x, z-x\rangle^{2 k-l}\left((z-x)^{2 m}\right)_{i_{1} \ldots i_{m} j_{1} \ldots j_{m}} \frac{f^{j_{1} \ldots j_{m}}(z)}{|z-x|^{2 m+2 k-2 l+n-1}} \mathrm{~d} z
$$

Let us write this in the form

$$
\begin{aligned}
& \left(N_{m}^{k} f\right)_{i_{1} \ldots i_{m}}(x) \\
& =2 \int_{\mathbb{R}^{n}}\left[\sum_{l=0}^{k}(-1)^{l}\binom{k}{l} \frac{\langle x, x-z\rangle^{2 k-l}}{|x-z|^{2 k-2 l}}\right]\left((z-x)^{2 m}\right)_{i_{1} \ldots i_{m} j_{1} \ldots j_{m}} \frac{f^{j_{1} \ldots j_{m}}(z)}{|z-x|^{2 m+n-1}} \mathrm{~d} z .
\end{aligned}
$$

By Lemma 4.2 with $a=|x-z|$ and $b=\langle z, x-z\rangle$,

$$
\begin{aligned}
\sum_{l=0}^{k}(-1)^{l}\binom{k}{l} \frac{\langle x, x-z\rangle^{2 k-l}}{|x-z|^{2 k-2 l}} & =\sum_{l=0}^{k}(-1)^{l}\binom{k}{l} \frac{\left(|x-z|^{2}+\langle z, x-z\rangle\right)^{2 k-l}}{|x-z|^{2 k-2 l}} \\
& =\sum_{l=0}^{k}\binom{k}{l} \frac{\langle z, x-z\rangle^{k+l}}{|x-z|^{2 l}}=\sum_{l=0}^{k}\binom{k}{l} \frac{\langle z, x-z\rangle^{k+l}}{|z-x|^{2 l}}
\end{aligned}
$$

Substitute this expression into the previous formula

$$
\left(N_{m}^{k} f\right)_{i_{1} \ldots i_{m}}(x)=2 \sum_{l=0}^{k}\binom{k}{l} \int_{\mathbb{R}^{n}}\langle z, x-z\rangle^{k+l}\left((x-z)^{2 m}\right)_{i_{1} \ldots i_{m} j_{1} \ldots j_{m}} \frac{f^{j_{1} \ldots j_{m}}(z)}{|x-z|^{2 m+2 l+n-1}} \mathrm{~d} z
$$

Then we represent the first factor of the integrand as follows

$$
\langle z, x-z\rangle^{k+l}=\left(z^{k+l}\right)^{p_{1} \ldots p_{k+l}}\left((x-z)^{k+l}\right)_{p_{1} \ldots p_{k+l}}
$$

Substituting this expression into the previous formula, we write the result in the form

$$
\begin{aligned}
& \left(N_{m}^{k} f\right)_{i_{1} \ldots i_{m}}(x) \\
& =2 \sum_{l=0}^{k}\binom{k}{l} \int_{\mathbb{R}^{n}}\left(z^{k+l} \otimes f(z)\right)^{p_{1} \ldots p_{k+l} j_{1} \ldots j_{m}} \frac{\left((x-z)^{2 m+k+l}\right)_{i_{1} \ldots i_{m} j_{1} \ldots j_{m} p_{1} \ldots p_{k+l}}}{|x-z|^{2 m+2 l+n-1}} \mathrm{~d} z
\end{aligned}
$$

We can replace $\left(z^{k+l} \otimes f(z)\right)^{p_{1} \ldots p_{k+l} j_{1} \ldots j_{m}}$ with $\left(z^{k+l} f(z)\right)^{j_{1} \ldots j_{m} p_{1} \ldots p_{k+l}}$ since the second factor in the integrand is symmetric in all indices. Hence

$$
\begin{aligned}
& \left(N_{m}^{k} f\right)_{i_{1} \ldots i_{m}}(x) \\
& =2 \sum_{l=0}^{k}\binom{k}{l} \int_{\mathbb{R}^{n}}\left(z^{k+l} f(z)\right)^{j_{1} \ldots j_{m} p_{1} \ldots p_{k+l}} \frac{\left((x-z)^{2 m+k+l}\right)_{i_{1} \ldots i_{m} j_{1} \ldots j_{m} p_{1} \ldots p_{k+l}}}{|x-z|^{2 m+2 l+n-1}} \mathrm{~d} z
\end{aligned}
$$

Every integral on the right-hand side is the convolution of $\left(x^{k+l} f\right)^{j_{1} \ldots j_{m} p_{1} \ldots p_{k+l}}$ with $\frac{\left(x^{2 m+k+l}\right)_{i_{1} \ldots i_{m} j_{1} \ldots j_{m} p_{1} \ldots p_{k+l}}}{|x|^{2 m+2 l+n-1}}$. We thus arrive at (4.2).
We use the abbreviated notation $\partial_{i_{1} \ldots i_{k}}=\frac{\partial^{k}}{\partial y_{1} \ldots \partial y^{i_{k}}}$ for partial derivatives. Recall that indices can be written either in lower position or in upper position. In particular, $\partial^{i_{1} \ldots i_{k}}=\partial_{i_{1} \ldots i_{k}}$. Recall that $j_{y}: S^{m} \rightarrow S^{m-1}$ is the operator of contraction with $y$,
see Subsection 2.1 where the operator $j_{u}$ is defined. For $0 \leq k \leq m$, tensor fields $A^{(m, k)} \in C^{\infty}\left(\mathbb{R}^{n} \backslash\{0\} ; S^{2 m-k}\right)$ are defined by (3.7) or in coordinates

$$
A_{i_{1} \ldots i_{2 m-k}}^{(m, k)}=\partial_{i_{1} \ldots i_{2 m-k}}|y|^{2 m-2 k-1} .
$$

Proposition 4.1 can be equivalently written in terms of Fourier transforms $\widehat{f}$ and $\widehat{N_{m}^{k} f}$.
Proposition 4.3. Let $0 \leq k \leq m$ and $n \geq 2$. For $f \in \mathcal{S}\left(\mathbb{R}^{n} ; S^{m}\right)$, the equation (3.8) holds with $g=\hat{f}$ and $F^{(m, k)}$ defined by (3.3).

Proof. Applying the Fourier transform to the equality (4.2), we obtain

$$
\widehat{N}_{m}^{k} f_{i_{1} \ldots i_{m}}=2 \sum_{l=0}^{k}\binom{k}{l} \widehat{\left(x^{k+l} f\right)^{j_{1} \ldots j_{m} p_{1} \ldots p_{k+l}} \mathcal{F}\left[\frac{\left(x^{2 m+k+l}\right)_{i_{1} \ldots i_{m} j_{1} \ldots j_{m} p_{1} \ldots p_{k+l}}}{|x|^{2 m+2 l+n-1}}\right] . ~ . ~ . ~}
$$

Using the standard properties of the Fourier transform [Hör83, Lemma 7.1.2]

$$
\widehat{x_{j} f}=i \partial_{j} \widehat{f}, \quad \widehat{\partial_{j} f}=i y_{j} \widehat{f}
$$

we transform our formula to the form

$$
\begin{aligned}
{\widehat{N_{m}^{k} f}}_{i_{1} \ldots i_{m}}=2(-1)^{m+k} \sum_{l=0}^{k}(-1)^{l}\binom{k}{l} & \sigma\left(j_{1} \ldots j_{m} p_{1} \ldots p_{k+l}\right)\left(\partial^{p_{1} \ldots p_{k+l}} \widehat{f}^{j_{1} \ldots j_{m}}\right) \\
& \times \partial_{i_{1} \ldots i_{m} j_{1} \ldots j_{m} p_{1} \ldots p_{k+l}} \mathcal{F}\left[|x|^{-2 m-2 l-n+1}\right] .
\end{aligned}
$$

Here we can omit the symmetrization $\sigma\left(j_{1} \ldots j_{m} p_{1} \ldots p_{k+l}\right)$ since the second factor $\partial_{i_{1} \ldots i_{m} j_{1} \ldots j_{m} p_{1} \ldots p_{k+l}} \mathcal{F}\left[|x|^{-2 m-2 l-n+1}\right]$ is symmetric in all indices. Thus,

$$
\begin{equation*}
\widehat{N}_{m}^{k} f_{i_{1} \ldots i_{m}}=2(-1)^{m+k} \sum_{l=0}^{k}(-1)^{l}\binom{k}{l}\left(\partial^{p_{1} \ldots p_{k+l}} \widehat{f}^{j_{1} \ldots j_{m}}\right) \partial_{i_{1} \ldots i_{m} j_{1} \ldots j_{m} p_{1} \ldots p_{k+l}} \mathcal{F}\left[|x|^{-2 m-2 l-n+1}\right] . \tag{4.3}
\end{equation*}
$$

Let $\mathcal{S}^{\prime}\left(\mathbb{R}^{n}\right)$ be the space of tempered distributions. Recall that $\lambda \mapsto|x|^{\lambda}$ is the meromorphic $\mathcal{S}^{\prime}\left(\mathbb{R}^{n}\right)$-valued function of $\lambda \in \mathbb{C}$ with simple poles at points $-n,-n-2,-n-4, \ldots$ The Fourier transform of $|x|^{\lambda}$ is expressed by

$$
\begin{aligned}
\mathcal{F}\left[|x|^{\lambda}\right] & =\frac{2^{\lambda+n / 2} \Gamma\left(\frac{\lambda+n}{2}\right)}{\Gamma(-\lambda / 2)}|y|^{-\lambda-n} \quad\left(\lambda,-\lambda-n \notin 2 \mathbb{Z}^{+}\right), \\
\mathcal{F}\left[|x|^{2 k}\right] & =(2 \pi)^{n / 2}(-\Delta)^{k} \delta \quad\left(k \in \mathbb{Z}^{+}\right),
\end{aligned}
$$

where $\delta$ is the Dirac function. In particular,

$$
\mathcal{F}\left[|x|^{-2 m-2 l-n+1}\right]=\frac{\Gamma\left(\frac{1-2 m-2 l}{2}\right)}{2^{2 m+2 l+n / 2-1} \Gamma\left(\frac{2 m+2 l+n-1}{2}\right)}|y|^{2 m+2 l-1} .
$$

Substitute this value into (4.3)

$$
\begin{align*}
{\widehat{N_{m}^{k}}}_{i_{1} \ldots i_{m}}(y)=\frac{(-1)^{m+k}}{2^{2 m+n / 2-2}} \sum_{l=0}^{k}\binom{k}{l} \frac{(-1)^{l} \Gamma\left(\frac{1-2 m-2 l}{2}\right)}{2^{2 l} \Gamma\left(\frac{2 m+2 l+n-1}{2}\right)} & \left(\partial_{i_{1} \ldots i_{m} j_{1} \ldots j_{m} p_{1} \ldots p_{k+l}}|y|^{2 m+2 l-1}\right)  \tag{4.4}\\
& \times \partial^{p_{1} \ldots p_{k+l}} \widehat{f}^{j_{1} \ldots j_{m}}(y) .
\end{align*}
$$

Let us contract the equation (4.4) with $y^{i_{1}} \ldots y^{i_{k}}$, i.e., multiply the equation by $y^{i_{1}} \ldots y^{i_{k}}$ and perform the summation over indices $i_{1} \ldots i_{k}$

$$
\begin{align*}
& \left(j_{y}^{k} \widehat{N_{m}^{k} f}\right)_{i_{k+1} \ldots i_{m}}(y)=\frac{(-1)^{m+k}}{2^{2 m+n / 2-2}} \sum_{l=0}^{k}\binom{k}{l} \frac{(-1)^{l} \Gamma\left(\frac{1-2 m-2 l}{2}\right)}{2^{2 l} \Gamma\left(\frac{2 m+2 l+n-1}{2}\right)}  \tag{4.5}\\
& \quad \times\left[y^{i_{1}} \ldots y^{i_{k}} \partial_{i_{1} \cdots i_{k}}\left(\partial_{i_{k+1} \ldots i_{m} j_{1} \ldots j_{m} p_{1} \ldots p_{k+l}}|y|^{2 m+2 l-1}\right)\right] \partial^{p_{1} \ldots p_{k+l}} \widehat{f}^{j_{1} \ldots j_{m}}(y) .
\end{align*}
$$

On the right-hand side, all summands corresponding to $l>0$ are equal to zero. Indeed, $\partial_{i_{k+1} \ldots i_{m} j_{1} \ldots j_{m} p_{1} \ldots p_{k+l}}|y|^{2 m+2 l-1}$ is the positively homogeneous function of degree $l-1$. By the Euler equation for homogeneous functions,

$$
y^{i_{1}} \ldots y^{i_{k}} \partial_{i_{1} \ldots i_{k}}\left(\partial_{i_{k+1} \ldots i_{m} j_{1} \ldots j_{m} p_{1} \ldots p_{k+l}}|y|^{2 m+2 l-1}\right)= \begin{cases}(-1)^{k} k!|y|^{2 m-1} & \text { if } l=0 \\ 0 & \text { if } l>0\end{cases}
$$

The formula (4.5) becomes

$$
\begin{equation*}
\left(j_{y}^{k} \widehat{N_{m}^{k} f}\right)_{i_{k+1} \ldots i_{m}}(y)=\frac{(-1)^{m} k!\Gamma\left(\frac{1-2 m}{2}\right)}{2^{2 m+n / 2-2} \Gamma\left(\frac{2 m+n-1}{2}\right)}\left(\partial_{i_{k+1} \ldots i_{m} j_{1} \ldots j_{m} p_{1} \ldots p_{k}}|y|^{2 m-1}\right) \partial^{p_{1} \ldots p_{k}} \widehat{f}^{j_{1} \ldots j_{m}}(y) . \tag{4.6}
\end{equation*}
$$

This is equivalent to (3.8).
Lemma 4.4. Let $0 \leq k \leq m$ and $n \geq 2$. Then $j_{y}^{k+1} \widehat{N_{m}^{k} f}(y)=0$ for any tensor field $f \in \mathcal{S}\left(\mathbb{R}^{n} ; S^{m}\right)$ and for any $y \in \mathbb{R}^{n}$.
Proof. The statement trivially holds in the case of $k=m$. In the case of $k<m$ we apply the operator $j_{y}$ to the equality (4.6)

$$
\left(j_{y}^{k+1} \widehat{N_{m}^{k} f}\right)_{i_{k+2} \ldots i_{m}}(y)=\frac{1}{C_{m}^{k}}\left[\left(y^{i_{k+1}} \partial_{i_{k+1}}\right)\left(\partial_{i_{k+2} \ldots i_{m} j_{1} \ldots j_{m} p_{1} \ldots p_{k}}|y|^{2 m-1}\right)\right] \partial^{p_{1} \ldots p_{k}} \widehat{f}^{j_{1} \ldots j_{m}}(y),
$$

where $C_{m}^{k}=(-1)^{m} k!\Gamma\left(\frac{1-2 m}{2}\right) /\left(2^{2 m+n / 2-2} \Gamma\left(\frac{2 m+n-1}{2}\right)\right)$. The expression in brackets is equal to zero since $\partial_{i_{k+2} \ldots i_{m j_{1}} \ldots j_{m} p_{1} \ldots p_{k}}|y|^{2 m-1}$ is a positively homogeneous function of zero degree.

From now on we can forget the momentum ray transform. The rest of the article is devoted to investigation of the system (3.8).

Lemma 4.4 implies that right-hand sides of equations (3.8) satisfy

$$
\begin{equation*}
j_{y} F^{(m, k)}(y)=0 \quad(0 \leq k \leq m) . \tag{4.7}
\end{equation*}
$$

Thus, equalities (4.7) constitute necessary conditions for existence of a solution $g \in$ $\mathcal{S}\left(\mathbb{R}^{n} ; S^{m}\right)$ to the system (3.8). Most probably, equalities (4.7) are necessary and sufficient consistency conditions for the system (3.8), but this fact is not proved.

## 5. Reduction of the system (3.8) to an algebraic system

Tensor fields $A^{(m, k)} \in C^{\infty}\left(\mathbb{R}^{n} \backslash\{0\} ; S^{2 m-k}\right)(0 \leq k \leq m)$ are defined by (3.7). There exist two important relations between these tensor fields.

Lemma 5.1. The following equalities are valid:

$$
\begin{gather*}
j_{y} A^{(m, k)}=-k A^{(m-1, k-1)} \quad(0 \leq k \leq m)  \tag{5.1}\\
\operatorname{div} A^{(m, k)}=(2 m-2 k-1)(n+2 m-2 k-3) A^{(m, k+1)} \quad(0 \leq k \leq m) \tag{5.2}
\end{gather*}
$$

Proof. Applying the operator $j_{y}$ to the equality (3.7), we have

$$
j_{y} A^{(m, k)}=j_{y} d^{2 m-k}|y|^{2 m-2 k-1} .
$$

With the help of the operator $\langle y, \partial\rangle=y^{j} \frac{\partial}{\partial y^{j}}$, the latter formula can be written as

$$
\begin{equation*}
j_{y} A^{(m, k)}=\langle y, \partial\rangle d^{2 m-k-1}|y|^{2 m-2 k-1} . \tag{5.3}
\end{equation*}
$$

The tensor field $d^{2 m-k-1}|y|^{2 m-2 k-1}$ is positively homogeneous of degree $-k$. By the Euler equation for homogeneous functions,

$$
\langle y, \partial\rangle d^{2 m-k-1}|y|^{2 m-2 k-1}=-k d^{2 m-k-1}|y|^{2 m-2 k-1}
$$

Substituting this expression into (5.3), we obtain

$$
j_{y} A^{(m, k)}=-k d^{2 m-k-1}|y|^{2 m-2 k-1} .
$$

By (3.6), the right-hand side of this formula is equal to $-k A^{(m-1, k-1)}$. This proves (5.1).
Let us write (3.7) in the coordinate form

$$
A_{i_{k+1} \ldots i_{2 m}}^{(m, k)}=\partial_{i_{k+1} \ldots i_{2 m}}|y|^{2 m-2 k-1} .
$$

Differentiate this equality

$$
\frac{\partial A_{i_{k+1} \ldots i_{2 m}}^{(m, k)}}{\partial y^{j}}=\partial_{j i_{k+1} \ldots i_{2 m}}|y|^{2 m-2 k-1}
$$

From this

$$
\begin{aligned}
\left(\operatorname{div} A^{(m, k)}\right)_{i_{k+2} \ldots i_{2 m}} & =\delta^{j l} \frac{\partial A_{l i_{k+2} \ldots i_{2 m}}^{(m, k)}}{\partial y^{j}}=\delta^{j l} \partial_{j l i_{k+2} \ldots i_{2 m}}|y|^{2 m-2 k-1} \\
& =\partial_{i_{k+2} \ldots i_{2 m}}\left(\Delta|y|^{2 m-2 k-1}\right) .
\end{aligned}
$$

This can be written in the coordinate-free form

$$
\begin{equation*}
\operatorname{div} A^{(m, k)}=d^{2 m-k-1}\left(\Delta|y|^{2 m-2 k-1}\right) \tag{5.4}
\end{equation*}
$$

Using the obvious formula

$$
\Delta|y|^{\alpha}=\alpha(\alpha+n-2)|y|^{\alpha-2},
$$

we obtain

$$
\Delta|y|^{2 m-2 k-1}=(2 m-2 k-1)(n+2 m-2 k-3)|y|^{2 m-2 k-3} .
$$

Substituting this expression into (5.4), we have

$$
\operatorname{div} A^{(m, k)}=(2 m-2 k-1)(n+2 m-2 k-3) d^{2 m-k-1}|y|^{2 m-2 k-3} .
$$

By (3.7),

$$
d^{2 m-k-1}|y|^{2 m-2 k-3}=A^{(m, k+1)} .
$$

Two last formulas imply (5.2).
From (5.2), one easily proves by induction on $k$

$$
\begin{equation*}
\operatorname{div}^{k} A^{(m, 0)}=\frac{(2 m-1)!!(n+2 m-3)!!}{(2 m-2 k-1)!!(n+2 m-2 k-3)!!} A^{(m, k)} \quad(0 \leq k \leq m) \tag{5.5}
\end{equation*}
$$

We reproduce the system (3.8)

$$
\begin{equation*}
A^{(m, 0)} /\left(d^{l} g\right)=F^{(m, l)} \quad(l=0,1, \ldots, m) \tag{5.6}
\end{equation*}
$$

Here $F^{(m, l)} \in C^{\infty}\left(\mathbb{R}^{n} \backslash\{0\} ; S^{m-l}\right)(0 \leq l \leq m)$ are arbitrary tensor fields belonging to the kernel of $j_{y}$.

Proposition 5.2. If a tensor field $g \in C^{\infty}\left(\mathbb{R}^{n} \backslash\{0\} ; S^{m}\right)$ satisfies (5.6), then

$$
\begin{equation*}
\left(\operatorname{div}^{k} A^{(m, 0)}\right) /\left(d^{l} g\right)=(-1)^{k} \sum_{p=0}^{k}(-1)^{p}\binom{k}{p} \operatorname{div}^{p} F^{(m, k+l-p)} \quad(0 \leq k \leq m, 0 \leq l \leq m-k) \tag{5.7}
\end{equation*}
$$

Proof. We prove (5.7) by induction on $k$. For $k=0$, (5.7) coincides with (5.6). Assume (5.7) to be valid for some $k$. Apply the operator div to the equation (5.7)

$$
\begin{equation*}
\operatorname{div}\left(\left(\operatorname{div}^{k} A^{(m, 0)}\right) /\left(d^{l} g\right)\right)=(-1)^{k} \sum_{p}(-1)^{p}\binom{k}{p} \operatorname{div}^{p+1} F^{(m, k+l-p)} \tag{5.8}
\end{equation*}
$$

We assume binomial coefficients to be defined for all integers $k$ and $p$ under the agreement:

$$
\begin{equation*}
\binom{k}{p}=0 \quad \text { if either } k<0 \text { or } p<0 \text { or } k<p \tag{5.9}
\end{equation*}
$$

Due to the agreement, we can assume the summation to be performed over all integers $p$ in (5.8) and formulas below.

The equality

$$
\operatorname{div}(u / v)=(\operatorname{div} u) / v+u /(d v)
$$

is valid for any two tensor fields. It is easily proved on the base of definitions of the operators $d$ and div. With the help of this equality, we write (5.8) in the form

$$
\left(\operatorname{div}^{k+1} A^{(m, 0)}\right) /\left(d^{l} g\right)+\left(\operatorname{div}^{k} A^{(m, 0)}\right) /\left(d^{l+1} g\right)=(-1)^{k} \sum_{p}(-1)^{p}\binom{k}{p} \operatorname{div}^{p+1} F^{(m, k+l-p)}
$$

By the induction hypothesis,

$$
\left(\operatorname{div}^{k} A^{(m, 0)}\right) /\left(d^{l+1} g\right)=(-1)^{k} \sum_{p}(-1)^{p}\binom{k}{p} \operatorname{div}^{p} F^{(m, k+l-p+1)}
$$

Substituting this expression into the previous formula, we write the result in the form

$$
\begin{aligned}
\left(\operatorname{div}^{k+1} A^{(m, 0)}\right) /\left(d^{l} g\right)= & (-1)^{k} \sum_{p}(-1)^{p}\binom{k}{p} \operatorname{div}^{p+1} F^{(m, k+l-p)} \\
& +(-1)^{k+1} \sum_{p}(-1)^{p}\binom{k}{p} \operatorname{div}^{p} F^{(m, k+l-p+1)} .
\end{aligned}
$$

Changing the summation variable of the first sum as $p:=p-1$, we obtain

$$
\left(\operatorname{div}^{k+1} A^{(m, 0)}\right) /\left(d^{l} g\right)=(-1)^{k+1} \sum_{p}(-1)^{p}\left[\binom{k}{p-1}+\binom{k}{p}\right] \operatorname{div}^{p} F^{(m, k+l-p+1)}
$$

By the Pascal triangle equality, $\binom{k}{p-1}+\binom{k}{p}=\binom{k+1}{p}$. Substituting this expression into the last formula, we arrive at (5.7) for $k:=k+1$.
Setting $l=0$ in (5.7), we obtain

$$
\left(\operatorname{div}^{k} A^{(m, 0)}\right) / g=(-1)^{k} \sum_{p=0}^{k}(-1)^{p}\binom{k}{p} \operatorname{div}^{p} F^{(m, k-p)} \quad(0 \leq k \leq m) .
$$

Substituting the value (5.5) of $\operatorname{div}^{k} A^{(m, 0)}$, we arrive at the equation

$$
A^{(m, k)} / g=(-1)^{k} \frac{(2 m-2 k-1)!!(n+2 m-2 k-3)!!}{(2 m-1)!!(n+2 m-3)!!} \sum_{p=0}^{k}(-1)^{p}\binom{k}{p} \operatorname{div}^{p} F^{(m, k-p)} .
$$

We have thus proved
Proposition 5.3. If a tensor field $g \in C^{\infty}\left(\mathbb{R}^{n} \backslash\{0\} ; S^{m}\right)$ satisfies (3.8), then it also solves the system (3.9) with right-hand sides defined by (3.4).

We emphasize that (3.9) is a system of linear algebraic equations in coordinates of the unknown tensor field $g$. Of course the system (3.9) is not equivalent to (3.8). Proposition 5.3 states that (3.8) implies (3.9) but not vice versa. Nevertheless, we will see that $g$ can be uniquely recovered from (3.9). In this sense the system (3.8) is reduced to the algebraic system (3.9).

## 6. Solution of the system (3.9)

The following statement completes the proof of Theorem 3.3.
Proposition 6.1. If the system (3.9) is solvable, then the solution $g=\widehat{f}$ is unique and is expressed by the formula (3.5).
The proof of Proposition 6.1 is not easy. The main part of the proof is contained in the following two lemmas.
Lemma 6.2. Given a tensor field $g \in C^{\infty}\left(\mathbb{R}^{n} \backslash\{0\} ; S^{m+1}\right)$, let us fix a Cartesian coordinate system on $\mathbb{R}^{n}$, fix a value of the index $i_{m+1}$ and introduce the tensor field $\tilde{g} \in C^{\infty}\left(\mathbb{R}^{n} \backslash\{0\} ; S^{m}\right)$ by

$$
\begin{equation*}
\tilde{g}_{i_{1} \ldots i_{m}}=g_{i_{1} \ldots i_{m} i_{m+1}} . \tag{6.1}
\end{equation*}
$$

Let us also introduce the vector field $\tilde{\delta}$ by

$$
\tilde{\delta}_{i}=\delta_{i i_{m+1}}
$$

Then, for every $0 \leq k \leq m$,

$$
\begin{align*}
\left(A^{(m, k)} / \tilde{g}\right)_{i_{k+1} \ldots i_{m}} & =\frac{1}{m+1}\left[\frac{1}{2 m-2 k+1}\left(A^{(m+1, k)} / g\right)_{i_{k+1} \ldots i_{m+1}}\right.  \tag{6.2}\\
& \left.-y_{i_{m+1}}\left(A^{(m+1, k+1)} / g\right)_{i_{k+1} \ldots i_{m}}-(m-k)\left(\tilde{\delta}\left(A^{(m, k)} / g\right)\right)_{i_{k+1} \ldots i_{m}}\right]
\end{align*}
$$

Proof. The identity

$$
\partial_{i_{1} \ldots i_{p}}\left(|y|^{\alpha} y_{k}\right)=y_{k} \partial_{i_{1} \ldots i_{p}}|y|^{\alpha}+p \sigma\left(i_{1} \ldots i_{p}\right)\left(\delta_{i_{1} k} \partial_{i_{2} \ldots i_{p}}|y|^{\alpha}\right)
$$

holds for any integer $p \geq 0$, any real $\alpha$ and any $1 \leq k \leq n$. It is easily proved by induction on $p$. With the help of this identity, we obtain

$$
\begin{aligned}
& \partial_{i_{k+1} \ldots i_{m+1} j_{1} \ldots j_{m+1}}|y|^{2 m-2 k+1}=(2 m-2 k+1) \partial_{i_{k+1} \ldots i_{m} j_{1} \ldots j_{m+1}}\left(|y|^{2 m-2 k-1} y_{i_{m+1}}\right) \\
& \quad=(2 m-2 k+1)\left[y_{i_{m+1}} \partial_{i_{k+1} \ldots i_{m} j_{1} \ldots j_{m+1}}|y|^{2 m-2 k-1}\right. \\
& \left.\quad+(2 m-k+1) \sigma\left(i_{k+1} \ldots i_{m} j_{1} \ldots j_{m+1}\right)\left(\delta_{i_{m+1} j_{m+1}} \partial_{i_{k+1} \ldots i_{m} j_{1} \ldots j_{m}}|y|^{2 m-2 k-1}\right)\right] .
\end{aligned}
$$

Expanding the symmetrization $\sigma\left(i_{k+1} \ldots i_{m} j_{1} \ldots j_{m+1}\right)$ with respect to the index $j_{m+1}$ (see [Sha94, Lemma 2.4.1]), we write this in the form

$$
\begin{gathered}
\frac{1}{2 m-2 k+1} \partial_{i_{k+1} \ldots i_{m+1} j_{1} \ldots j_{m+1}}|y|^{2 m-2 k+1}=y_{i_{m+1}} \partial_{i_{k+1} \ldots i_{m} j_{1} \ldots j_{m+1}}|y|^{2 m-2 k-1} \\
\quad+\sigma\left(i_{k+1} \ldots i_{m} j_{1} \ldots j_{m}\right)\left(\delta_{i_{m+1} j_{m+1}} \partial_{i_{k+1} \ldots i_{m} j_{1} \ldots j_{m}}|y|^{2 m-2 k-1}\right. \\
\left.\quad+(2 m-k) \delta_{i_{m+1} j_{1}} \partial_{i_{k+1} \ldots i_{m} j_{2} \ldots j_{m+1}}|y|^{2 m-2 k-1}\right) .
\end{gathered}
$$

Since the tensor $\delta_{i_{m+1} j_{m+1}} \partial_{i_{k+1} \ldots i_{m} j_{1} \ldots j_{m}}|y|^{2 m-2 k-1}$ is symmetric in $i_{k+1}, \ldots, i_{m}, j_{1}, \ldots, j_{m}$, the formula can be written as follows:

$$
\begin{align*}
& \frac{1}{2 m-2 k+1} \partial_{i_{k+1} \ldots i_{m+1} j_{1} \ldots j_{m+1}}|y|^{2 m-2 k+1}=y_{i_{m+1}} \partial_{i_{k+1} \ldots i_{m} j_{1} \ldots j_{m+1}}|y|^{2 m-2 k-1} \\
& +\delta_{i_{m+1} j_{m+1}} \partial_{i_{k+1} \ldots i_{m} j_{1} \ldots j_{m}}|y|^{2 m-2 k-1}  \tag{6.3}\\
& +(2 m-k) \sigma\left(i_{k+1} \ldots i_{m} j_{1} \ldots j_{m}\right)\left(\delta_{i_{m+1} j_{1}} \partial_{i_{k+1} \ldots i_{m} j_{2} \ldots j_{m+1}}|y|^{2 m-2 k-1}\right)
\end{align*}
$$

By (3.7),

$$
\begin{aligned}
\partial_{i_{k+1} \ldots i_{m} j_{1} \ldots j_{m+1}}|y|^{2 m-2 k-1} & =A_{i_{k_{1}}\left(\frac{1, i, i_{m} j_{1} \ldots j_{m+1}}{(m+1, k+1)}\right.}^{\partial_{i_{k+1} \ldots i_{m} j_{1} \ldots j_{m}}|y|^{2 m-2 k-1}}=A_{i_{k+1}, \ldots i_{m} j_{1} \ldots j_{m}}^{(m,} \\
\partial_{i_{k+1} \ldots i_{m} j_{2} \ldots j_{m+1}}|y|^{2 m-2 k-1} & =A_{i_{k+1} \ldots i_{m} j_{2} \ldots j_{m+1}}^{(m, k)}
\end{aligned}
$$

Substitute these expressions into (6.3)

$$
\begin{align*}
& \frac{1}{2 m-2 k+1} \partial_{i_{k+1} \ldots i_{m+1} j_{1} \ldots j_{m+1}}|y|^{2 m-2 k+1}=y_{i_{m+1}} A_{i_{k+1} \ldots i_{m} j_{1} \ldots j_{m+1}}^{(m+1, k+1)} \\
& +\delta_{i_{m+1} j_{m+1}} A_{i_{k+1} \ldots i_{m} j_{1} \ldots j_{m}}^{(m, k}  \tag{6.4}\\
& +(2 m-k) \sigma\left(i_{k+1} \ldots i_{m} j_{1} \ldots j_{m}\right)\left(\delta_{i_{m+1} j_{1}} A_{i_{k+1} \ldots i_{m} j_{2} \ldots j_{m+1}}^{(m, k)}\right)
\end{align*}
$$

The equality

$$
\begin{align*}
& \sigma\left(i_{k+1} \ldots i_{m} j_{1} \ldots j_{m}\right)\left(\delta_{i_{m+1} j_{1}} A_{i_{k+1} \ldots i_{m} j_{2} \ldots j_{m+1}}^{(m, k)}\right) \\
& =\frac{1}{2 m-k} \sigma\left(i_{k+1} \ldots i_{m}\right) \sigma\left(j_{1} \ldots j_{m}\right)\left[(m-k) \delta_{i_{m+1} i_{m}} A_{i_{k+1} \ldots i_{m-1} j_{1} \ldots j_{m+1}}^{(m, k)}\right.  \tag{6.5}\\
& \left.+m \delta_{i_{m+1} j_{1}} A_{i_{k+1} \ldots i_{m} j_{2} \ldots j_{m+1}}^{(m, k)}\right]
\end{align*}
$$

is easily proved on the base of the only fact: the tensor $A^{(m, k)}$ is symmetric. Formally speaking, the first term $(m-k) \delta_{i_{m+1} i_{m}} A_{i_{k+1} \ldots i_{m-1} j_{1} \ldots j_{m+1}}^{(m, k)}$ in brackets makes sense for $k \leq$ $m-2$ only. Nevertheless, the formula (6.5) holds for $k=m-1$ if we assume that $A_{i_{m} \ldots i_{m-1} j_{1} \ldots j_{m+1}}^{(m, k}=A_{j_{1} \ldots j_{m+1}}^{(m, k)}$. In the case of $k=m$, the first term in brackets is equal to zero because of the factor $(m-k)$. Thus, the formula (6.5) holds for all $0 \leq k \leq m$.

With the help of (6.5), the formula (6.4) becomes

$$
\begin{aligned}
& \frac{1}{2 m-2 k+1} \partial_{i_{k+1} \ldots i_{m+1} j_{1} \ldots j_{m+1}}|y|^{2 m-2 k+1}=y_{i_{m+1}} A_{i_{k+1} \ldots i_{m} \ldots j_{m+1}}^{(m+1, k+1)} \\
& +\delta_{i_{m+1} j_{m+1}} A_{i_{k+1} \ldots i_{m} j_{1} \ldots j_{m}}^{(m, k)} \\
& +(m-k) \sigma\left(i_{k+1} \ldots i_{m}\right) \sigma\left(j_{1} \ldots j_{m}\right)\left(\delta_{i_{m+1} i_{m}} A_{i_{k+1} \ldots i_{m-1} j_{1} \ldots j_{m+1}}^{(m, k)}\right) \\
& +m \sigma\left(i_{k+1} \ldots i_{m}\right) \sigma\left(j_{1} \ldots j_{m}\right)\left(\delta_{i_{m+1} j_{1}} A_{i_{k+1} \ldots i_{m} j_{2} \ldots j_{m+1}}^{(m, k)}\right) .
\end{aligned}
$$

On the last line, the symmetrization $\sigma\left(i_{k+1} \ldots i_{m}\right)$ can be deleted since the tensor $A_{i_{k+1} \ldots i_{m} j_{2} \ldots j_{m+1}}^{(m, k)}$ is symmetric in these indices. The formula simplifies to the following one:

$$
\begin{align*}
& \frac{1}{2 m-2 k+1} \partial_{i_{k+1} \ldots i_{m+1} j_{1} \ldots j_{m+1}}|y|^{2 m-2 k+1}=y_{i_{m+1}} A_{i_{k+1} \ldots i_{m} j_{1} \ldots j_{m+1}}^{(m+1, k+1)} \\
& +\delta_{i_{m+1} j_{m+1}} A_{i_{k+1} \ldots i_{m} j_{1} \ldots j_{m}}^{(m, k} \\
& +(m-k) \sigma\left(i_{k+1} \ldots i_{m}\right) \sigma\left(j_{1} \ldots j_{m}\right)\left(\delta_{i_{m+1} i_{m}} A_{i_{k+1} \ldots i_{m-1} j_{1} \ldots j_{m+1}}^{(m, k}\right)  \tag{6.6}\\
& +m \sigma\left(j_{1} \ldots j_{m}\right)\left(\delta_{i_{m+1} j_{1}} A_{i_{k+1} \ldots i_{m} j_{2} \ldots j_{m+1}}^{(m, k)}\right) .
\end{align*}
$$

Formulas (6.3) and (6.6) imply

$$
\begin{aligned}
& \frac{1}{2 m-2 k+1}\left(A^{(m+1, k)} / g\right)_{i_{k+1} \ldots i_{m+1}}=\left[y_{i_{m+1}} A_{i_{k+1} \ldots i_{m} j_{1} \ldots j_{m+1}}^{(m+1, k+1)}\right. \\
& +\delta_{i_{m+1} j_{m+1}} A_{i_{k+1} \ldots i_{m} j_{1} \ldots j_{m}}^{(m, k)} \\
& +(m-k) \sigma\left(i_{k+1} \ldots i_{m}\right) \sigma\left(j_{1} \ldots j_{m}\right)\left(\delta_{i_{m+1} i_{m}} A_{i_{k+1} \ldots i_{m-1} j_{1} \ldots j_{m+1}}^{(m, k)}\right) \\
& \left.+m \sigma\left(j_{1} \ldots j_{m}\right)\left(\delta_{i_{m+1} j_{1}} A_{i_{k+1} \ldots i_{m} j_{2} \ldots j_{m+1}}^{(m, k)}\right)\right] g^{j_{1} \ldots j_{m+1}} .
\end{aligned}
$$

The symmetrization $\sigma\left(j_{1} \ldots j_{m}\right)$ can be deleted after opening brackets since the tensor $g^{j_{1} \ldots j_{m+1}}$ is symmetric in these indices. We thus obtain

$$
\begin{aligned}
\frac{1}{2 m-2 k+1} & \left(A^{(m+1, k)} / g\right)_{i_{k+1} \ldots i_{m+1}}=y_{i_{m+1}} A_{i_{k+1} \ldots i_{m} j_{1} \ldots j_{m+1}}^{(m+1, k+1)} g^{j_{1} \ldots j_{m+1}} \\
& +\delta_{i_{m+1} j_{m+1}} A_{i_{k+1} \ldots i_{m} j_{1} \ldots j_{m}}^{(m, k)} g^{j_{1} \ldots j_{m+1}} \\
& +(m-k) \sigma\left(i_{k+1} \ldots i_{m}\right)\left(\delta_{i_{m+1} i_{m}} A_{i_{k+1} \ldots i_{m-1} j_{1} \ldots j_{m+1}}^{(m, k)} g^{j_{1} \ldots j_{m+1}}\right) \\
& +m \delta_{i_{m+1} j_{1}} A_{i_{k+1} \ldots i_{m} j_{2} \ldots j_{m+1}}^{(m, k)} g^{j_{1} \ldots j_{m+1}} .
\end{aligned}
$$

Implementing the contraction with the Kronecker tensor in second and last lines, we obtain

$$
\begin{aligned}
\frac{1}{2 m-2 k+1} & \left(A^{(m+1, k)} / g\right)_{i_{k+1} \ldots i_{m+1}}=y_{i_{m+1}} A_{i_{k+1} \ldots i_{m} j_{1} \ldots j_{m+1}}^{(m+1,1)} g^{j_{1} \ldots j_{m+1}} \\
& +A_{i_{k+1} \ldots i_{m} j_{1} \ldots j_{m}}^{(m, k} g_{i_{m+1}}^{j_{1} \ldots j_{m}} \\
& +(m-k) \sigma\left(i_{k+1} \ldots i_{m}\right)\left(\delta_{i_{m+1} i_{m}} A_{i_{k+1} \ldots i_{m-1} j_{1} \ldots j_{m+1}}^{(m, k)} g^{j_{1} \ldots j_{m+1}}\right) \\
& +m A_{i_{k+1} \ldots i_{m} j_{1} \ldots j_{m}}^{(m, k)} g_{i_{m+1}}^{j_{1} \ldots j_{m}} .
\end{aligned}
$$

In the last line, we have replaced the summation indices $j_{2}, \ldots, j_{m+1}$ with $j_{1}, \ldots, j_{m}$. We see now that second and last lines contain similar terms. Grouping this terms, we write the formula as follows:

$$
\begin{align*}
\frac{1}{2 m-2 k+1} & \left(A^{(m+1, k)} / g\right)_{i_{k+1} \ldots i_{m+1}}=y_{i_{m+1}} A_{i_{k+1} \ldots i_{m} j_{1} \ldots j_{m+1}}^{(m+1, k+1)} g^{j_{1} \ldots j_{m+1}} \\
& +(m-k) \sigma\left(i_{k+1} \ldots i_{m}\right)\left(\delta_{i_{m+1} i_{m}} A_{i_{k+1} \ldots i_{m-1} j_{1} \ldots j_{m+1}}^{(m, k)} g^{j_{1} \ldots j_{m+1}}\right)  \tag{6.7}\\
& +(m+1) A_{i_{k+1} \ldots i_{m} j_{1} \ldots j_{m}}^{(m, k)} g_{i_{m+1}}^{j_{1} \ldots j_{m}} .
\end{align*}
$$

Recall that the value of the index $i_{m+1}$ is fixed and $\tilde{g}^{j_{1} \ldots j_{m}}=g_{i_{m+1}}^{j_{1} \ldots j_{m}}$. The formula (6.7) can be written as

$$
\begin{aligned}
\frac{1}{2 m-2 k+1} & \left(A^{(m+1, k)} / g\right)_{i_{k+1} \ldots i_{m+1}}=y_{i_{m+1}}\left(A^{(m+1, k+1)} / g\right)_{i_{k+1} \ldots i_{m}} \\
& +(m-k)\left(\tilde{\delta}\left(A^{(m, k)} / g\right)\right)_{i_{k+1} \ldots i_{m}}+(m+1)\left(A^{(m, k)} / \tilde{g}\right)_{i_{k+1} \ldots i_{m}}
\end{aligned}
$$

This is equivalent to (6.2).
Lemma 6.3. For a tensor field $g \in C^{\infty}\left(\mathbb{R}^{n} \backslash\{0\} ; S^{m}\right)$, the following identity holds:

$$
\begin{equation*}
A^{(m, 0)} / g=m!(2 m-1)!!|y|^{-1} g+\sum_{k=1}^{m} \sum_{p=0}^{\min (k, m-k)} \beta(m, k, p) i_{y}^{k-p} i^{p} j_{y}^{p}\left(A^{(m, k)} / g\right) \tag{6.8}
\end{equation*}
$$

where the coefficients $\beta(m, k, p)$ are uniquely determined by the recurrent formulas

$$
\begin{align*}
\tilde{\beta}(m+1, k, p) & =\frac{1}{2 m-2 k+1} \beta(m, k, p)-\frac{k-p}{k} \beta(m, k-1, p)  \tag{6.9}\\
& +\frac{m-k-p+2}{k} \beta(m, k-1, p-1)
\end{align*}
$$

and

$$
\beta(m+1, k, p)= \begin{cases}(2 m+1)(\tilde{\beta}(m+1, k, p)+1) & \text { if }(k, p)=(1,0)  \tag{6.10}\\ (2 m+1)(\tilde{\beta}(m+1, k, p)-m) & \text { if }(k, p)=(1,1) \\ (2 m+1) \tilde{\beta}(m+1, k, p) & \text { otherwise }\end{cases}
$$

under the agreement
(6.11) $\beta(m, k, p)=0$ if either $k=0$ or $k>m$ or $p<0$ or $p>\min (k, m-k)$.

Proof. The proof is going by induction on $m$. For $m=0$, the sum on the right-hand side of (6.8) is absent and the formula holds since $A^{(m, 0)}=|y|^{-1}$. Assume (6.8) to be valid for some $m \geq 0$ and let $g \in C^{\infty}\left(\mathbb{R}^{n} \backslash\{0\} ; S^{m+1}\right)$. We fix a value of the index $i_{m+1}$ and introduce the tensor field $\tilde{g} \in C^{\infty}\left(\mathbb{R}^{n} \backslash\{0\} ; S^{m}\right)$ by (6.1). By the induction hypothesis, the formula (6.8) holds for $\tilde{g}$. Let us write the formula in coordinates

$$
\begin{align*}
& A_{i_{1} \ldots i_{m} j_{1} \ldots j_{m}}^{(m, 0)} g_{i_{m+1}}^{j_{1} \ldots j_{m}}=m!(2 m-1)!!|y|^{-1} g_{i_{1} \ldots i_{m+1}} \\
& +\sigma\left(i_{1} \ldots i_{m}\right) \sum_{k=1}^{m} \sum_{p=0}^{m i n} \beta(m, k, p) y^{l_{1}} \ldots y^{l_{p}} \times  \tag{6.12}\\
& \quad \times \delta_{i_{1} i_{2}} \ldots \delta_{i_{2 p-1} i_{2 p}} y_{i_{i_{p+1}} \ldots y_{i_{k+p}} A_{i_{k+p+1} \ldots i_{m} l_{1} \ldots l_{p} j_{1} \ldots j_{m}}^{(m, k)} g_{i_{m+1}}^{j_{1} \ldots j_{m}} .} .
\end{align*}
$$

By Lemma 6.2,

$$
\begin{align*}
& A_{i_{k+p+1} \ldots i_{m} l_{1} \ldots l_{p} j_{1} \ldots j_{m}}^{(m, k)} g_{i_{m+1}}^{j_{1} \ldots j_{m}}=\left(A^{(m, k)} / \tilde{g}\right)_{i_{k+p+1} \ldots i_{m} l_{1} \ldots l_{p}}  \tag{6.13}\\
& =\frac{1}{m+1}\left[\frac{1}{2 m-2 k+1}\left(A^{(m+1, k)} / g\right)_{i_{k+p+1} \ldots i_{m+1} l_{1} \ldots l_{p}}-y_{i_{m+1}}\left(A^{(m+1, k+1)} / g\right)_{i_{k+p+1} \ldots i_{m} l_{1} \ldots l_{p}}\right. \\
& \left.-(m-k)\left(\tilde{\delta}\left(A^{(m, k)} / g\right)\right)_{i_{k+p+1} \ldots i_{m} l_{1} \ldots l_{p}}\right] .
\end{align*}
$$

In the case of $k=m$, the last term on the right-hand side of (6.13) is equal to zero. In the case of $k<m$, we transform the last term on the right-hand side of (6.13) with
the help of (5.1) as follows:

$$
\begin{align*}
& \left(\tilde{\delta}\left(A^{(m, k)} / g\right)\right)_{i_{k+p+1} \ldots i_{m} l_{1} \ldots l_{p}}=-\frac{1}{k+1}\left(\tilde{\delta}\left(j_{y} A^{(m+1, k+1)} / g\right)\right)_{i_{k+p+1} \ldots i_{m} l_{1} \ldots l_{p}}  \tag{6.14}\\
& =-\frac{1}{k+1} \sigma\left(i_{k+p+1} \ldots i_{m} l_{1} \ldots l_{p}\right)\left(\delta_{i_{m+1} i_{k+p+1}}\left(j_{y} A^{(m+1, k+1)} / g\right)_{i_{k+p+2} \ldots i_{m} l_{1} \ldots l_{p}}\right) .
\end{align*}
$$

The equality

$$
\begin{aligned}
& \sigma\left(i_{k+p+1} \ldots i_{m} l_{1} \ldots l_{p}\right)\left(\delta_{i_{m+1} i_{k+p+1}}\left(j_{y} A^{(m+1, k+1)} / g\right)_{i_{k+p+2} \ldots i_{m} l_{1} \ldots l_{p}}\right) \\
&=\frac{m-k-p}{m-k} \sigma\left(i_{k+p+1} \ldots i_{m}\right)\left(\delta_{i_{m+1} i_{k+p+1}}\left(j_{y} A^{(m+1, k+1)} / g\right)_{i_{k+p+2} \ldots i_{m} l_{1} \ldots l_{p}}\right) \\
&+\frac{p}{m-k} \sigma\left(l_{1} \ldots l_{p}\right)\left(\delta_{i_{m+1} l_{1}}\left(j_{y} A^{(m+1, k+1)} / g\right)_{i_{k+p+1} \ldots i_{m} l_{2} \ldots l_{p}}\right)
\end{aligned}
$$

holds since $j_{y} A^{(m+1, k+1)} / g$ is a symmetric tensor. With the help of this, the formula (6.14) takes the form

$$
\begin{align*}
& \left(\tilde{\delta}\left(A^{(m, k)} / g\right)\right)_{i_{k+p+1} \ldots i_{m} l_{1} \ldots l_{p}} \\
& =-\frac{m-k-p}{(m-k)(k+1)} \sigma\left(i_{k+p+1} \ldots i_{m}\right)\left(\delta_{i_{m+1} i_{k+p+1}}\left(j_{y} A^{(m+1, k+1)} / g\right)_{i_{k+p+2} \ldots i_{m} l_{1} \ldots l_{p}}\right)  \tag{6.15}\\
& -\frac{p}{(m-k)(k+1)} \sigma\left(l_{1} \ldots l_{p}\right)\left(\delta_{i_{m+1} l_{1}}\left(j_{y} A^{(m+1, k+1)} / g\right)_{i_{k+p+1} \ldots i_{m} l_{2} \ldots l_{p}}\right) .
\end{align*}
$$

Replacing the last term on the right-hand side of (6.13) with its value (6.15), we obtain (6.16)

$$
\begin{aligned}
& A_{i_{k+p+1} \ldots i_{m} l_{1} \ldots l_{p} j_{1} \ldots j_{m}}^{(m, k)} g_{i_{m+1}}^{j_{1} \ldots j_{m}}=\left(A^{(m, k)} / \tilde{g}\right)_{i_{k+p+1} \ldots i_{m} l_{1} \ldots l_{p}} \\
&=\frac{1}{m+1} {\left[\frac{1}{2 m-2 k+1}\left(A^{(m+1, k)} / g\right)_{i_{k+p+1} \ldots i_{m+1} l_{1} \ldots l_{p}}-y_{i_{m+1}}\left(A^{(m+1, k+1)} / g\right)_{i_{k+p+1} \ldots i_{m} l_{1} \ldots l_{p}}\right.} \\
& \quad+\frac{m-k-p}{k+1} \sigma\left(i_{k+p+1} \ldots i_{m}\right)\left(\delta_{i_{m+1} i_{k+p+1}}\left(j_{y} A^{(m+1, k+1)} / g\right)_{i_{k+p+2} \ldots i_{m} l_{1} \ldots l_{p}}\right) \\
&\left.\quad+\frac{p}{k+1} \sigma\left(l_{1} \ldots l_{p}\right)\left(\delta_{i_{m+1} l_{1}}\left(j_{y} A^{(m+1, k+1)} / g\right)_{i_{k+p+1} \ldots i_{m} l_{2} \ldots l_{p}}\right)\right] .
\end{aligned}
$$

It is not quite obvious now that two last lines on the right-hand side of (6.16) are equal to zero in the case of $k=m$. Nevertheless, in the case of $k=m$ we are interested in (6.16) for $p=0$ only, as is seen from (6.12). For $k=m$ and $p=0$, the last two lines on the right-hand side of (6.16) are equal to zero.

We substitute the expression (6.16) into (6.12). After the substitution, the symmetrization $\sigma\left(i_{k+p+1} \ldots i_{m}\right)$ can be omitted because of the presence of the "larger" symmetrization $\sigma\left(i_{1} \ldots i_{m}\right)$. The symmetrization $\sigma\left(l_{1} \ldots l_{p}\right)$ can be also omitted because of the presence
of the factor $y^{l_{1}} \ldots y^{l_{p}}$. We thus obtain

$$
\begin{aligned}
& A_{i_{1} \ldots i_{m} j_{1} \ldots j_{m}}^{(m, 0)} g_{i_{m+1}}^{j_{1} \ldots j_{m}}=m!(2 m-1)!!|y|^{-1} g_{i_{1} \ldots i_{m+1}} \\
& +\frac{1}{m+1} \sigma\left(i_{1} \ldots i_{m}\right) \sum_{k=1}^{m} \sum_{p=0}^{\min (k, m-k)} \beta(m, k, p) \delta_{i_{1} i_{2}} \ldots \delta_{i_{2 p-1} i_{2 p}} y_{i_{2 p+1}} \ldots y_{i_{k+p}} y^{l_{1}} \ldots y^{l_{p}} \times \\
& \times\left[\frac{1}{2 m-2 k+1}\left(A^{(m+1, k)} / g\right)_{i_{k+p+1} \ldots i_{m+1} l_{1} \ldots l_{p}}-y_{i_{m+1}}\left(A^{(m+1, k+1)} / g\right)_{i_{k+p+1} \ldots i_{m} l_{1} \ldots l_{p}}\right. \\
& \quad+\frac{m-k-p}{k+1} \delta_{i_{m+1} i_{k+p+1}}\left(j_{y} A^{(m+1, k+1)} / g\right)_{i_{k+p+2} \ldots i_{m} l_{1} \ldots l_{p}} \\
& \left.\quad+\frac{p}{k+1} \delta_{i_{m+1} l_{1}}\left(j_{y} A^{(m+1, k+1)} / g\right)_{i_{k+p+1} \ldots i_{m} l_{2} \ldots l_{p}}\right] .
\end{aligned}
$$

After pulling the factor $y^{l_{1}} \ldots y^{l_{p}}$ inside brackets, this becomes

$$
\begin{aligned}
& A_{i_{1} \ldots i_{m} j_{1} \ldots j_{m}}^{(m, 0)} g_{i_{m+1}}^{j_{1} \ldots j_{m}}=m!(2 m-1)!!|y|^{-1} g_{i_{1} \ldots i_{m+1}} \\
& +\frac{1}{m+1} \sigma\left(i_{1} \ldots i_{m}\right) \sum_{k=1}^{m} \sum_{p=0}^{\min (k, m-k)} \beta(m, k, p) \delta_{i_{1} i_{2}} \ldots \delta_{i_{2 p-1} i_{2 p}} y_{i_{2 p+1}} \ldots y_{i_{k+p}} \times \\
& \times\left[\frac{1}{2 m-2 k+1}\left(j_{y}^{p} A^{(m+1, k)} / g\right)_{i_{k+p+1} \ldots i_{m+1}}-y_{i_{m+1}}\left(j_{y}^{p} A^{(m+1, k+1)} / g\right)_{i_{k+p+1} \ldots i_{m}}\right. \\
& \quad+\frac{m-k-p}{k+1} \delta_{i_{m+1} i_{k+p+1}}\left(j_{y}^{p+1} A^{(m+1, k+1)} / g\right)_{i_{k+p+2} \ldots i_{m}} \\
& \left.\quad+\frac{p}{k+1} y_{i_{m+1}}\left(j_{y}^{p} A^{(m+1, k+1)} / g\right)_{i_{k+p+1} \ldots i_{m}}\right] .
\end{aligned}
$$

Observe that second and last terms in brackets differ by coefficients only. After grouping these terms, the formula becomes

$$
\begin{aligned}
& A_{i_{1} \ldots i_{m} j_{1} \ldots j_{m}}^{(m, 0)} g_{i_{m+1}}^{j_{1} \ldots j_{m}}=m!(2 m-1)!!|y|^{-1} g_{i_{1} \ldots i_{m+1}} \\
& +\frac{1}{m+1} \sigma\left(i_{1} \ldots i_{m}\right) \sum_{k=1}^{m} \sum_{p=0}^{\min (k, m-k)} \beta(m, k, p) \delta_{i_{1} i_{2}} \ldots \delta_{i_{2 p-1} i_{2 p}} y_{i_{2 p+1}} \ldots y_{i_{k+p}} \times \\
& \times\left[\frac{1}{2 m-2 k+1}\left(j_{y}^{p} A^{(m+1, k)} / g\right)_{i_{k+p+1} \ldots i_{m+1}}-\frac{k-p+1}{k+1} y_{i_{m+1}}\left(j_{y}^{p} A^{(m+1, k+1)} / g\right)_{i_{k+p+1} \ldots i_{m}}\right. \\
& \left.\quad+\frac{m-k-p}{k+1} \delta_{i_{m+1} i_{k+p+1}}\left(j_{y}^{p+1} A^{(m+1, k+1)} / g\right)_{i_{k+p+2} \ldots i_{m}}\right] .
\end{aligned}
$$

Next, we pull the factor $\delta_{i_{2 p-1} i_{2 p}} y_{i_{2 p+1}} \ldots y_{i_{k+p}}$ inside brackets

$$
\begin{align*}
& A_{i_{1} \ldots i_{m} j_{1} \ldots j_{m}}^{(m, 0)} g_{i_{m+1}}^{j_{1} \ldots j_{m}}=m!(2 m-1)!!|y|^{-1} g_{i_{1} \ldots i_{m+1}} \\
& +\frac{1}{m+1} \sum_{k=1}^{m} \sum_{p=0}^{\min (k, m-k)} \beta(m, k, p) \tag{6.17}
\end{align*} \quad\left[\frac{1}{2 m-2 k+1}\left(i_{y}^{k-p} i^{p} j_{y}^{p}\left(A^{(m+1, k)} / g\right)\right)_{i_{1} \ldots i_{m+1}} .\right.
$$

Next, we apply Lemma 6.2 with $k=0$. More precisely, we reproduce the formula (6.7) from the proof of the lemma for $k=0$

$$
\begin{aligned}
& \left(A^{(m+1,0)} / g\right)_{i_{1} \ldots i_{m+1}}=(m+1)(2 m+1) A_{i_{1} \ldots i_{m} j_{1} \ldots j_{m}}^{(m, 0)} g_{i_{m+1}}^{j_{1} \ldots j_{m}} \\
& +(2 m+1) y_{i_{m+1}} A_{i_{1} \ldots i_{m} j_{1} \ldots j_{m+1}}^{(m+1,1} g^{j_{1} \ldots j_{m+1}} \\
& +m(2 m+1) \sigma\left(i_{1} \ldots i_{m}\right)\left(\delta_{i_{m+1} i_{m}} A_{i_{1} \ldots i_{m-1} j_{1} \ldots j_{m+1}}^{(m, 0)} g^{j_{1} \ldots j_{m+1}}\right)
\end{aligned}
$$

This can be written in the form

$$
\begin{aligned}
& \left(A^{(m+1,0)} / g\right)_{i_{1} \ldots i_{m+1}}=(m+1)(2 m+1) A_{i_{1} \ldots i_{m} j_{1} \ldots j_{m}}^{(m, 0)} g_{i_{m+1}}^{j_{1} \ldots j_{m}} \\
& \quad \quad+(2 m+1) y_{i_{m+1}}\left(A^{(m+1,1)} / g\right)_{i_{1} \ldots i_{m}}+m(2 m+1)\left(i_{\tilde{\delta}}\left(A^{(m, 0)} / g\right)\right)_{i_{1} \ldots i_{m}}
\end{aligned}
$$

By (5.1), $A^{(m, 0)}=-j_{y} A^{(m+1,1)}$. Substituting this expression into the last line of the previous formula, we obtain

$$
\begin{align*}
& \left(A^{(m+1,0)} / g\right)_{i_{1} \ldots i_{m+1}}=(m+1)(2 m+1) A_{i_{1} \ldots i_{m} j_{1} \ldots j_{m}}^{(m, 0)} g_{i_{m+1}}^{j_{1} \ldots j_{m}} \\
& +(2 m+1) y_{i_{m+1}}\left(A^{(m+1,1)} / g\right)_{i_{1} \ldots i_{m}}-m(2 m+1)\left(i_{\tilde{\delta}} j_{y}\left(A^{(m+1,1)} / g\right)\right)_{i_{1} \ldots i_{m}} . \tag{6.18}
\end{align*}
$$

Now, we replace the first term $A_{i_{1} \ldots i_{m} j_{1} \ldots j_{m}}^{(m, 0)} g_{i_{m+1}}^{j_{1} \ldots j_{m}}$ on the right-hand side of (6.18) with its expression (6.17)

$$
\left.\begin{array}{l}
\frac{1}{2 m+1}\left(A^{(m+1,0)} / g\right)_{i_{1} \ldots i_{m+1}}=(m+1)!(2 m-1)!!|y|^{-1} g_{i_{1} \ldots i_{m+1}} \\
+\sum_{k=1}^{m} \sum_{p=0}^{\min (k, m-k)} \beta(m, k, p)\left[\frac{1}{2 m-2 k+1}\left(i_{y}^{k-p} i^{p} j_{y}^{p}\left(A^{(m+1, k)} / g\right)\right)_{i_{1} \ldots i_{m+1}}\right. \\
\quad-\frac{k-p+1}{k+1} y_{i_{m+1}}\left(i_{y}^{k-p} i^{p} j_{y}^{p}\left(A^{(m+1, k+1)} / g\right)\right)_{i_{1} \ldots i_{m}}  \tag{6.19}\\
\left.\quad+\frac{m-k-p}{k+1}\left(i_{\tilde{\delta}} i_{y}^{k-p} i^{p} j_{y}^{p+1}\left(A^{(m+1, k+1)} / g\right)\right)_{i_{1} \ldots i_{m}}\right]
\end{array}\right] \begin{aligned}
& +y_{i_{m+1}}\left(A^{(m+1,1)} / g\right)_{i_{1} \ldots i_{m}}-m\left(i_{\tilde{\delta}} j_{y}\left(A^{(m+1,1)} / g\right)\right)_{i_{1} \ldots i_{m}} .
\end{aligned}
$$

From now on, we again let $i_{m+1}$ be an arbitrary index. We apply the symmetrization $\sigma\left(i_{1} \ldots i_{m+1}\right)$ to the equation (6.19). The operator $i_{\tilde{\delta}}$ becomes $i$ after the symmetrization and the result can be written in the coordinate-free form (recall that operators $i_{y}$ and $i$ commute)
(6.20)

$$
\begin{aligned}
& \frac{1}{2 m+1} A^{(m+1,0)} / g=(m+1)!(2 m-1)!!|y|^{-1} g \\
& +\sum_{k=1}^{m} \sum_{p=0}^{\min (k, m-k)} \beta(m, k, p)\left[\frac{1}{2 m-2 k+1} i_{y}^{k-p} i^{p} j_{y}^{p}\left(A^{(m+1, k)} / g\right)\right. \\
& \left.\quad \quad-\frac{k-p+1}{k+1} i_{y}^{k-p+1} i^{p} j_{y}^{p}\left(A^{(m+1, k+1)} / g\right)+\frac{m-k-p}{k+1} i_{y}^{k-p} i^{p+1} j_{y}^{p+1}\left(A^{(m+1, k+1)} / g\right)\right] \\
& +i_{y}\left(A^{(m+1,1)} / g\right)-m i j_{y}\left(A^{(m+1,1)} / g\right) .
\end{aligned}
$$

Let us write (6.20) in the form

$$
\begin{aligned}
& \frac{1}{2 m+1} A^{(m+1,0)} / g=(m+1)!(2 m-1)!!|y|^{-1} g \\
& +\sum_{k=1}^{m} \sum_{p=0}^{\min (k, m-k)} \frac{1}{2 m-2 k+1} \beta(m, k, p) i_{y}^{k-p} i^{p} j_{y}^{p}\left(A^{(m+1, k)} / g\right) \\
& -\sum_{k^{\prime}=1}^{m} \sum_{p=0}^{\min \left(k^{\prime}, m-k^{\prime}\right)} \frac{k^{\prime}-p+1}{k^{\prime}+1} \beta\left(m, k^{\prime}, p\right) i_{y}^{k^{\prime}-p+1} i^{p} j_{y}^{p}\left(A^{\left(m+1, k^{\prime}+1\right)} / g\right) \\
& +\sum_{k^{\prime}=1}^{m} \sum_{p^{\prime}=0}^{\min \left(k^{\prime}, m-k^{\prime}\right)} \frac{m-k^{\prime}-p^{\prime}}{k^{\prime}+1} \beta\left(m, k^{\prime}, p^{\prime}\right) i_{y}^{k^{\prime}-p^{\prime}} i^{p^{\prime}+1} j_{y}^{p^{\prime}+1}\left(A^{\left(m+1, k^{\prime}+1\right)} / g\right) \\
& +i_{y}\left(A^{(m+1,1)} / g\right)-m i j_{y}\left(A^{(m+1,1)} / g\right) .
\end{aligned}
$$

We change summation variables by $k^{\prime}=k-1$ in the second sum and by $k^{\prime}=k-1, p^{\prime}=$ $p-1$ in the third sum. The formula becomes

$$
\begin{align*}
& \frac{1}{2 m+1} A^{(m+1,0)} / g=(m+1)!(2 m-1)!!|y|^{-1} g \\
& +\sum_{k=1}^{m} \sum_{p=0}^{\min (k, m-k)} \frac{1}{2 m-2 k+1} \beta(m, k, p) i_{y}^{k-p} i^{p} j_{y}^{p}\left(A^{(m+1, k)} / g\right) \\
& -\sum_{k=2}^{m+1} \sum_{p=0}^{\min (k-1, m-k+1)} \frac{k-p}{k} \beta(m, k-1, p) i_{y}^{k-p} i^{p} j_{y}^{p}\left(A^{(m+1, k)} / g\right)  \tag{6.21}\\
& +\sum_{k=2}^{m+1} \sum_{p=1}^{\min (k-1, m-k+1)+1} \frac{m-k-p+2}{k} \beta(m, k-1, p-1) i_{y}^{k-p} i^{p} j_{y}^{p}\left(A^{(m+1, k)} / g\right) \\
& +i_{y}\left(A^{(m+1,1)} / g\right)-m i j_{y}\left(A^{(m+1,1)} / g\right) .
\end{align*}
$$

We are going to equate summation limits in three sums on the right-hand side of (6.21) in order to unite the sums. Then we are going to involve two terms on the last line of (6.21) into the same sum. This needs some logical and arithmetic analysis.

In the first sum on the right-hand side of (6.21), the summation over $k$ can be extended to $1 \leq k \leq m+1$ since $\beta(m, m+1, p)=0$ by the agreement (6.11). Let us demonstrate that the summation over $p$ can be extended to $0 \leq p \leq \min (k, m-k+1)$. Indeed, $\min (k, m-k)=\min (k, m-k+1)$ if $k \leq m-k$. If $k>m-k$, then there appears one extra term corresponding to $p=m-k+1$ in the first sum. But $\beta(m, k, m-k+1)=0$ by the agreement (6.11). Thus, summation limits of the first sum can be replaced with

$$
\begin{equation*}
1 \leq k \leq m+1, \quad 0 \leq p \leq \min (k, m-k+1) . \tag{6.22}
\end{equation*}
$$

In the second sum on the right-hand side of (6.21), the summation over $k$ can be extended to $1 \leq k \leq m+1$ since $\beta(m, 0, p)=0$ by the agreement (6.11). Let us demonstrate that the summation over $p$ can be extended to $0 \leq p \leq \min (k, m-k+1)$. Indeed, $\min (k-1, m-k)=\min (k, m-k+1)$ if $k>m-k+1$. If $k \leq m-k+1$, then there appears one extra term corresponding to $p=k$ in the second sum. But $\beta(m, k-1, k)=0$ by the agreement (6.11). Thus, summation limits of the second sum can be replaced with (6.22).

In the third sum on the right-hand side of (6.21), the summation over $k$ can be extended to $1 \leq k \leq m+1$ since $\beta(m, 0, p-1)=0$ by the agreement (6.11). The lower summation limit over $p$ can be replaced with zero since $\beta(m, k-1,-1)=0$ by the agreement (6.11). Let us demonstrate that the upper summation limit over $p$ can be replaced with $\min (k, m-k+1)$. Indeed, $\min (k-1, m-k+1)+1=\min (k, m-k+1)$ if either $2 k<m+2$ or $2 k>m+2$. The only critical case is $2 k=m+2$ when $\min (k-1, m-k+1)+1=m-k+2$ and $\min (k, m-k+1)=m-k+1$. We are going to loose the term corresponding to $p=m-k+2$ after the replacement. But this term is equal to zero due to the presence of the factor $\frac{m-k-p+2}{k}$.

Thus, summation limits can be replaced with (6.22) in all sums on the right-hand side of (6.21). After the replacement, we unite three sums and write (6.21) in the form

$$
\begin{align*}
& A^{(m+1,0)} / g=(m+1)!(2 m+1)!!|y|^{-1} g \\
& +(2 m+1) \sum_{k=1}^{m+1} \sum_{p=0}^{\min (k, m-k+1)} \tilde{\beta}(m+1, k, p) i_{y}^{k-p} i^{p} j_{y}^{p}\left(A^{(m+1, k)} / g\right)  \tag{6.23}\\
& +(2 m+1) i_{y}\left(A^{(m+1,1)} / g\right)-m(2 m+1) i j_{y}\left(A^{(m+1,1)} / g\right),
\end{align*}
$$

where $\tilde{\beta}(m+1, k, p)$ is defined by (6.9).
Finally, we have to include two terms on the last line of (6.23) into the sum. The term $i_{y}\left(A^{(m+1,1)} / g\right)$ corresponds to $(k, p)=(1,0)$ and the term $i j_{y}\left(A^{(m+1,1)} / g\right)$ corresponds to $(k, p)=(1,1)$. Therefore we define $\beta(m+1, k, p)$ by (6.10). The formula (6.23) becomes now

$$
\begin{aligned}
A^{(m+1,0)} / g & =(m+1)!(2 m+1)!!|y|^{-1} g \\
& +\sum_{k=1}^{m+1} \sum_{p=0}^{\min (k, m-k+1)} \beta(m+1, k, p) i_{y}^{k-p} i^{p} j_{y}^{p}\left(A^{(m+1, k)} / g\right) .
\end{aligned}
$$

This coincides with (6.8) for $m:=m+1$.
Proof of Proposition 6.1. Coefficients $\beta(m, k, p)$ are determined by pretty complicated recurrent formulas (6.9)-(6.11). Nevertheless, the coefficients can be expressed by the explicit formula

$$
\beta(m, k, p)=\left\{\begin{array}{l}
(-1)^{k+p+1} \frac{(2 m-1)!!}{(2 m-2 k-1)!!} 2^{-p}\binom{m}{k}\binom{m-k}{p} \quad \text { for } k>0  \tag{6.24}\\
0 \text { for } k \leq 0
\end{array}\right.
$$

Indeed, being defined by (6.9), $\beta(m, k, p)$ satisfy (6.11) under the agreement (5.9). Formulas (6.9)-(6.10) can be equivalently written in the form

$$
\begin{gather*}
\beta(m+1,1,0)=(2 m+1)\left(\frac{1}{2 m-1} \beta(m, 1,0)+1\right),  \tag{6.25}\\
\beta(m+1,1,1)=(2 m+1)\left(\frac{1}{2 m-1} \beta(m, 1,1)-m\right),  \tag{6.26}\\
\beta(m+1, k, p)=(2 m+1)\left[\frac{1}{2 m-2 k+1} \beta(m, k, p)-\frac{k-p}{k} \beta(m, k-1, p)\right.  \tag{6.27}\\
\left.+\frac{m-k-p+2}{k} \beta(m, k-1, p-1)\right] \quad((k, p) \neq(1,0),(k, p) \neq(1,1)) .
\end{gather*}
$$

Unlike (6.9)-(6.10), formulas (6.25)-(6.27) do not involve $\tilde{\beta}(m+1, k, p)$. One easily proves that equations (6.25)-(6.27) are satisfied by values (6.24). We express $g$ from (6.8).

Substituting the value (6.24) of $\beta(m, k, p)$ into the expression, we arrive at the formula (3.5) with $\hat{f}=g$. Substituting the value (6.24) into (6.8) we arrive at the formula (3.5) with $\widehat{f}=g$. This completes the proof of Proposition 6.1 as well as of Theorem 3.3.

## 7. Proof of Theorems 3.1 and 3.2

7.1. Vector fields. In the case of $m=1$, the formula (3.5) looks as follows:

$$
\begin{equation*}
\widehat{f}=|y|\left(H^{(1,0)}-i_{y} H^{(1,1)}\right) . \tag{7.1}
\end{equation*}
$$

By (3.4),

$$
H^{(1,0)}=F^{(1,0)}, \quad H^{(1,1)}=\frac{1}{n-1}\left(\operatorname{div} F^{(1,0)}-F^{(1,1)}\right)
$$

and by (3.3),

$$
F^{(1,0)}=c_{1, n} \widehat{N_{1}^{0} f}, \quad F^{(1,1)}=c_{1, n} j_{y} \widehat{N_{1}^{1} f}
$$

where

$$
c_{1, n}=-\frac{2^{n / 2} \Gamma\left(\frac{n+1}{2}\right)}{\Gamma\left(-\frac{1}{2}\right)}=\frac{2^{n / 2-1} \Gamma\left(\frac{n+1}{2}\right)}{\sqrt{\pi}}
$$

From this

$$
H^{(1,0)}=c_{1, n} \widehat{N_{1}^{0} f}, \quad H^{(1,1)}=\frac{c_{1, n}}{n-1}\left(\operatorname{div} \widehat{N_{1}^{0} f}-j_{y} \widehat{N_{1}^{1} f}\right) .
$$

Substitute these expressions into (7.1)

$$
\begin{equation*}
\widehat{f}=c_{1, n}|y|\left(\widehat{N_{1}^{0} f}-\frac{1}{n-1} i_{y} \operatorname{div} \widehat{N_{1}^{0} f}+\frac{1}{n-1} i_{y} j_{y} \widehat{N_{1}^{1} f}\right) . \tag{7.2}
\end{equation*}
$$

We apply the inverse Fourier transform to the formula (7.2) and use the commutator formulas

$$
\begin{equation*}
\mathcal{F}^{-1}|y|=(-\Delta)^{1 / 2} \mathcal{F}^{-1}, \quad \mathcal{F}^{-1} i_{y} j_{y}=-d \operatorname{div} \mathcal{F}^{-1}, \quad \mathcal{F}^{-1} i_{y} \operatorname{div}=d j_{x} \mathcal{F}^{-1} \tag{7.3}
\end{equation*}
$$

In this way we obtain

$$
f=c_{1, n}(-\Delta)^{1 / 2}\left(N_{1}^{0} f-\frac{1}{n-1} d j_{x} N_{1}^{0} f-\frac{1}{n-1} d \operatorname{div} N_{1}^{1} f\right)
$$

This completes the proof of Theorem 3.1.
7.2. Second rank tensor fields. In the case of $m=2$, the formula (3.5) looks as follows:

$$
\begin{equation*}
\widehat{f}=\frac{1}{6}|y|\left(H^{(2,0)}-6 i_{y} H^{(2,1)}+3 i j_{y} H^{(2,1)}+3 i_{y}^{2} H^{(2,2)}\right) \tag{7.4}
\end{equation*}
$$

By (3.4),

$$
\begin{aligned}
& H^{(2,0)}=F^{(2,0)}, \quad H^{(2,1)}=\frac{1}{3(n+1)}\left(\operatorname{div} F^{(2,0)}-F^{(2,1)}\right), \\
& H^{(2,2)}=\frac{1}{3(n-1)(n+1)}\left(\operatorname{div}^{2} F^{(2,0)}-2 \operatorname{div} F^{(2,1)}+F^{(2,2)}\right)
\end{aligned}
$$

and by (3.3),

$$
F^{(2,0)}=c_{2, n} \widehat{N_{2}^{0} f}, \quad F^{(2,1)}=c_{2, n} j_{y} \widehat{N_{2}^{1} f}, \quad F^{(2,2)}=\frac{1}{2} c_{2, n} j_{y}^{2} \widehat{N_{2}^{2} f},
$$

where

$$
\begin{equation*}
c_{2, n}=3 \frac{2^{n / 2} \Gamma\left(\frac{n+3}{2}\right)}{24} \sqrt{\pi} . \tag{7.5}
\end{equation*}
$$

From this

$$
\begin{aligned}
& H^{(2,0)}=c_{2, n} \widehat{N_{2}^{0} f}, \quad H^{(2,1)}=\frac{c_{2, n}}{3(n+1)}\left(\operatorname{div} \widehat{N_{2}^{0} f}-j_{y} \widehat{N_{2}^{1} f}\right), \\
& H^{(2,2)}=\frac{c_{2, n}}{3(n-1)(n+1)}\left(\operatorname{div}^{2} \widehat{N_{2}^{0} f}-2 \operatorname{div} j_{y} \widehat{N_{2}^{1} f}+\frac{1}{2} j_{y}^{2} \widehat{N_{2}^{2} f}\right) .
\end{aligned}
$$

Substitute these expressions into (7.4)

$$
\begin{aligned}
\widehat{f}=\frac{c_{2, n}}{6}|y|[ & \widehat{N_{2}^{0} f}-\frac{2}{n+1} i_{y}\left(\operatorname{div} \widehat{N_{2}^{0} f}-j_{y} \widehat{N_{2}^{1} f}\right) \\
& +\frac{1}{n+1} i\left(j_{y} \operatorname{div} \widehat{N_{2}^{0} f}-j_{y}^{2} \widehat{N_{2}^{1} f}\right) \\
& \left.+\frac{1}{(n-1)(n+1)} i_{y}^{2}\left(\operatorname{div}^{2} \widehat{N_{2}^{0} f}-2 \operatorname{div} j_{y} \widehat{N_{2}^{1} f}+\frac{1}{2} j_{y}^{2} \widehat{N_{2}^{2} f}\right)\right] .
\end{aligned}
$$

By Lemma 4.4, $j_{y}^{2} \widehat{N_{2}^{1} f}=0$, and the latter formula is simplified to the following one:

$$
\begin{align*}
\widehat{f}=\frac{c_{2, n}}{6}|y|[ & \widehat{N_{2}^{0} f}+\frac{1}{n+1} i j_{y} \operatorname{div} \widehat{N_{2}^{0} f} \\
& -\frac{2}{n+1} i_{y}\left(\operatorname{div} \widehat{N_{2}^{0} f}-j_{y} \widehat{N_{2}^{1} f}\right)  \tag{7.6}\\
& \left.+\frac{1}{(n-1)(n+1)} i_{y}^{2}\left(\operatorname{div}^{2} \widehat{N_{2}^{0} f}-2 \operatorname{div} j_{y} \widehat{N_{2}^{1} f}+\frac{1}{2} j_{y}^{2} \widehat{N_{2}^{2} f}\right)\right] .
\end{align*}
$$

The second term on the right-hand side of (7.6) can be simplified. Indeed, the commutator formula

$$
\begin{equation*}
j_{y} \operatorname{div}=\operatorname{div} j_{y}-j \tag{7.7}
\end{equation*}
$$

is proved by an easy calculation in coordinates. By this formula,

$$
j_{y} \operatorname{div} \widehat{N_{2}^{0} f}=\operatorname{div} j_{y} \widehat{N_{2}^{0} f}-j \widehat{N_{2}^{0} f}
$$

By Lemma 4.4, $j_{y} \widehat{N_{2}^{0} f}=0$, and the latter formula gives $j_{y} \operatorname{div} \widehat{N_{2}^{0} f}=-j \widehat{N_{2}^{0} f}$. Substitute this value into (7.6)

$$
\begin{align*}
\widehat{f}=\frac{c_{2, n}}{6}|y|[ & \widehat{N_{2}^{0} f}-\frac{1}{n+1} i j \widehat{N_{2}^{0} f} \\
& -\frac{2}{n+1}\left(i_{y} \operatorname{div} \widehat{N_{2}^{0} f}-i_{y} j_{y} \widehat{N_{2}^{1} f}\right)  \tag{7.8}\\
& \left.+\frac{1}{(n-1)(n+1)}\left(i_{y}^{2} \operatorname{div}^{2} \widehat{N_{2}^{0} f}-2 i_{y}^{2} \operatorname{div} j_{y} \widehat{N_{2}^{1} f}+\frac{1}{2} i_{y}^{2} j_{y}^{2} \widehat{N_{2}^{2} f}\right)\right] .
\end{align*}
$$

We apply the inverse Fourier transform to the formula (7.8) and use the commutator formulas (7.3) as well as
$\mathcal{F}^{-1} i_{y}^{2}=-d^{2} \mathcal{F}^{-1}, \quad \mathcal{F}^{-1} \operatorname{div}^{2}=-j_{x}^{2} \mathcal{F}^{-1}, \quad \underset{25}{\mathcal{F}^{-1} j_{y} d=\operatorname{div} i_{x} \mathcal{F}^{-1}, \quad \mathcal{F}^{-1} \operatorname{div} j_{y}=j_{x} \operatorname{div} \mathcal{F}^{-1} . . . . . . . . . . ~}$

In this way we obtain

$$
\begin{aligned}
f(x)=\frac{c_{2, n}}{6}(-\Delta)^{1 / 2}[ & N_{2}^{0} f-\frac{1}{n+1} i j N_{2}^{0} f \\
& -\frac{2}{n+1} d\left(j_{x} N_{2}^{0} f+\operatorname{div} N_{2}^{1} f\right) \\
& \left.+\frac{1}{(n-1)(n+1)} d^{2}\left(j_{x}^{2} N_{2}^{0} f-2 j_{x} \operatorname{div} N_{2}^{1} f+\frac{1}{2} \operatorname{div}^{2} N_{2}^{2} f\right)\right] .
\end{aligned}
$$

Substituting the value (7.5) of $c_{2, n}$, we arrive at (3.2). This completes the proof of Theorem 3.2.
7.3. Third rank tensor fields. In the case of $m=3$, the formula (3.5) looks as follows:

$$
\begin{equation*}
\widehat{f}=\frac{|y|}{90}\left(H^{(3,0)}-15 i_{y} H^{(3,1)}+15 i j_{y} H^{(3,1)}+45 i_{y}^{2} H^{(3,2)}-\frac{45}{2} i i_{y} j_{y} H^{(3,2)}-15 i_{y}^{3} H^{(3,3)}\right) \tag{7.9}
\end{equation*}
$$

By (3.4),

$$
\begin{aligned}
& H^{(3,0)}=F^{(3,0)}, \quad H^{(3,1)}=\frac{1}{5(n+3)}\left(\operatorname{div} F^{(3,0)}-F^{(3,1)}\right) \\
& H^{(3,2)}=\frac{1}{15(n+1)(n+3)}\left(\operatorname{div}^{2} F^{(3,0)}-2 \operatorname{div} F^{(3,1)}+F^{(3,2)}\right) \\
& H^{(3,3)}=\frac{1}{15(n-1)(n+1)(n+3)}\left(\operatorname{div}^{3} F^{(3,0)}-3 \operatorname{div}^{2} F^{(3,1)}+3 \operatorname{div} F^{(3,2)}-F^{(3,3)}\right)
\end{aligned}
$$

and by (3.3),

$$
F^{(3,0)}=c_{3, n} \widehat{N_{3}^{0} f}, \quad F^{(3,1)}=c_{3, n} j_{y} \widehat{N_{3}^{1} f}, \quad F^{(3,2)}=\frac{1}{2} c_{3, n} j_{y}^{2} \widehat{N_{3}^{2} f}, \quad F^{(3,3)}=\frac{1}{6} c_{3, n} j_{y}^{3} \widehat{N_{3}^{2} f},
$$

where

$$
\begin{equation*}
c_{3, n}=15 \pi^{-1 / 2} 2^{n / 2+1} \Gamma\left(\frac{n+5}{2}\right) . \tag{7.10}
\end{equation*}
$$

From this

$$
\begin{aligned}
& H^{(3,0)}=c_{3, n} \widehat{N_{3}^{0} f}, \quad H^{(3,1)}=\frac{c_{3, n}}{5(n+3)}\left(\operatorname{div} \widehat{N_{3}^{0} f}-j_{y} \widehat{N_{3}^{1} f}\right), \\
& H^{(3,2)}=\frac{c_{3, n}}{15(n+1)(n+3)}\left(\operatorname{div}^{2} \widehat{N_{3}^{0} f}-2 \operatorname{div} j_{y} \widehat{N_{3}^{1} f}+\frac{1}{2} j_{y}^{2} \widehat{N_{3}^{2} f}\right), \\
& H^{(3,3)}=\frac{c_{3, n}}{15(n-1)(n+1)(n+3)}\left(\operatorname{div}^{3} \widehat{N_{3}^{0} f}-3 \operatorname{div}^{2} j_{y} \widehat{N_{3}^{1} f}+\frac{3}{2} \operatorname{div} j_{y}^{2} \widehat{N_{3}^{2} f}-\frac{1}{6} j_{y}^{3} \widehat{N_{3}^{3} f}\right) .
\end{aligned}
$$

Substitute these expressions into (7.9)

$$
\begin{aligned}
\widehat{f}=\frac{c_{3, n}}{90}|y|[ & \widehat{N_{3}^{0} f}-\frac{3}{n+3} i_{y}\left(\operatorname{div} \widehat{N_{3}^{0} f}-j_{y} \widehat{N_{3}^{1}} f\right) \\
& +\frac{3}{n+3} i\left(j_{y} \operatorname{div} \widehat{N_{3}^{0} f}-j_{y}^{2} \widehat{N_{3}^{1} f}\right) \\
& +\frac{3}{(n+1)(n+3)} i_{y}^{2}\left(\operatorname{div}^{2} \widehat{N_{3}^{0} f}-2 \operatorname{div} j_{y} \widehat{N_{3}^{1} f}+\frac{1}{2} j_{y}^{2} \widehat{N_{3}^{2} f}\right) \\
& -\frac{3}{2(n+1)(n+3)} i i_{y}\left(j_{y} \operatorname{div}^{2} \widehat{N_{3}^{0} f}-2 j_{y} \operatorname{div} j_{y} \widehat{N_{3}^{1} f}+\frac{1}{2} j_{y}^{3} \widehat{N_{3}^{2} f}\right) \\
& \left.-\frac{1}{(n-1)(n+1)(n+3)} i_{y}^{3}\left(\operatorname{div}^{3} \widehat{N_{3}^{0} f}-3 \operatorname{div}^{2} j_{y} \widehat{N_{3}^{1} f}+\frac{3}{2} \operatorname{div} j_{y}^{2} \widehat{N_{3}^{2} f}-\frac{1}{6} j_{y}^{3} \widehat{N_{3}^{3} f}\right)\right] .
\end{aligned}
$$

By Lemma 4.4, $j_{y}^{2} \widehat{N_{3}^{1} f}=0$ and $j_{y}^{3} \widehat{N_{3}^{2} f}=0$. The previous formula is simplified to the following one:

$$
\begin{align*}
\widehat{f}=\frac{c_{3, n}}{90}|y|[ & \widehat{N_{3}^{0} f}+\frac{3}{n+3} i j_{y} \operatorname{div} \widehat{N_{3}^{0} f}-\frac{3}{n+3} i_{y}\left(\operatorname{div} \widehat{N_{3}^{0} f}-j_{y} \widehat{N_{3}^{1} f}\right)  \tag{7.11}\\
& +\frac{3}{(n+1)(n+3)} i_{y}^{2}\left(\operatorname{div}^{2} \widehat{N_{3}^{0} f}-2 \operatorname{div} j_{y} \widehat{N_{3}^{1} f}+\frac{1}{2} j_{y}^{2} \widehat{N_{3}^{2} f}\right) \\
& -\frac{3}{2(n+1)(n+3)} i i_{y}\left(j_{y} \operatorname{div}^{2} \widehat{N_{3}^{0} f}-2 j_{y} \operatorname{div} j_{y} \widehat{N_{3}^{1} f}\right) \\
& \left.-\frac{1}{(n-1)(n+1)(n+3)} i_{y}^{3}\left(\operatorname{div}^{3} \widehat{N_{3}^{0} f}-3 \operatorname{div}^{2} j_{y} \widehat{N_{3}^{1} f}+\frac{3}{2} \operatorname{div} j_{y}^{2} \widehat{N_{3}^{2} f}-\frac{1}{6} j_{y}^{3} \widehat{N_{3}^{3} f}\right)\right] .
\end{align*}
$$

At least three terms on the right-hand side of (7.11) can be simplified. Indeed, using Lemma 4.4 and the commutator formula (7.7), we transform

$$
\begin{equation*}
j_{y} \operatorname{div} \widehat{N_{3}^{0} f}=\operatorname{div} j_{y} \widehat{N_{3}^{0} f}-j \widehat{N_{3}^{0} f}=-j \widehat{N_{3}^{0} f} \tag{7.12}
\end{equation*}
$$

Quite similarly,

$$
\begin{equation*}
j_{y} \operatorname{div} j_{y} \widehat{N_{3}^{1} f}=\left(\operatorname{div} j_{y}-j\right) j_{y} \widehat{N_{3}^{1} f}=\operatorname{div} j_{y}^{2} \widehat{N_{3}^{1} f}-j j_{y} \widehat{N_{3}^{1} f}=-j j_{y} \widehat{N_{3}^{1} f}=-j_{y} j \widehat{N_{3}^{1} f} . \tag{7.13}
\end{equation*}
$$

We have used that operators $j$ and $j_{y}$ commute. Let us also transform the term containing $j_{y} \operatorname{div}^{2}$

$$
\begin{aligned}
j_{y} \operatorname{div}^{2} \widehat{N_{3}^{0} f} & =\left(j_{y} \operatorname{div}\right) \operatorname{div} \widehat{N_{3}^{0} f}=\left(\operatorname{div} j_{y}-j\right) \operatorname{div} \widehat{N_{3}^{0} f} \\
& =\operatorname{div}\left(j_{y} \operatorname{div}\right) \widehat{N_{3}^{0} f}-j \operatorname{div} \widehat{N_{3}^{0} f}=\operatorname{div}\left(\operatorname{div} j_{y}-j\right) \widehat{N_{3}^{0} f}-j \operatorname{div} \widehat{N_{3}^{0} f} \\
& =\operatorname{div}^{2} j_{y} \widehat{N_{3}^{0} f}-\operatorname{div} j \widehat{N_{3}^{0} f}-j \operatorname{div} \widehat{N_{3}^{0} f}=-\operatorname{div} j \widehat{N_{3}^{0} f}-j \operatorname{div} \widehat{N_{3}^{0} f} .
\end{aligned}
$$

Using that $j$ and div commute [DS10], we get

$$
\begin{equation*}
j_{y} \operatorname{div}^{2} \widehat{N_{3}^{0} f}=-2 j \operatorname{div} \widehat{N_{3}^{0} f} \tag{7.14}
\end{equation*}
$$

Substituting expressions (7.12)-(7.14) and the value (7.10) of the constant $c_{3, n}$ into (7.11), we obtain the inversion formula recovering the Fourier transform of a tensor field $f \in \mathcal{S}\left(\mathbb{R}^{n} ; S^{3}\right)(n \geq 2)$ through the data $\left(\widehat{N_{3}^{0} f}, j_{y} \widehat{N_{3}^{1} f}, j_{y}^{2} \widehat{N_{3}^{2}} f, j_{y}^{3} \widehat{N_{3}^{3} f}\right)$

$$
\begin{aligned}
\widehat{f} & =\frac{2^{n / 2} \Gamma\left(\frac{n+5}{2}\right)}{3 \sqrt{\pi}}|y|\left[\widehat{N_{3}^{0} f}-\frac{3}{n+3} i j \widehat{N_{3}^{0} f}\right. \\
& -\frac{3}{(n+1)(n+3)} i_{y}\left((n+1) \operatorname{div} \widehat{N_{3}^{0} f}-i j \operatorname{div} \widehat{N_{3}^{0} f}-(n+1) j_{y} \widehat{N_{3}^{1} f}+i j j_{y} \widehat{N_{3}^{1} f}\right) \\
& +\frac{3}{(n+1)(n+3)} i_{y}^{2}\left(\operatorname{div}^{2} \widehat{N_{3}^{0} f}-2 \operatorname{div} j_{y} \widehat{N_{3}^{1} f}+\frac{1}{2} j_{y}^{2} \widehat{N_{3}^{2} f}\right) \\
& \left.-\frac{1}{(n-1)(n+1)(n+3)} i_{y}^{3}\left(\operatorname{div}^{3} \widehat{N_{3}^{0} f}-3 \operatorname{div}^{2} j_{y} \widehat{N_{3}^{1} f}+\frac{3}{2} \operatorname{div} j_{y}^{2} \widehat{N_{3}^{2} f}-\frac{1}{6} j_{y}^{3} \widehat{N_{3}^{3} f}\right)\right] .
\end{aligned}
$$

The same approach can be used for deriving the inversion formula for $m=4,5, \ldots$ The length of the formula grows with $m$ as well as the volume of calculations.

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