

Time-dependent conformal mapping techniques applied to fluid sloshing problems

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Outline

- 1 Fluid Problem and Governing Equations
- 2 General conjugate function theory
- 3 Return to Fluid Problem
- 4 Sloshing with Baffles
- 5 Dynamic Problem

Diagram illustrating a fluid domain in the x - y plane. The domain is bounded by $x=0$, $x=1$, and $y=0$. The top boundary is a free surface $y = \eta(x, t)$. The fluid is labeled $\phi(x, y, t)$. A horizontal arrow labeled $F(t)$ points to the right from the right boundary $x=1$. The x -axis is marked with 0 and 1, and the y -axis is marked with y .

$F(t)$ is either an imposed external forcing (given), or a coupled forcing (calculated via additional equation).

In anticipation of using conformal mappings we extend the domain from $x \in [0, 1]$ to $x \in [0, 2]$ by forming the even extension about $x = 1$.

This gives a periodic domain with period 2 in our notation.

Mass conservation gives

$$\Delta\phi := \phi_{xx} + \phi_{yy} = 0, \quad 0 < y < \eta(x, t), \quad 0 < x < 1.$$

Kinematic (free-surface particles remain on the free-surface)
free-surface condition is

$$\eta_t + \phi_x \eta_x = \phi_y \quad \text{at} \quad y = \eta(x, t) \quad 0 \leq x \leq 1.$$

While the dynamic (continuity of pressure) free-surface condition is:

$$\begin{aligned} \phi_t + \frac{1}{2}(\phi_x^2 + \phi_y^2) + g(\eta - h_0) + x\ddot{F} &= 0, \\ \text{on } y &= \eta(x, t) \quad 0 \leq x \leq 1 \\ \phi_t + \frac{1}{2}(\phi_x^2 + \phi_y^2) + g(\eta - h_0) + (2-x)\ddot{F} &= 0, \\ \text{on } y &= \eta(x, t) \quad 1 \leq x \leq 2 \end{aligned}$$

The boundary conditions at the vessel walls are

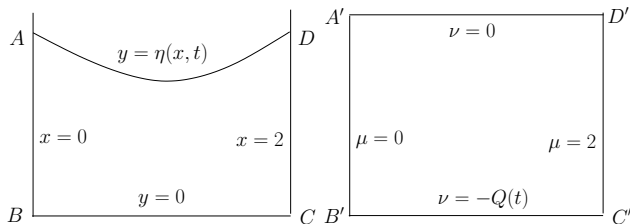
$$\phi_y = 0 \quad \text{at} \quad y = 0 \quad \text{and} \quad \phi_x = 0 \quad \text{at} \quad x = 0, 1, 2.$$

Additional equation for $F(t)$ if required.

To generate fully nonlinear numerical solutions of these equations is difficult due to the unknown position of the free-surface $\eta(x, t)$.

Numerical schemes are easier to implement on fixed domains.

Thus we wish to introduce a mapping such that:



where $Q(t)$ is the conformal modulus which is not known a priori.

Therefore the physical Cartesian coordinates transform to

$$(\mu, \nu, t) \mapsto (x(\mu, \nu, t), y(\mu, \nu, t)).$$

As the mapping is conformal

$$x_\mu = y_\nu \quad \text{and} \quad x_\nu = -y_\mu,$$

then both x and y satisfy Laplace's equation

$$x_{\mu\mu} + x_{\nu\nu} = 0, \quad y_{\mu\mu} + y_{\nu\nu} = 0.$$

On the free-surface

$$(X(\mu, t), Y(\mu, t)) = (x(\mu, 0, t), y(\mu, 0, t)) \quad \text{for} \quad \mu \in [0, 2].$$

gives parametric representation of free-surface.

Writing the free-surface equations in parametric form in the rectangular computational domain are

$$X_{\mu} Y_t - Y_{\mu} X_t = -\Psi_{\mu}, \quad \text{at } \nu = 0.$$

and

$$J\Phi_t - (Y_{\mu} Y_t + X_{\mu} X_t)\Phi_{\mu} + \frac{1}{2}(\Phi_{\mu}^2 - \Psi_{\mu}^2) + gJ(Y - h_0) + X\ddot{F} = 0, \\ \text{at } \nu = 0,$$

where $J = X_{\mu}^2 + Y_{\mu}^2$.

The bottom boundary condition reduces to

$$\psi_{\mu} = 0 \quad \text{on } \nu = -Q(t).$$

Ultimately, we hope to time-integrate these equations to find X , Y and Φ , but these two equations are implicit for the time derivative terms, hence are difficult to time integrate using Runge-Kutta, say.

But we note that for the parameterised curve $(X(\mu, t), Y(\mu, t))$, any curve can be written as the linear combination of its tangent vector (X_μ, Y_μ) and its normal vector $(-Y_\mu, X_\mu)$, so

$$\begin{aligned} X_t &= -\frac{\beta}{J} Y_\mu + \frac{\alpha}{J} X_\mu \\ Y_t &= \frac{\beta}{J} X_\mu + \frac{\alpha}{J} Y_\mu, \end{aligned}$$

where $\beta = -\Psi_\mu$ from the kinematic condition. Here α , representing the tangential fluid velocity, is unknown at this stage but is fixed by forcing the transformation to be analytic.

Also the dynamic condition becomes

$$\Phi_t = -g(Y - \delta) - \frac{1}{2J} \Phi_\mu^2 + \frac{1}{2J} \Psi_\mu^2 + \frac{\alpha}{J} \Phi_\mu.$$

Note: There is no PDE for Ψ hence we cannot directly time integrate these equations, we also have the problem of determining the form of α . However we do have the two complex functions

$$z = x + iy$$

$$w = \phi + i\psi.$$

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Consider a general analytical function $u(\mu, \nu) + i\nu(\mu, \nu)$ in the periodic half space $\mu \in [0, 2]$, $\nu \in [-\infty, 0]$ (i.e. infinite depth fluid). Using the mapping

$$\xi = \exp(-i\pi(\mu + i\nu)),$$

maps this domain to the inside of the unit circle.

Via Cauchy's integral theorem we have

$$u(\xi) + i\nu(\xi) = -\frac{1}{2\pi i} \oint_0^{2\pi} \frac{U(\theta) + iV(\theta)}{\theta - \xi} d\theta,$$

where $U(\mu) + iV(\mu) = u(\mu, 0) + i\nu(\mu, 0)$.

When evaluated on the edge of the disk, and using the above transformation leads to

$$U(\mu) + iV(\mu) = \frac{1}{2} \int_0^2 (U(s) + iV(s)) \left[1 - i \cot \left(\frac{\pi}{2}(\mu - s) \right) \right] ds.$$

or

$$(\mathbf{I} + i\mathbf{K})(U + iV) = \overline{U} + i\overline{V}.$$

Here

$$\mathbf{K}(U)(\mu) := \frac{1}{2} \int_0^2 U(s) \cot \left(\frac{\pi}{2}(\mu - s) \right) ds,$$

is the Hilbert transform and

$$\overline{(\cdot)} = \frac{1}{2} \int_0^2 (\cdot) d\mu.$$

Taking real and imaginary parts shows how these quantities are linked on the free-surface

$$V = \overline{V} - \mathbf{K}(U) \quad \text{and} \quad U = \overline{U} + \mathbf{K}(V).$$

Given V we then know U and vice versa.

In finite depth the bottom and surface conjugate functions are related (using the same procedure) by the Hilbert-Garrick transformation

$$\begin{bmatrix} \mathbf{I} + i(\mathbf{K} + \mathbf{R}_q) & -i\mathbf{S}_q \\ +i\mathbf{S}_q & \mathbf{I} - i(\mathbf{K} + \mathbf{R}_q) \end{bmatrix} \begin{pmatrix} U + iV \\ U_b + iV_b \end{pmatrix} = \begin{pmatrix} \bar{U} + i\bar{V} \\ \bar{U}_b + i\bar{V}_b \end{pmatrix},$$

where $U_b(\mu) + iV_b(\mu) = u(\mu, -Q) + iv(\mu, -Q)$.

Here $\mathbf{S}_q$ and $\mathbf{R}_q$ are integral transformations which depend upon the conformal modulus $Q(t)$.

Hence if we know (V, V_b) then we can use the Hilbert-Garrick transformation to determine (U, U_b) or vice versa.

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Determining α

To find the value of α (the tangential fluid velocity at the surface) we note that z_t/z_ζ ($\zeta = \mu + i\nu$) is an analytic function with boundary values

$$\operatorname{Im} \left(\frac{z_t}{z_\mu} \right) \Big|_{\nu=0} = \frac{\Psi_\mu}{J} \quad \text{and} \quad \operatorname{Im} \left(\frac{z_t}{z_\mu} \right) \Big|_{\nu=-Q(t)} = 0.$$

Hence the real part of z_t/z_μ on the free-surface (which is just α/J) can be determined by the Hilbert-Garrick transformation as

$$\frac{\alpha}{J} = \bar{\alpha} + (\mathbf{K} + \mathbf{R}_q) \left(-\frac{\Psi_\mu}{J} \right) = \bar{\alpha} - \mathbf{T}_q^{-1} \left(\frac{\Psi_\mu}{J} \right).$$

Easy to show that $\bar{\alpha} = 0$.

Also, using the Hilbert-Garrick transformation we can relate

$$X - \mu = \mathbf{T}_q^{-1}(Y) \quad \text{and} \quad \Psi = \mathbf{T}_q(\Phi).$$

Therefore we integrate

$$Y_t = -\frac{\Psi_\mu}{J} X_\mu - \mathbf{T}_q^{-1} \left(\frac{\Psi_\mu}{J} \right) Y_\mu,$$

$$\Phi_t = -g(Y - h_0) - \frac{1}{2J} \Phi_\mu^2 + \frac{1}{2J} \Psi_\mu^2 - \mathbf{T}_q^{-1} \left(\frac{\Psi_\mu}{J} \right) \Phi_\mu,$$

forward in time using 4th order Runge-Kutta, from some initial condition, for example if $F(t)$ is given then

$$X(\mu, 0) = \mu, \quad Y(\mu, 0) = \eta_0, \quad \Phi(\mu, 0) = 0, \quad \Psi(\mu, 0) = 0.$$

Discretize the free-surface via

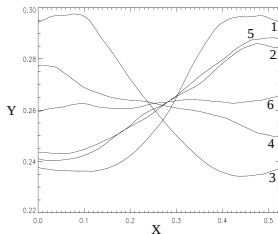
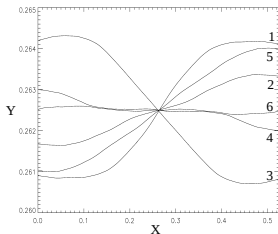
$$\mu_k = (k-1) \frac{1}{N} \quad k = 1, \dots, 2N.$$

For this doubly-connected problem we can easily solve Laplace's equation for x , y , ϕ , and ψ , which give us the Fourier form of the Hilbert-Garrick operators, for example

$$x - \mu = \sum_{n=1}^{\infty} A_n(t) \frac{\cosh((n\pi(\nu + Q)))}{\cosh(n\pi Q)} \sin(n\pi\mu),$$

$$y - \nu = Q(t) + \sum_{n=1}^{\infty} A_n(t) \frac{\sinh((n\pi(\nu + Q)))}{\cosh(n\pi Q)} \cos(n\pi\mu).$$

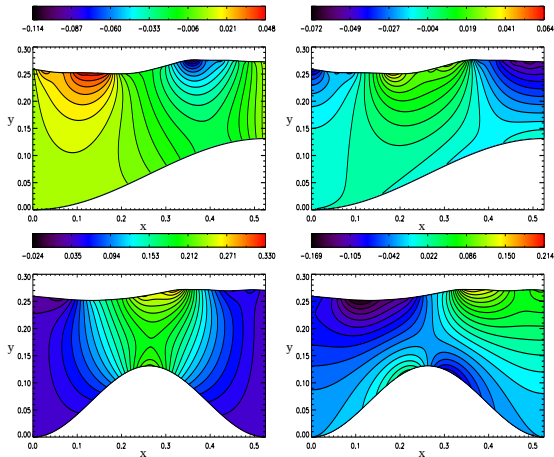
Hence we can use FFTs to determine the values of $A_n(t)$ on $\nu = 0$, reconstruct $X - \mu$ in Fourier space and then invert.



Forced variable bottom sloshing

Forced rectilinear sloshing in rectangular tank with bottom topography. Harmonic forcing $F(t) = \epsilon \cos(\omega t)$.

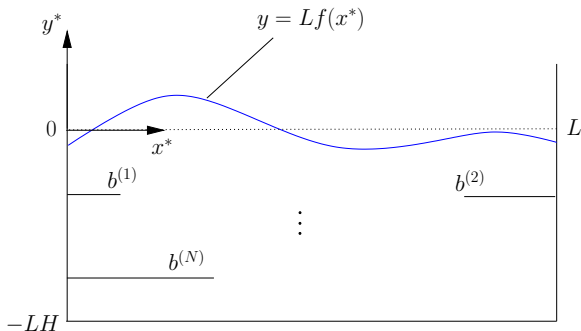
Horizontal and vertical velocities:



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Can we apply a similar complex analysis approach to incorporate N infinitely thin side-wall baffles?



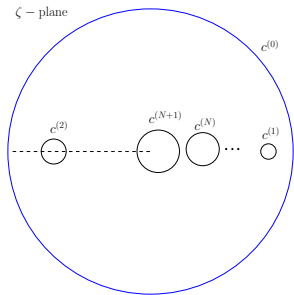
$$(x_0, y_0) = (x(\mu, 0), y(\mu, 0)), \quad \mu \in [-1, 1],$$

$$(x_n, y_n) = (x(\mu, -\hat{y}_n), y(\mu, -\hat{y}_n)), \quad \mu \in [-\hat{L}_n, \hat{L}_n],$$

$$\text{or } \mu \in [-1, -1 + \hat{L}_n] \cup [1 - \hat{L}_n, 1],$$

$$(x_{N+1}, y_{N+1}) = (x(\mu, -\hat{H}), y(\mu, -\hat{H})), \quad \mu \in [-1, 1].$$

Final mapping uses Schottky-Klein prime functions via the MATLAB routines of Crowdy, Kropf, Green and Nasser.



In the mapped domain we again apply Cauchy's theorem

$$\kappa(\zeta) = -\frac{1}{2\pi i} \oint_{\mathcal{C}} \frac{\kappa(\zeta')}{\zeta' - \zeta} d\zeta',$$

where

$$\kappa(\zeta) = (x(\zeta) - \mu(\zeta)) + i(y(\zeta) - \nu(\zeta)) = \tilde{x}(\zeta) + i\tilde{y}(\zeta).$$

which can be expressed as

$$\begin{aligned} \tilde{x}(\zeta) + i\tilde{y}(\zeta) &= \frac{1}{2\pi} \int_{-\pi}^{\pi} \frac{\tilde{x}_0(\theta) + i\tilde{y}_0(\theta)}{e^{i\theta} - \zeta} e^{i\theta} d\theta \\ &\quad - \sum_{n=1}^N \frac{q_n}{2\pi} \int_0^{2\pi} \frac{\tilde{x}_n(\phi) + i\tilde{y}_n(\phi)}{\delta_n + q_n e^{i\phi} - \zeta} e^{i\phi} d\phi \\ &\quad - \frac{q_{N+1}}{2\pi} \int_{-\pi}^{\pi} \frac{\tilde{x}_{N+1}(\theta) + i\tilde{y}_{N+1}(\theta)}{\delta_{N+1} + q_{N+1} e^{i\theta} - \zeta} e^{i\theta} d\theta. \end{aligned}$$

This is then evaluated on the free-surface, the bottom and on each baffle to generate $N + 2$ complex equations or $2N + 4$ real equations. For example

$$\begin{aligned} \tilde{x}_0(\sigma) + i\tilde{y}_0(\sigma) = & \frac{1}{2\pi} \int_{-\pi}^{\pi} (\tilde{x}_0(\theta) + i\tilde{y}_0(\theta)) d\theta \\ & - \frac{i}{2\pi} \mathcal{PV} \int_{-\pi}^{\pi} \cot \left[\frac{1}{2}(\theta - \sigma) \right] (\tilde{x}_0(\theta) + i\tilde{y}_0(\theta)) d\theta \\ & - \sum_{n=1}^N \frac{q_n}{\pi} \int_{-\pi}^{\pi} F_{n0}(\sigma, \phi) (\tilde{x}_n(\phi) + i\tilde{y}_n(\phi)) d\phi \\ & - \frac{q_{N+1}}{\pi} \int_{-\pi}^{\pi} F_{(N+1)0}(\sigma, \theta) (\tilde{x}_{N+1}(\theta) + i\tilde{y}_{N+1}(\theta)) d\theta. \end{aligned}$$

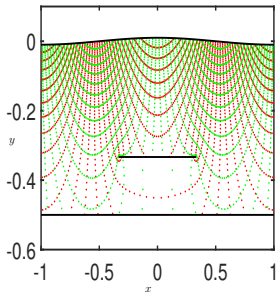
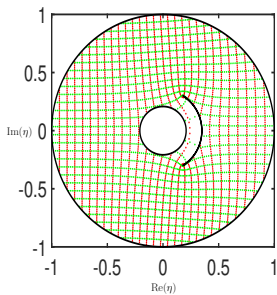
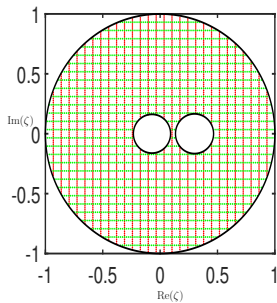
The ‘ F ’ functions are known functions in terms of the circle conformal moduli.

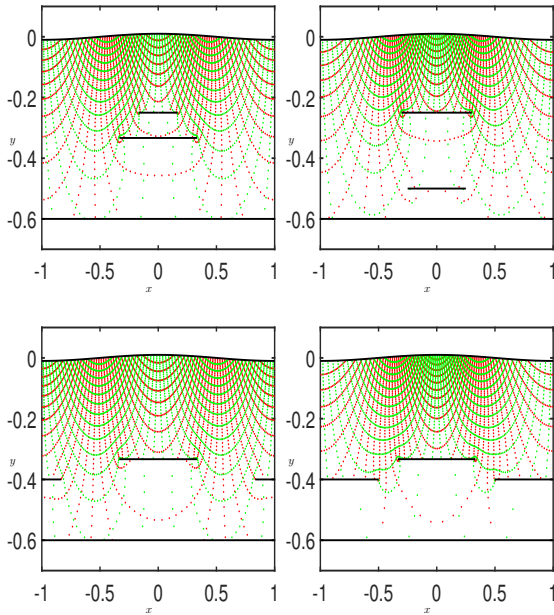
In order to perform a feasibility study for using this complex analysis approach for the dynamic fluid problem, we first consider a kinematic problem, such that the free-surface is specified, i.e $\eta(x, t) = f(x) = a \cos(\pi x)$.

In this case it means that we know $\tilde{y}_0, \tilde{y}_1, \tilde{y}_2, \dots, \tilde{y}_{N+1}$ and we need to calculate the corresponding $\tilde{x}_n$ values.

We discretize the integrals with equally spaced grid points, and then evaluate the equations from Cauchy's theorem at the mid-point of these grid points. This the PV integrals can be evaluated via the Trapezoidal rule.

These equations are then evaluated and we iteratively update the values of $\hat{y}_n, \hat{L}_n$ and $\hat{H}$. Essentially this is fixing the conformal moduli. ($\hat{H}(t)$ equivalent to $Q(t)$ in earlier notation)





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This feasibility study shows that the dynamic problem should be obtainable.

Some issues arising are:

- Equal spacing in μ does not translate to equal spacing in θ etc. So interpolation is needed at each iteration. Will this cause issues?

For the dynamic coupled problem $F(t)$ satisfies an equation similar to

$$(m_v + m_f)\ddot{F} + \nu F = -\frac{d}{dt} \int_0^L \int_0^{\eta(x,t)} \frac{\partial \phi}{\partial x} dy dx,$$

hence integral needs to be evaluated. But using Green's theorem this appears to be just line integrals along the surface, bottom and baffles.

Thank you