

# Motion, Monodromy, and Asymptotics

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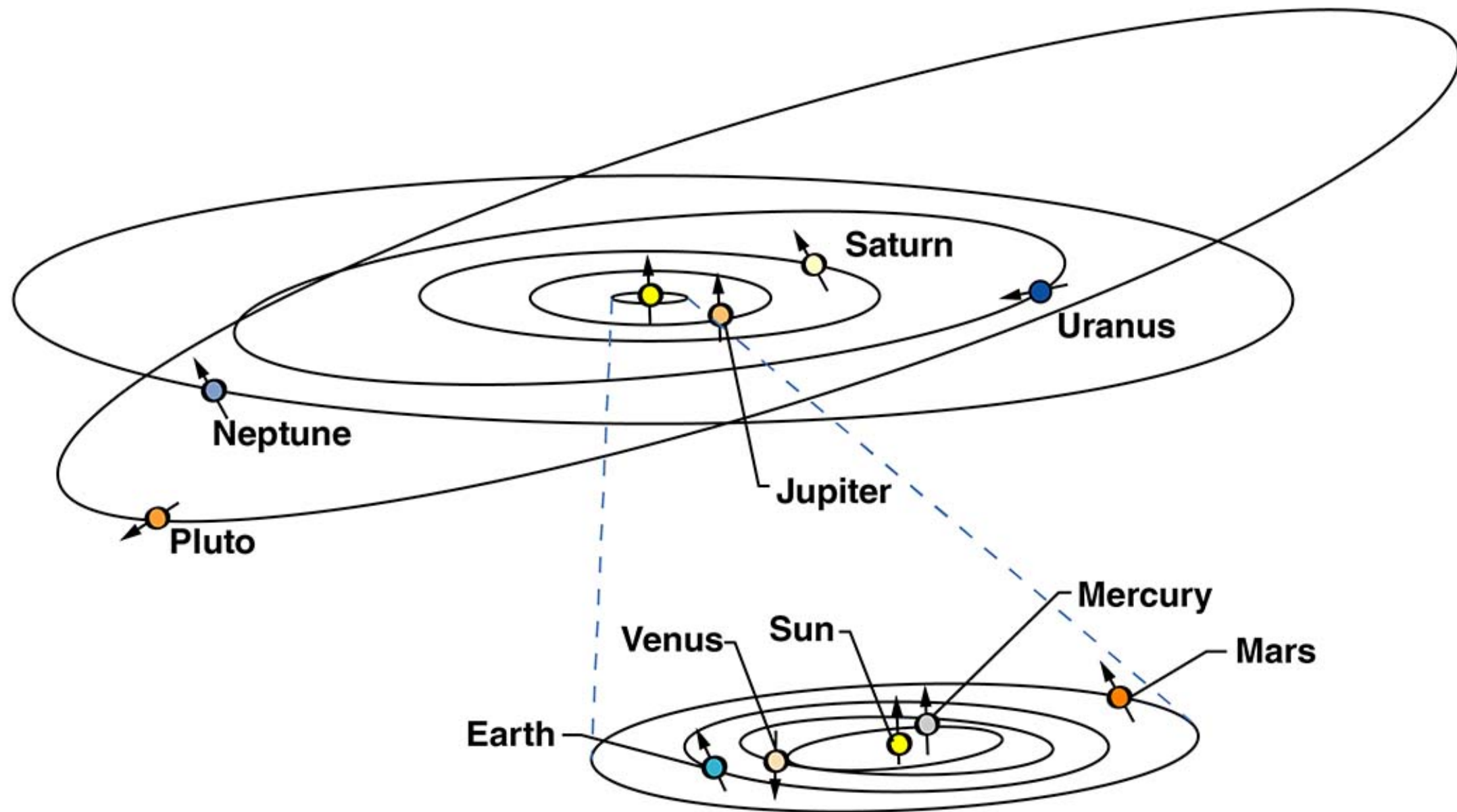




Grace Cossington Smith "*The bridge in-curve*" 1930, National Gallery of Victoria, Australia



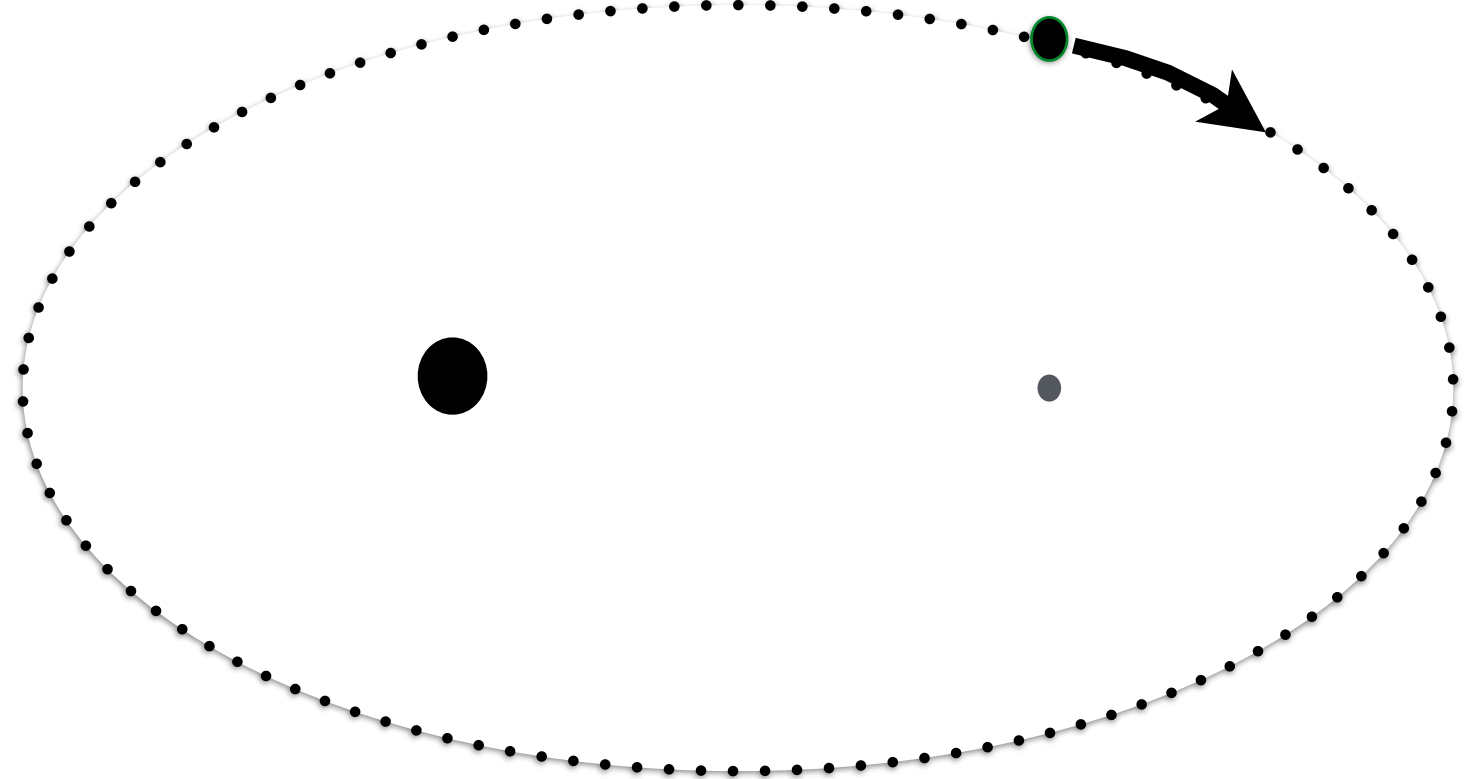
# Motion



Wikipedia

# Elliptic orbits

Kepler's first law: the orbit of every planet is an ellipse with the Sun at one of the two **foci**.

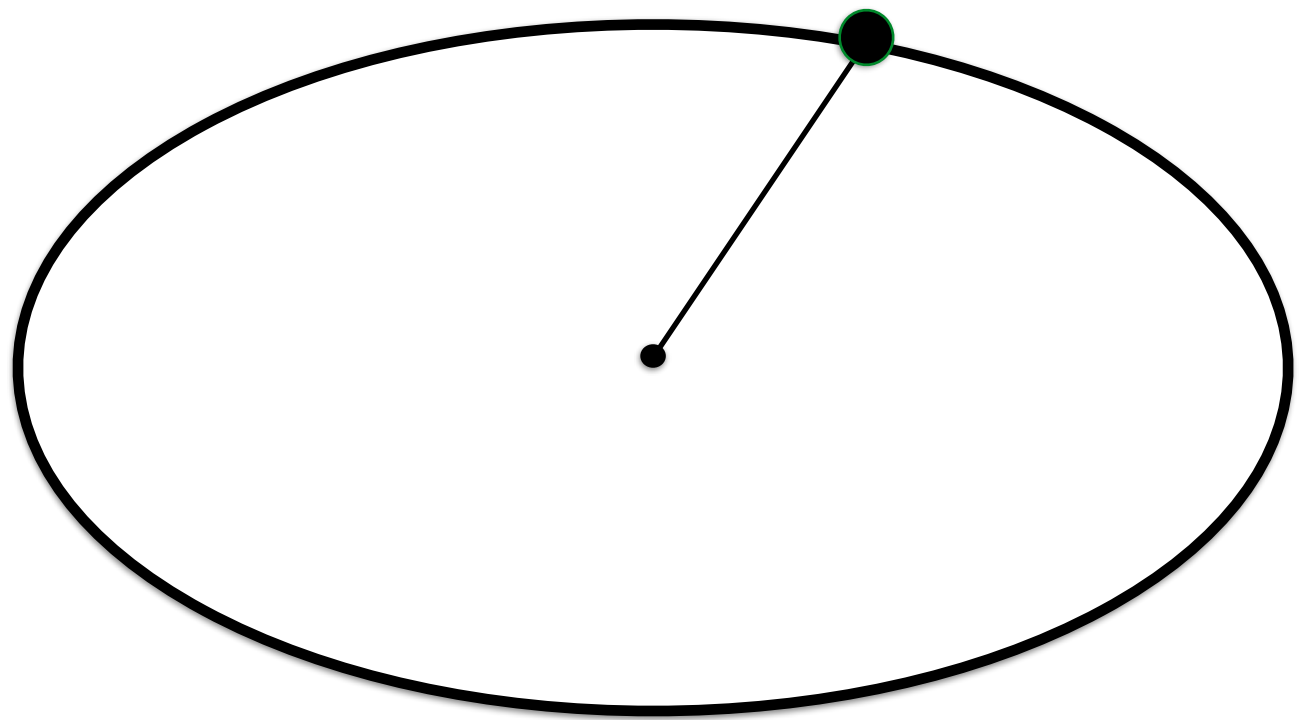




# Polynomials

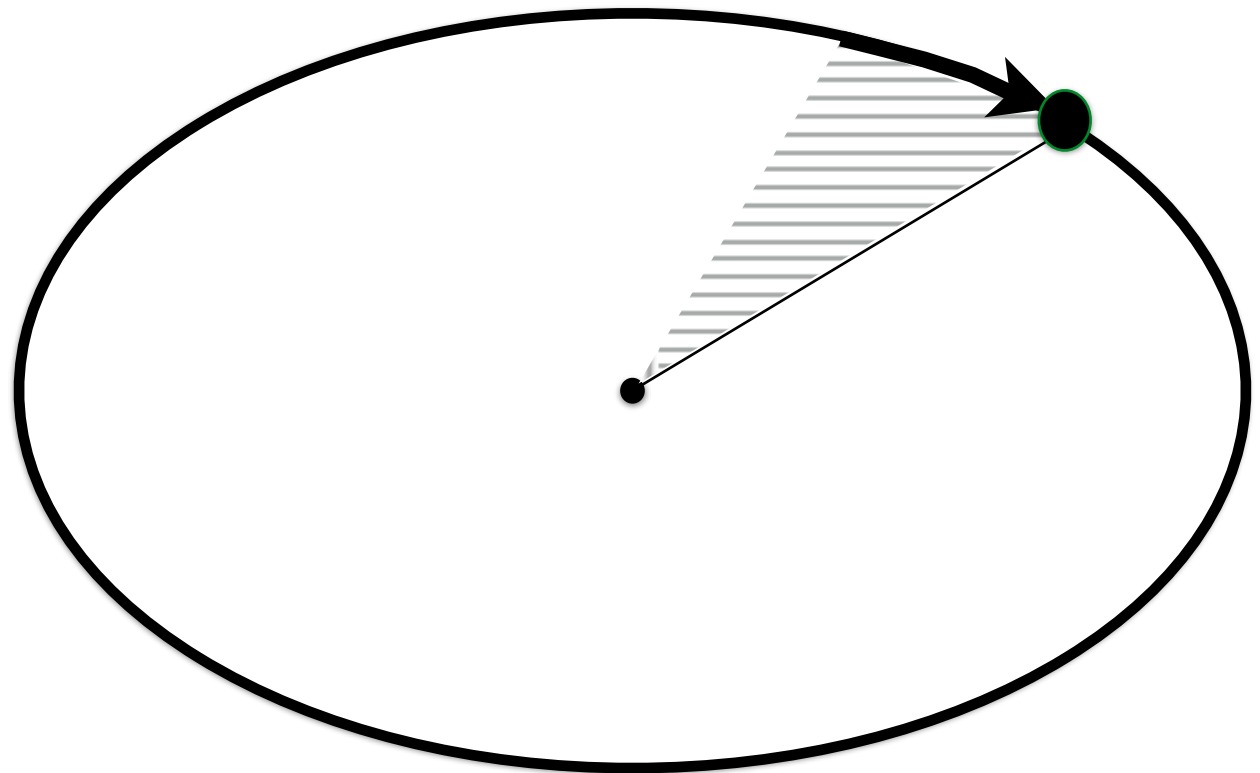
$$\frac{x^2}{a^2} + \frac{y^2}{b^2} - 1 = 0$$

The position  $(x, y)$  of a planet moving on an elliptical orbit is given by a polynomial of  $x$  and  $y$ .



# Area and arc length

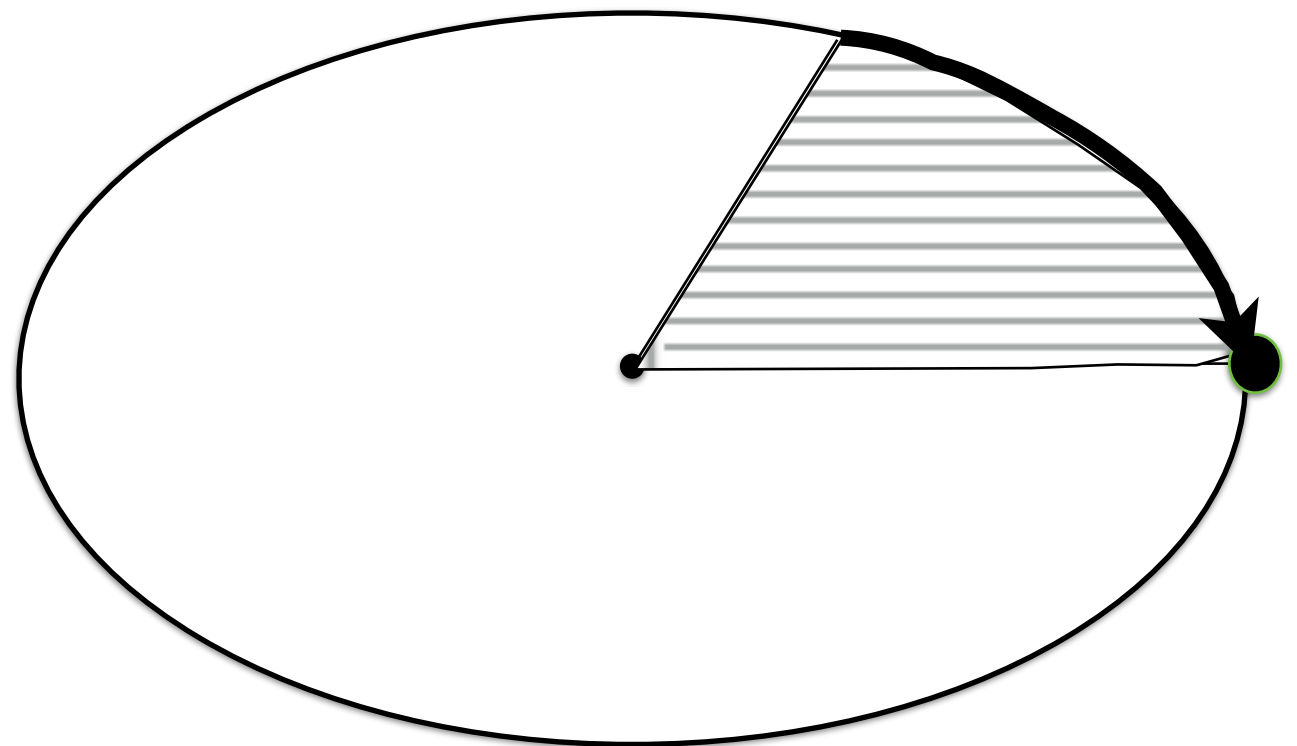
The area and arc length swept out by the ray to the planet are also functions of  $(x, y)$ .





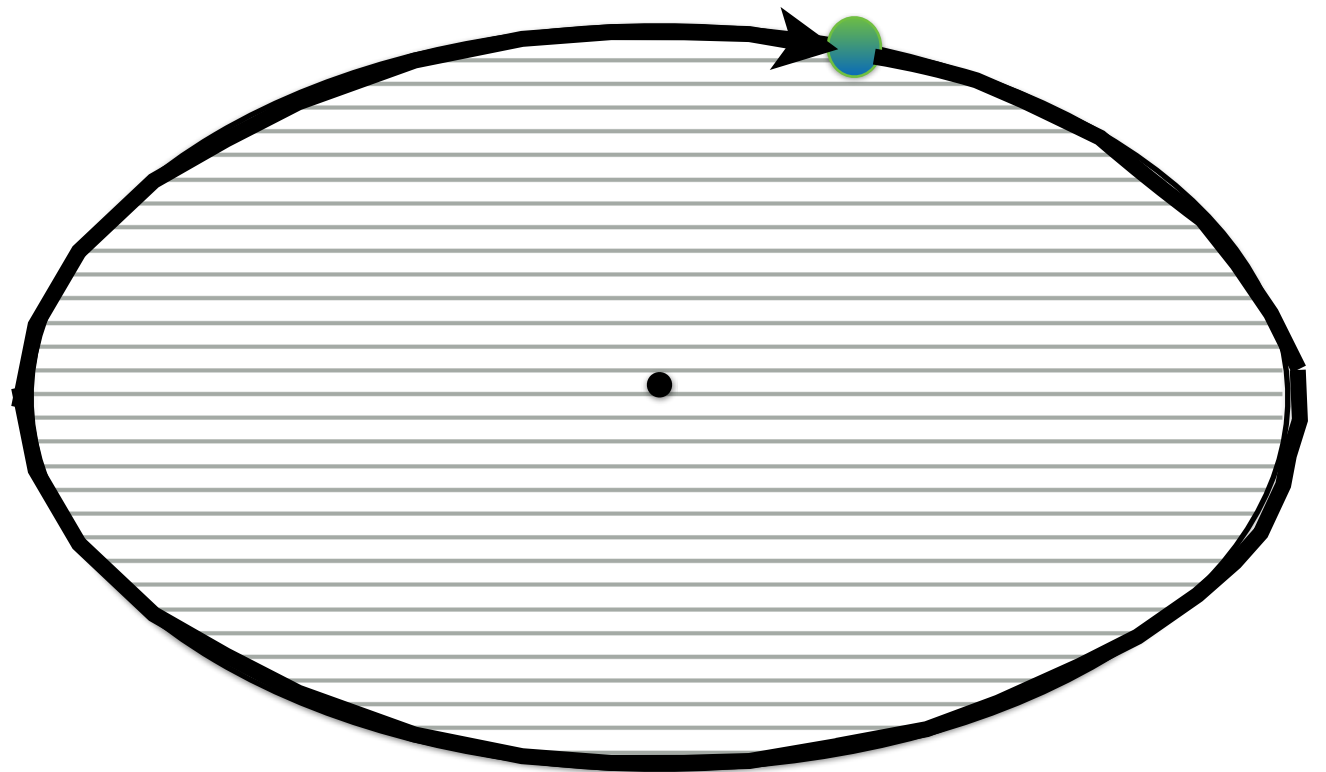
# Newton's question

So Newton asked, in 1687, whether the arc length and area swept out by the planet are also solutions of polynomial equations.



# Newton's answer I

As  $(x, y)$  moves along the orbit with time  $t$  and returns to the starting point, the ray to the planet has swept out the whole area bounded by the orbit.





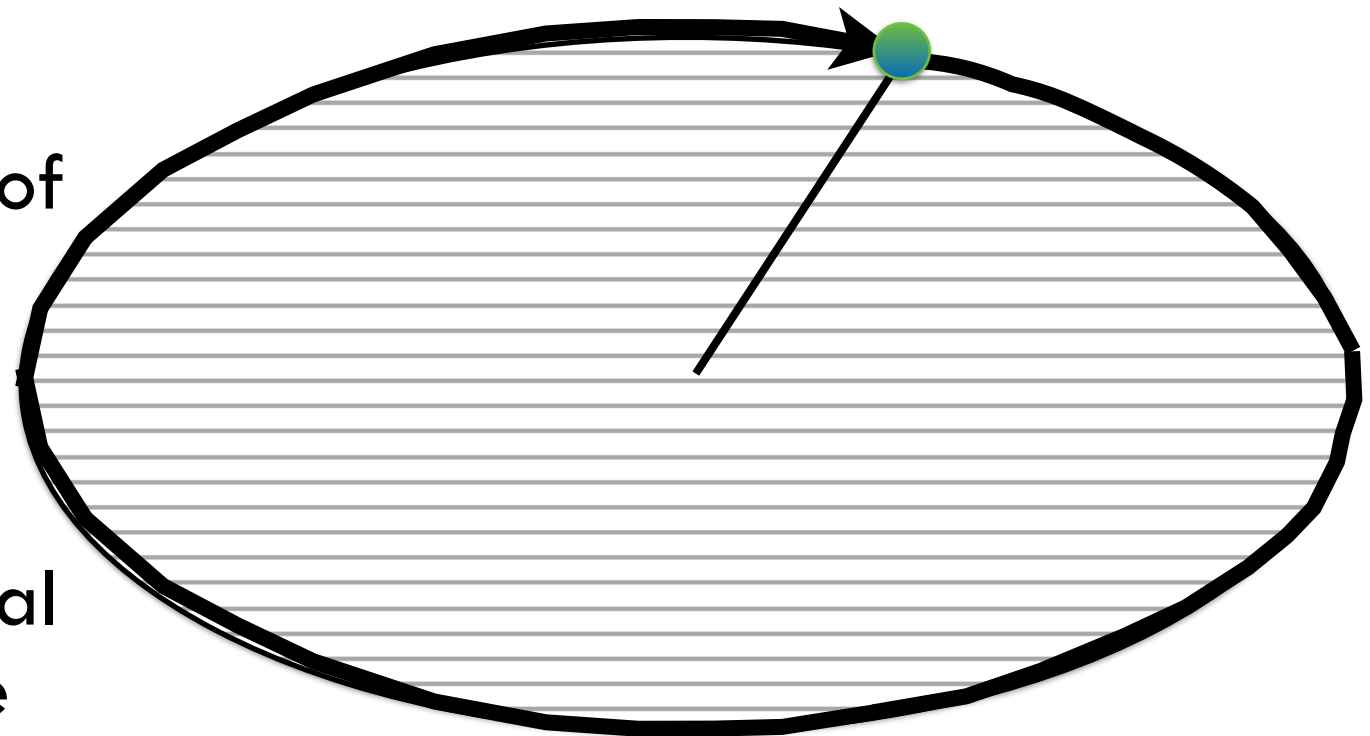
# Newton's answer II

The area increases again after another orbit, and again and again...

So, it takes an infinite number of values at each point  $(x, y)$

The same is true of the arc length.

But, the solution of a polynomial equation can only take a finite number of values (determined by its degree).



So the area and arc length cannot  
be solutions of a polynomial  
equation  $\Rightarrow$  They are  
**transcendental** functions.



# The arc length

The length along a small arc of the ellipse is

$$ds^2 = dx^2 + dy^2 = (a^2 \cos^2(\theta) + b^2 \sin^2(\theta)) d\theta^2$$

$$\Rightarrow s(\theta) = a \int_0^\theta \sqrt{1 - k^2 \sin^2(\theta)} d\theta \quad \text{Euler, 1738}$$

$$\text{where } k^2 = 1 - b^2/a^2$$

This is an elliptic integral (of the second kind). Legendre classified such integrals into three kinds in 1811. The integral of the first kind is

$$F(\theta, k) = \int_0^\theta \frac{d\theta}{\sqrt{1 - k^2 \sin^2(\theta)}}$$

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Inversion leads to *elliptic functions*:  $\text{sn}(t; k), \dots$

Abel 1825



# Weierstrass form

$$F(w, k) = \int_w^\infty \frac{du}{\sqrt{4u^3 - g_2u + g_3}}$$

Inverse function:  $\Rightarrow \wp(x; g_2, g_3)$

Weierstrass 1840s

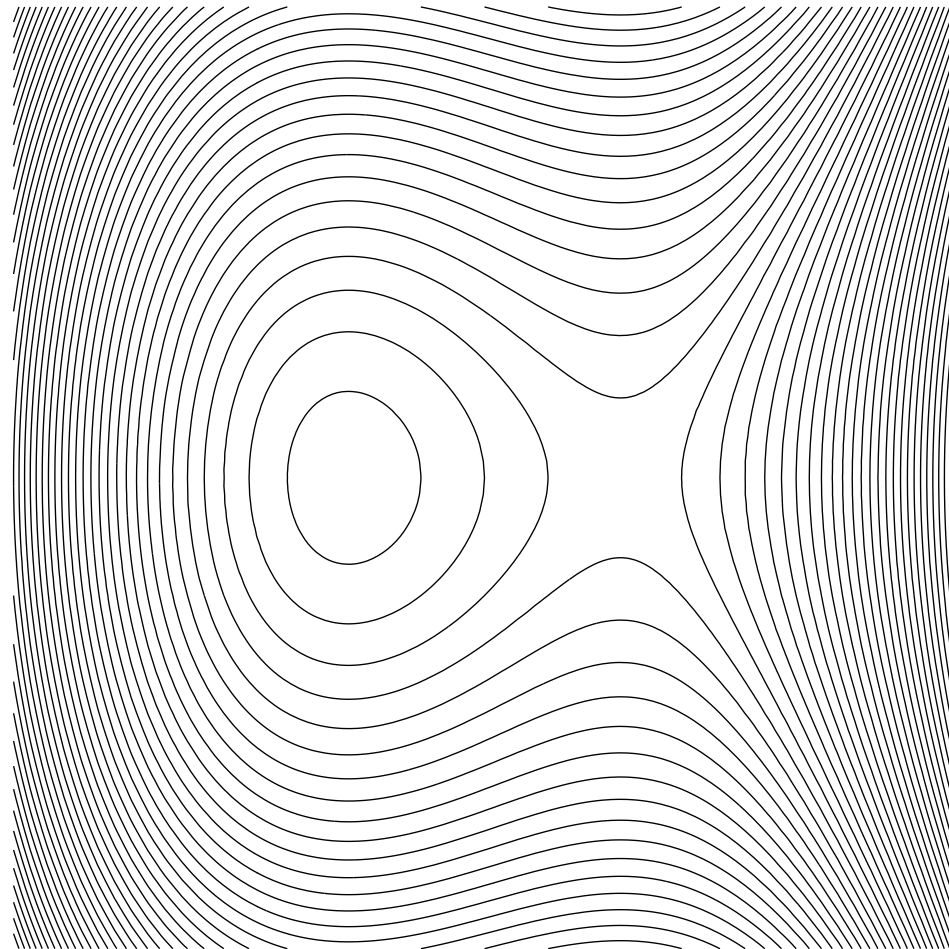
which satisfies differential equations:

$$w_x^2 = 4w^3 - g_2w + g_3$$

$$w_{xx} = 6w^2 - g_2$$

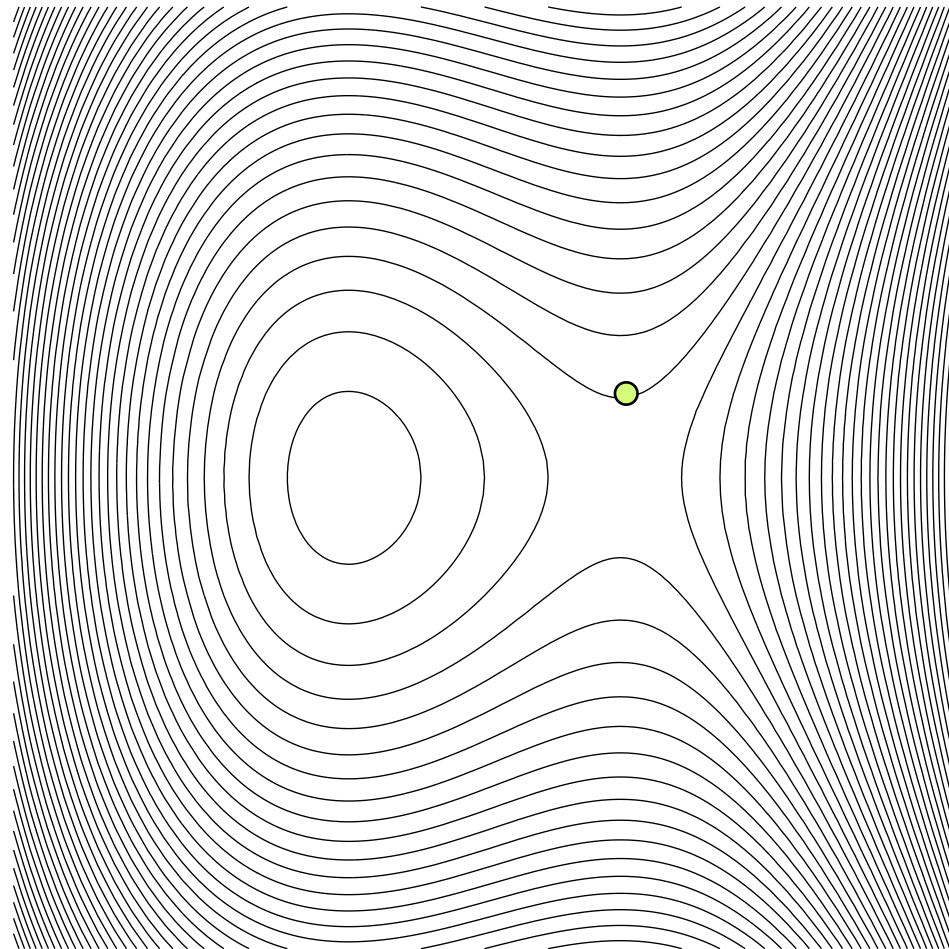
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$$y^2 - 4x^3 + g_2x - g_3 = 0$$



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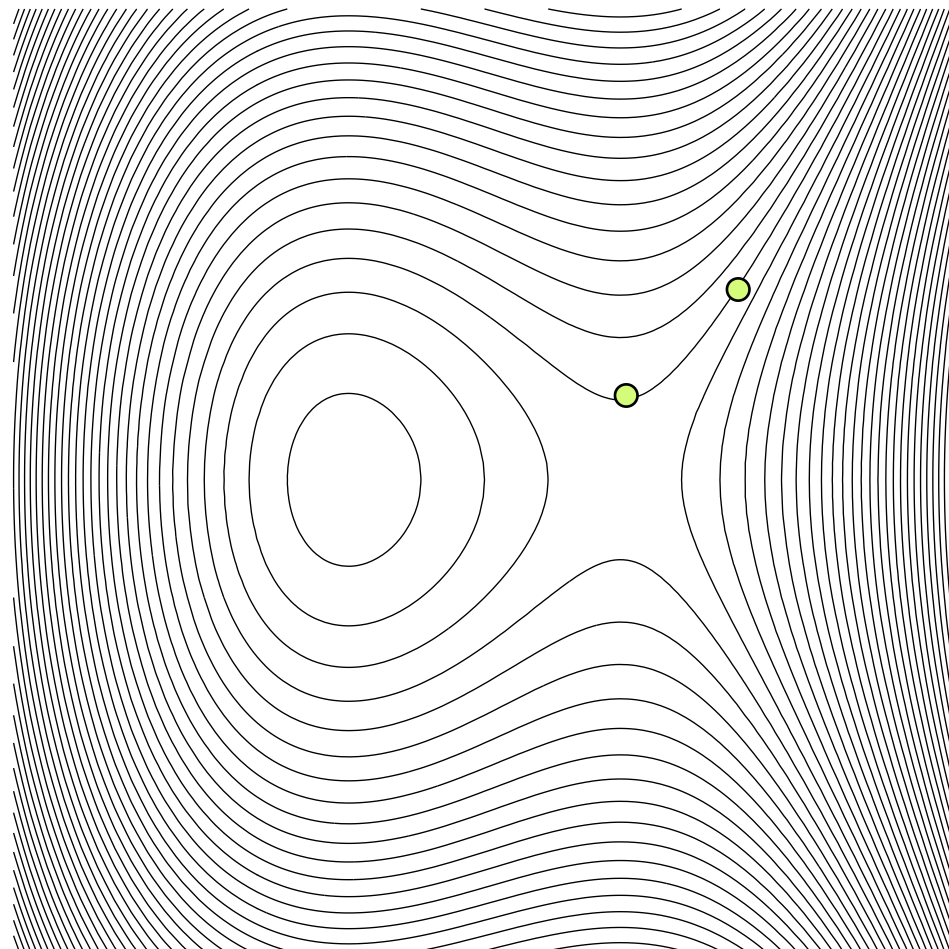
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For fixed  $g_2$ , each curve is parametrised by  $g_3$ , with points given by  $(\wp(s - s_0), \wp'(s - s_0))$ .

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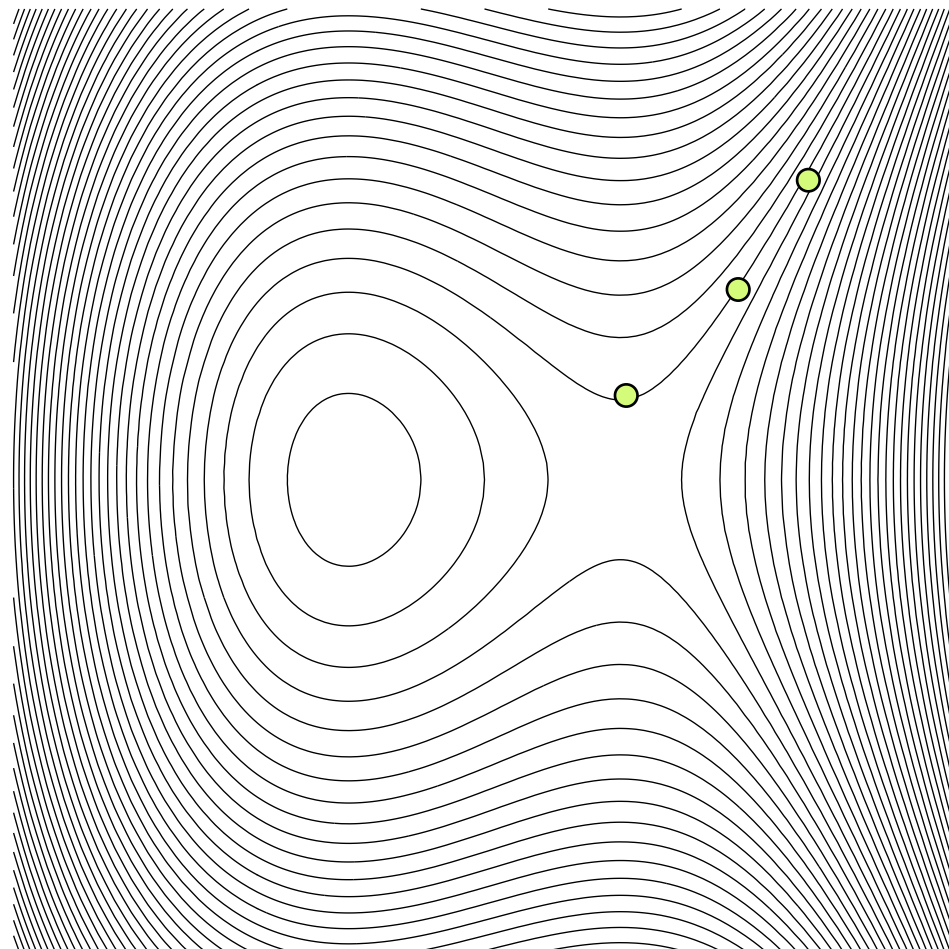


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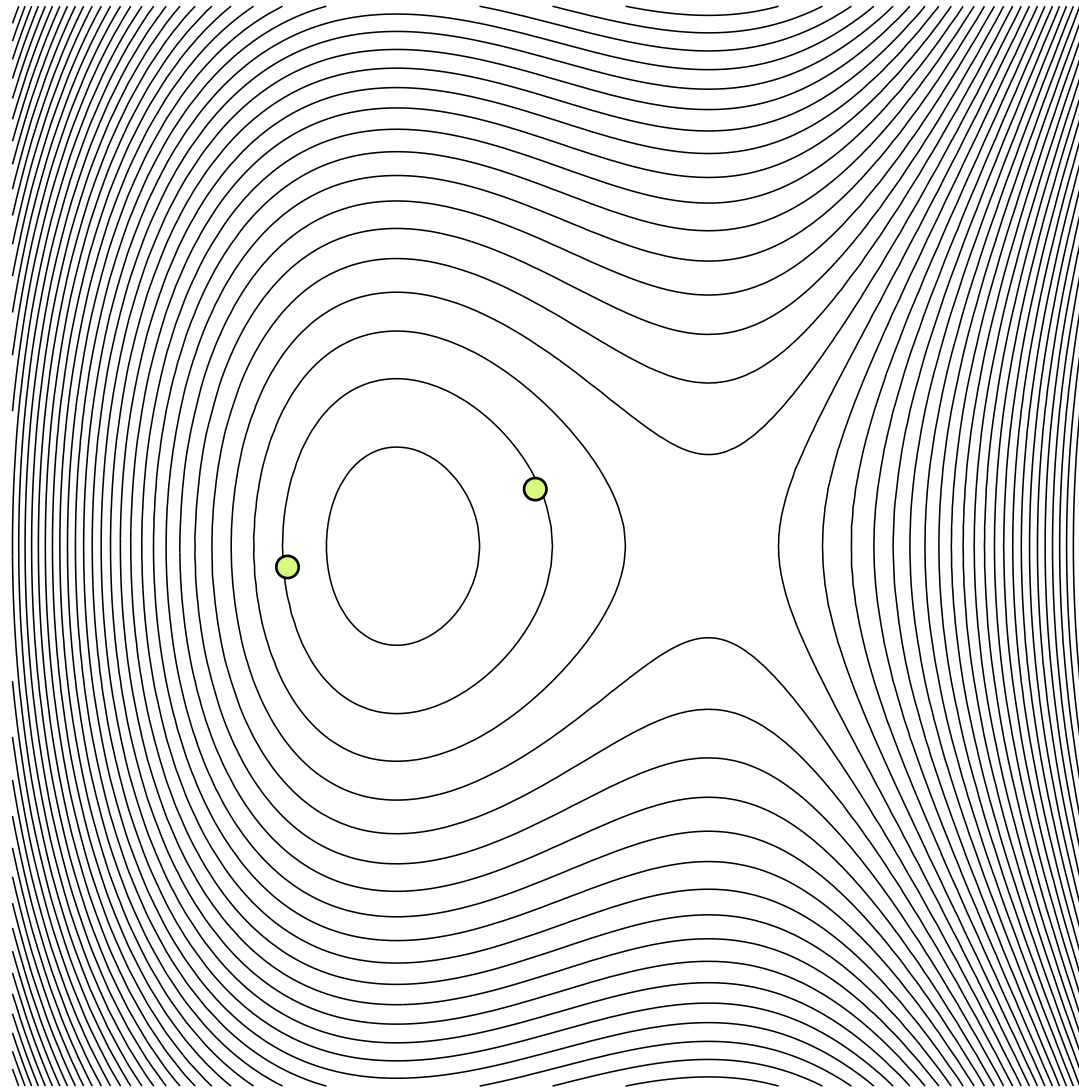
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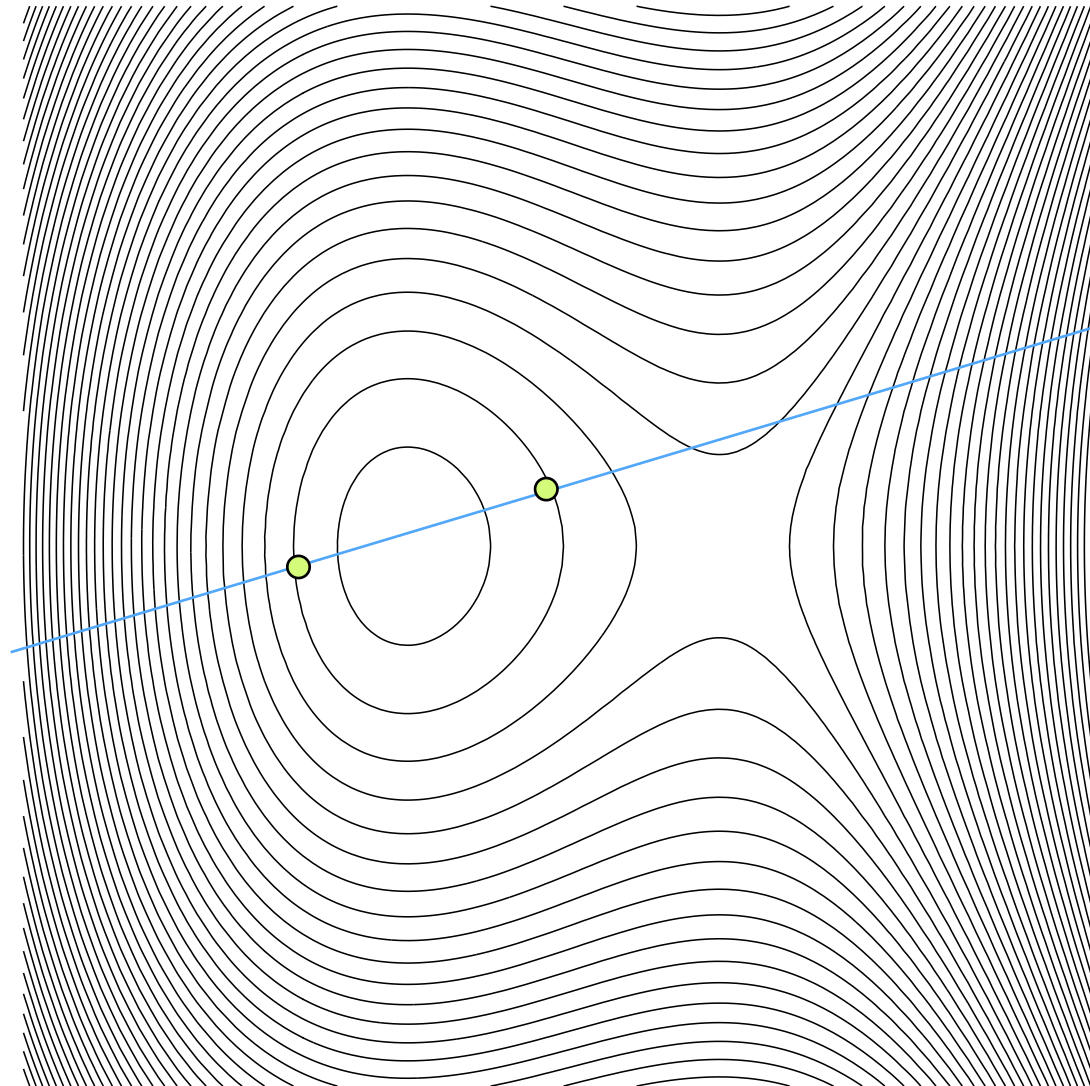


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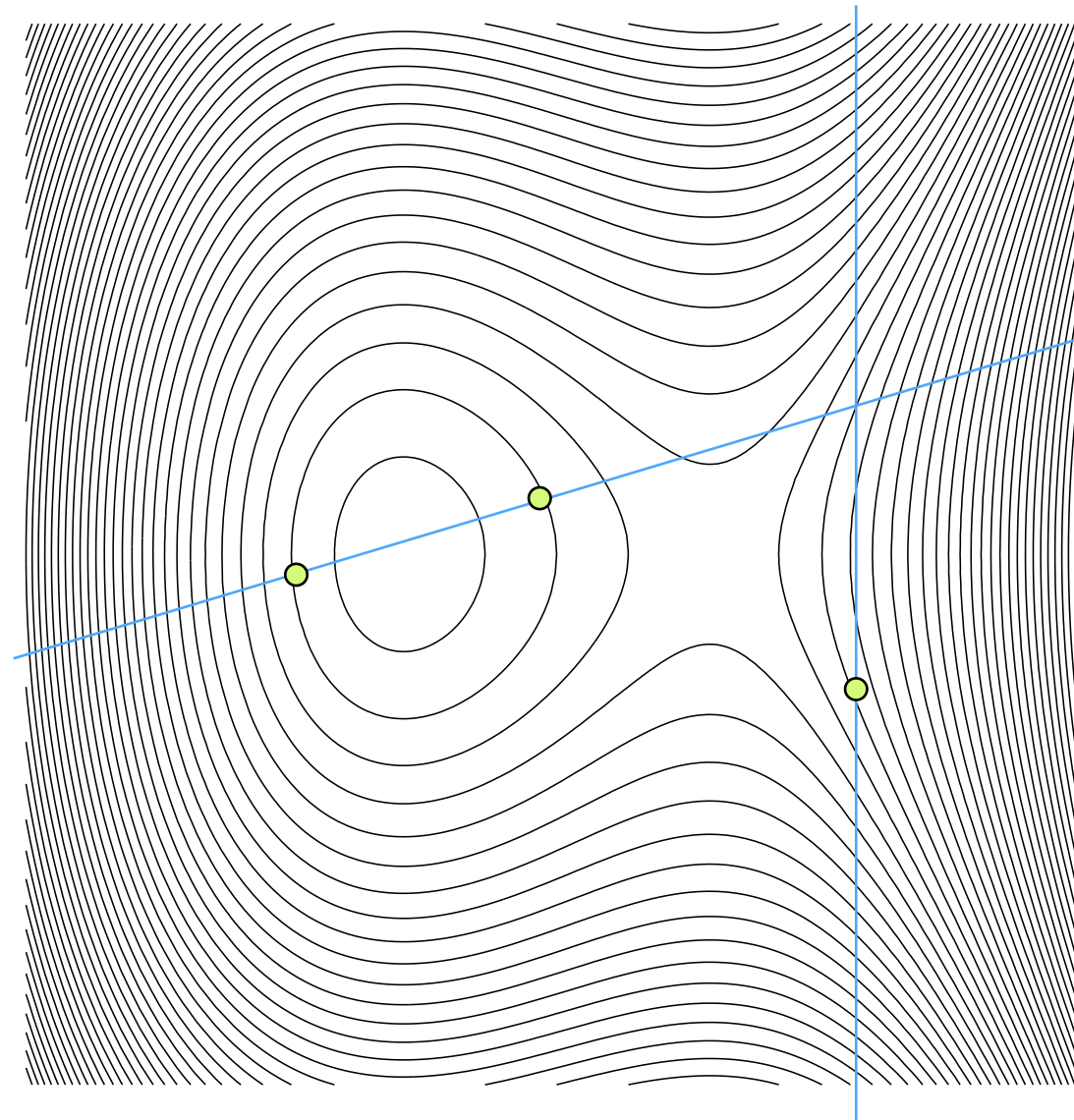
# Discrete motion



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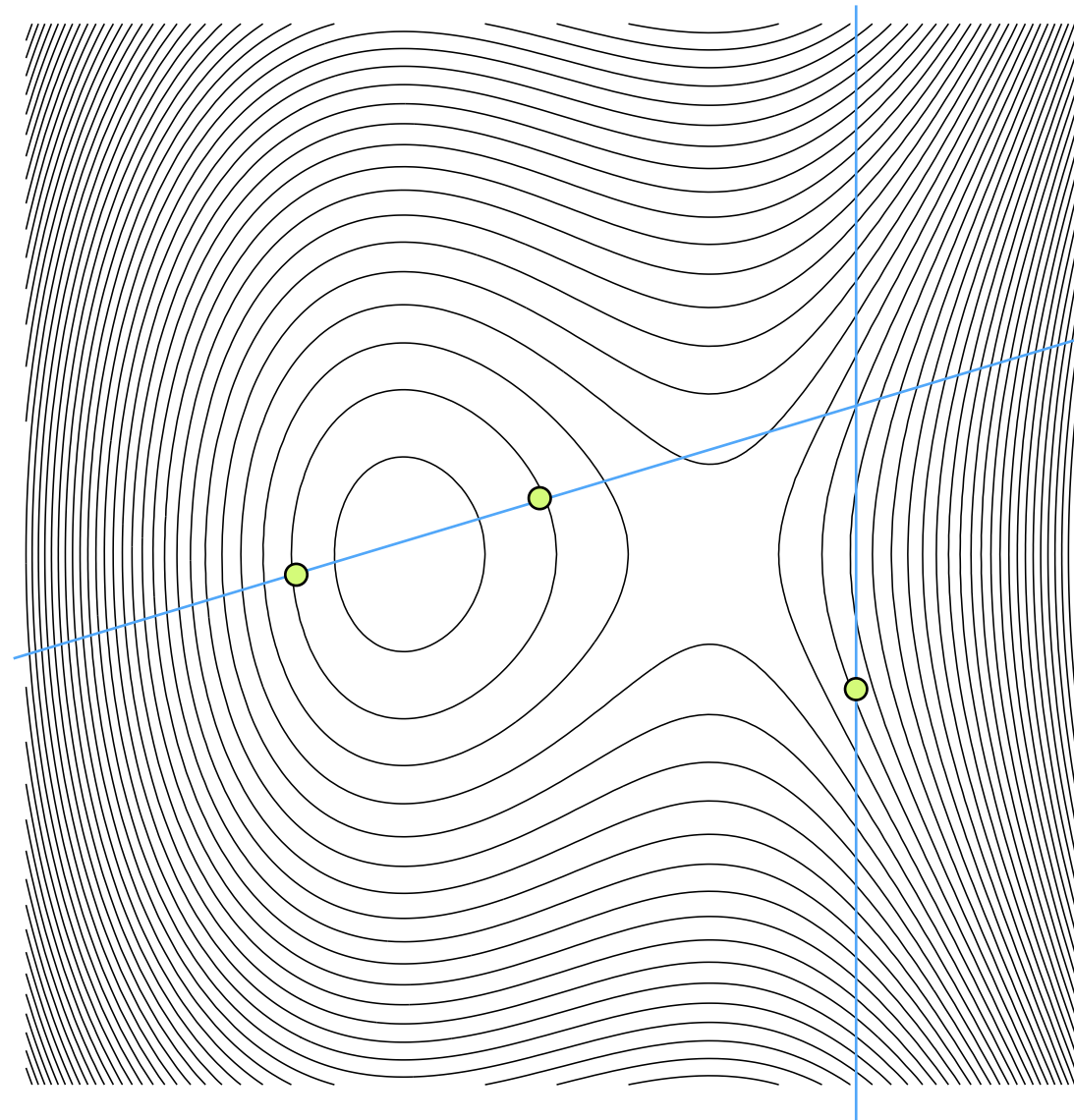


# Discrete motion





# Discrete motion



Elliptic functions satisfy an addition theorem.

# Cubic curves

$$y^2 = 4x^3 - g_2x + g_3$$

Newton classified all irreducible cubic curves in an unpublished manuscript, and defined functions through “Puisseux” series, e.g.,

*Newton, 1676*

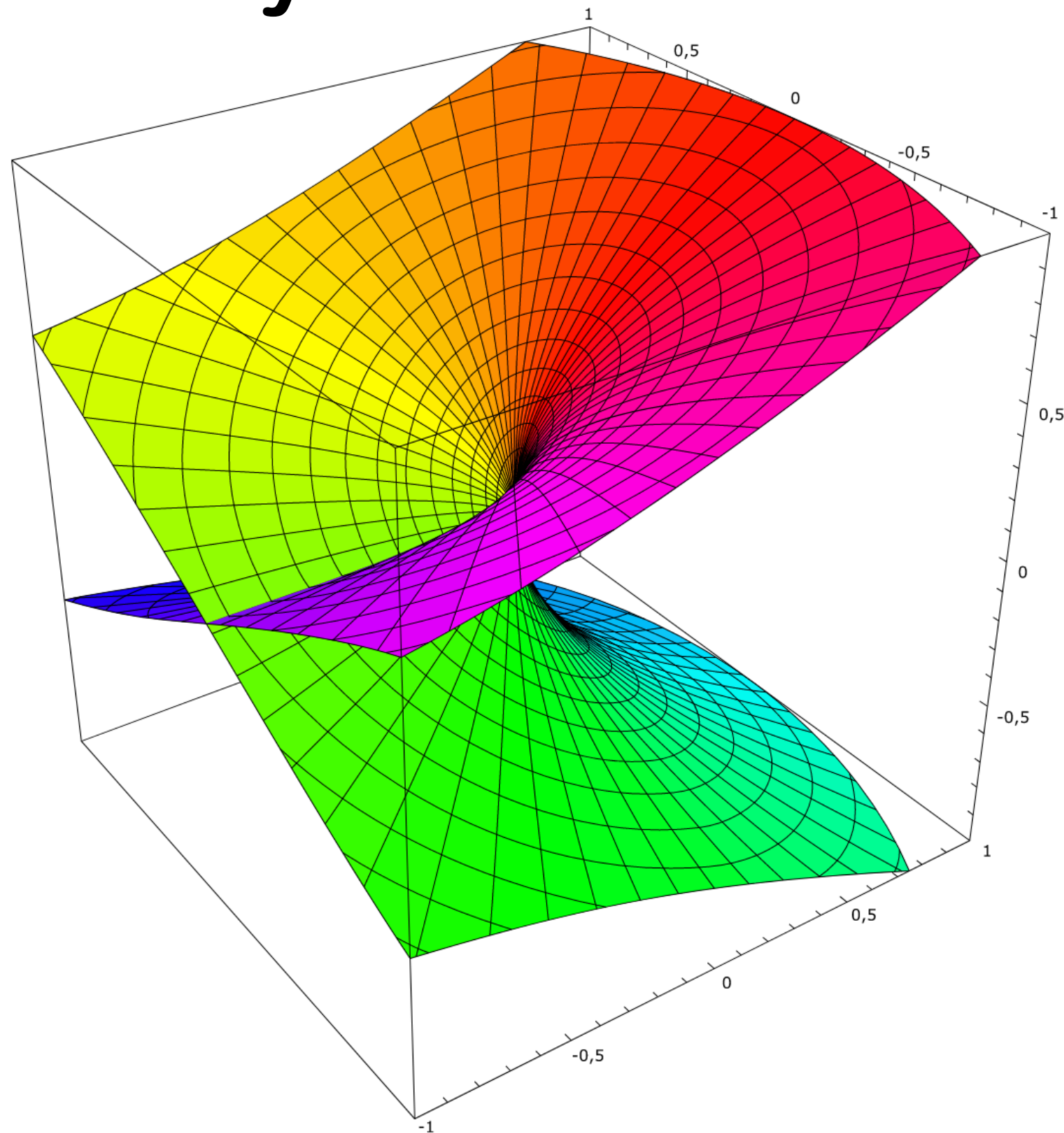
*Puisseux, 1850*

$$y^2 = x^3 + x$$

$$\Rightarrow y = x^{1/2} \left( 1 + x^2/2 - x^4/8 + \dots \right)$$

$\mapsto$  idea of *monodromy*, 200 years later.

# Monodromy



$$y = x^{3/2}$$

# New transcendental functions

“It is well known that the central problem of the whole of modern mathematics is the study of the **transcendental** functions defined by differential equations.”

*Klein, Lecture I, Evanston Colloquium, 1893.*



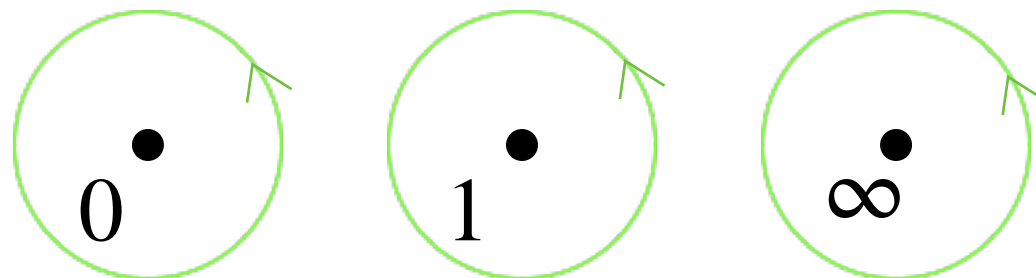
# Prototypical example

The hypergeometric differential equation

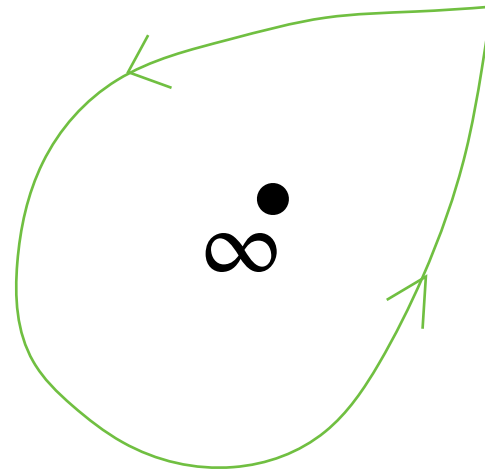
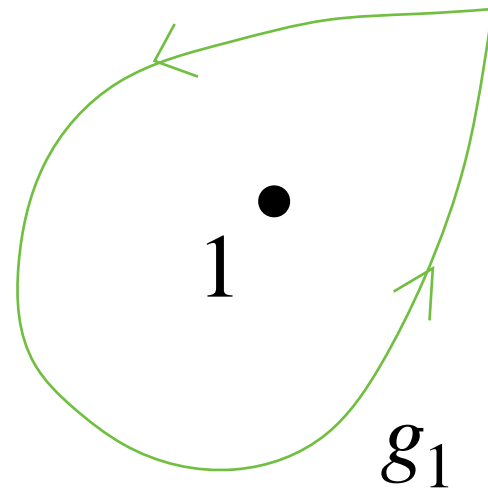
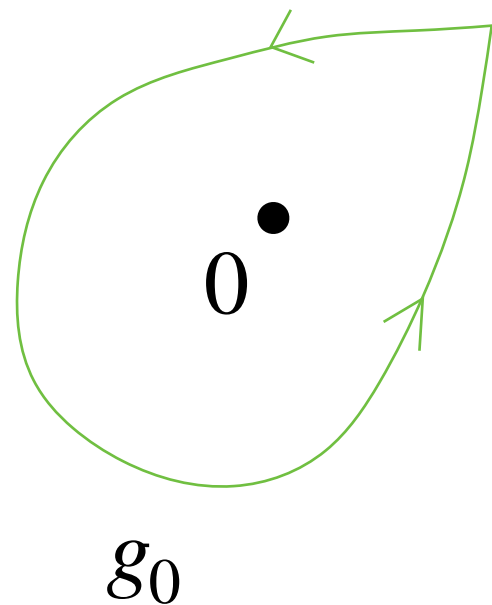
$$z(1 - z)w_{zz} + (c - (a + b + 1)z)w_z - abw = 0$$

has Fuchsian singularities (regular singularities) at  $0, 1, \infty$ .

The fundamental  $2 \times 2$  matrix of solutions  $Y(z)$  changes when analytically continued on a path around each singularity.



# Monodromy data



$$g_{\infty} = (g_0 \circ g_1)^{-1}$$

$g_0, g_1$  are  $2 \times 2$  matrices, which generate the **monodromy** group.

Data that remains invariant under simultaneous conjugation of such matrices is called **monodromy data**.

# Lazarus Fuchs



1833 – 1902



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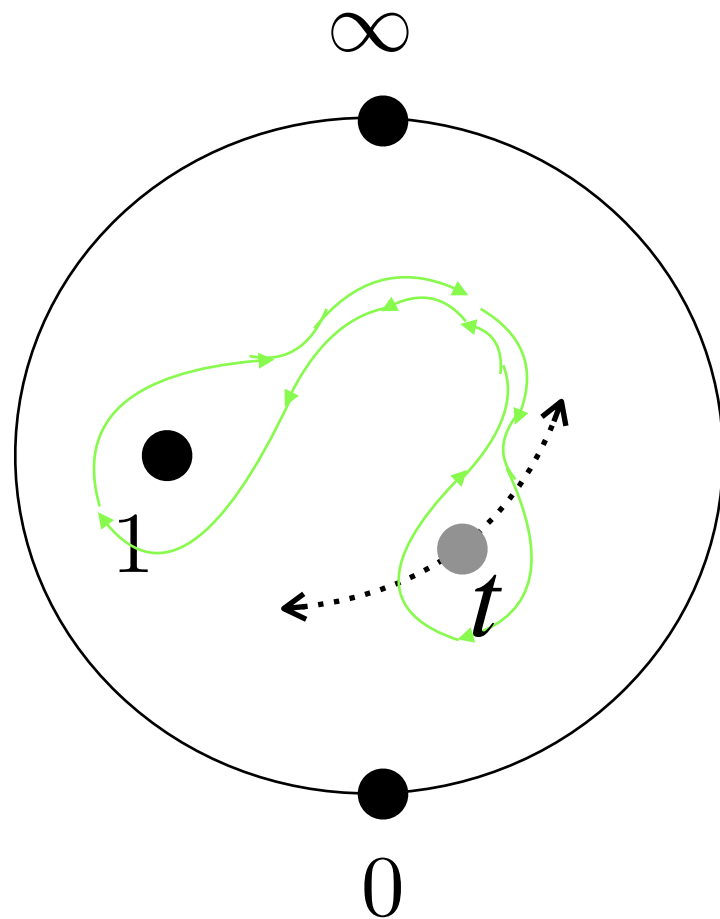
# Richard Fuchs



1873 – 1944



# Add another singularity



*R. Fuchs 1905*

$$\frac{dY}{dz} = \left( \frac{A_0}{z} + \frac{A_1}{z-1} + \frac{A_t}{z-t} \right) Y$$

Find the condition  
under which  
*monodromy* data of  
this system stays  
invariant under  
deformation of  $t$ .

→ *isomonodromy problem*

# Fuchs equation

$$\begin{aligned} w'' = & \frac{1}{2} \left( \frac{1}{w} + \frac{1}{w-1} + \frac{1}{w-t} \right) (w')^2 \\ & - \left( \frac{1}{t} + \frac{1}{t-1} + \frac{1}{w-t} \right) w' \\ & + \frac{w(w-1)(w-t)}{t^2(t-1)^2} \left( \alpha - \frac{\beta t}{w^2} \right. \\ & \quad \left. + \frac{\gamma(t-1)}{(w-1)^2} + \delta \frac{t(t-1)}{(w-t)^2} \right) \end{aligned}$$

# A limiting form

☞ Take

$$t \mapsto 1 + \epsilon t$$

$$\delta \mapsto \frac{\delta}{\epsilon^2}$$

$$\gamma \mapsto \frac{\gamma}{\epsilon} - \frac{\delta}{\epsilon^2}$$

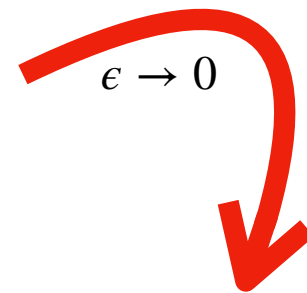
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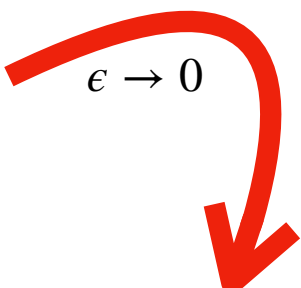
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$$\mathbf{P}_V : w'' = \left( \frac{1}{2w} + \frac{1}{w-1} \right) (w')^2 - \frac{w'}{t} \\ + \frac{(w-1)^2}{t^2} \left( \alpha w + \frac{\beta}{w} \right) \\ + \frac{\gamma w}{t} + \frac{\delta w(w+1)}{w-1}$$




# Successive limits

$$P_{IV} : \quad w'' = \frac{1}{2w}(w')^2 + \frac{3w^3}{2} + 4tw^2 + 2(t^2 - \alpha)w + \frac{\beta}{w}$$

$$P_{III} : \quad w'' = \frac{1}{w}(w')^2 - \frac{w'}{t} + \frac{1}{t}(\alpha w^2 + \beta) + \gamma w^3 + \frac{\delta}{w}$$

$$P_{II} : \quad w'' = 2w^3 + tw + \alpha$$

$$P_I : \quad w'' = 6w^2 + t$$

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- One way to describe them is through associated isomonodromy problems.

*Ablowitz & Segur 1977, Jimbo & Miwa 1981, Its & Novokshenov 1986, Kapaev 1988, Kitaev & Kapaev 1993, Deift & Zhou 1995, Fokas & Zhou 1992, Fokas et al 2006.*



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$$\begin{aligned} w(t) &= t^{1/2} u(z) \\ z &= \frac{4}{5} t^{5/4} \end{aligned} \quad \Rightarrow \quad u_{zz} = 6u^2 + 1 - \frac{u_z}{z} + \frac{4u}{25z^2}$$

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- So as  $z \rightarrow \infty$ , we find  $u \sim \wp(z - z_0; -2; 2E)$ , where

$$u_z^2 = 4u^3 + u + 2E$$

# Modulated elliptic functions



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- At these values, the elliptic function degenerates to a hyperbolic function and a further degeneracy reduces it to a rational function *Boutroux 1913, J. & Kruskal 1988-92*.

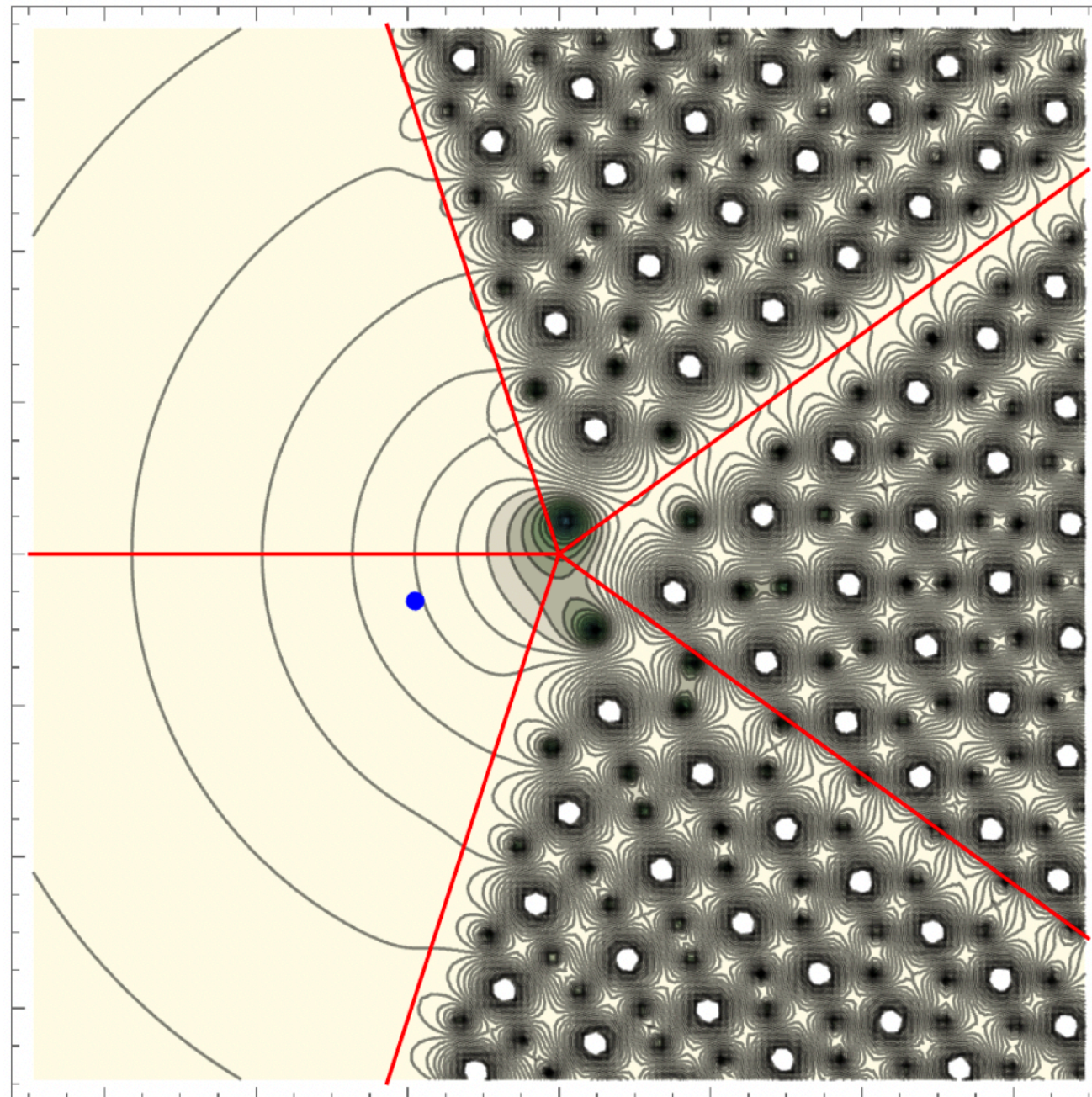
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- The hyperbolic behaviours occur along boundaries of quadrants in  $z$ , which are sectors of width  $2\pi/5$  in  $x$ .
- The algebraic behaviour occurs within two contiguous such sectors, and leads to *tronquée* solutions.



*Poles of a tronqué solution of PI in  $t$ -plane from  
arXiv:2204.09062 Figure 1 (b) by Alexander van Spaendonck  
and Marcel Vonk. (Figure is reflected from the original.)*

How are such functions related to  
*isomonodromy* problems?



**Monodromy**

# Isomonodromy problem for $P_I$

- $P_I$  is the compatibility condition for an associated 2x2 matrix linear system:

$$\frac{\partial Y}{\partial z} = A(z, t)Y \quad A(z) = A_4 z^4 + A_2 z^2 + A_1 z + \frac{A_{-1}}{z}$$

$$\frac{\partial Y}{\partial t} = B(z, t)Y$$

*Jimbo, Miwa 1981*

- This system has an irregular singular point at  $z = \infty$  and a regular singular point at  $z = 0$ .
- Monodromy now includes not only the information about how solutions change in the way described by Fuchs around 0, but also Stokes phenomena around  $\infty$ .

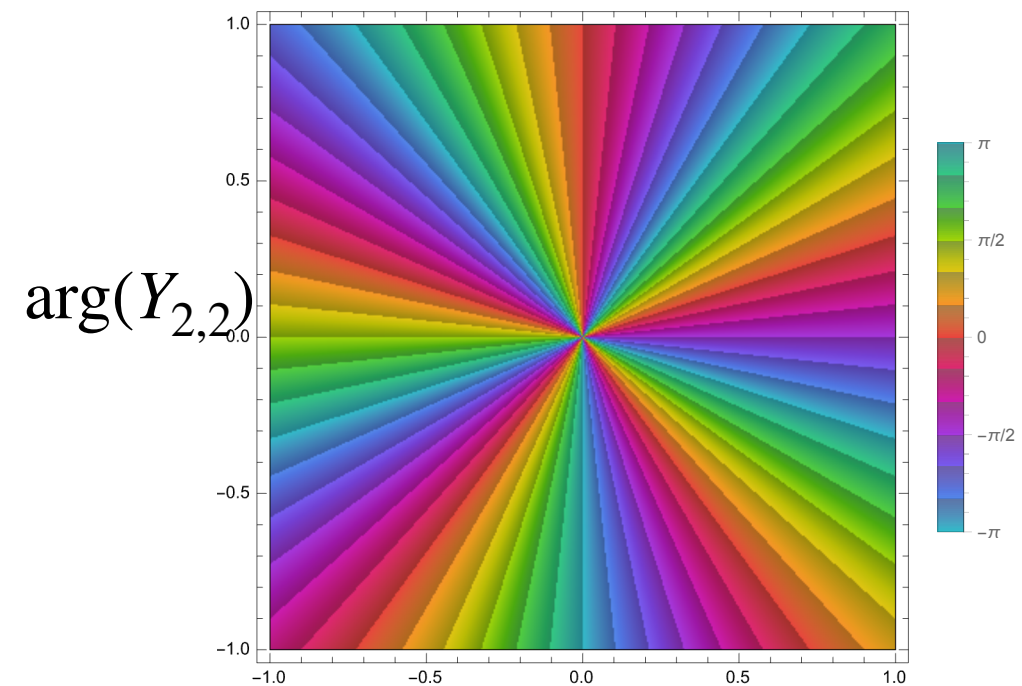
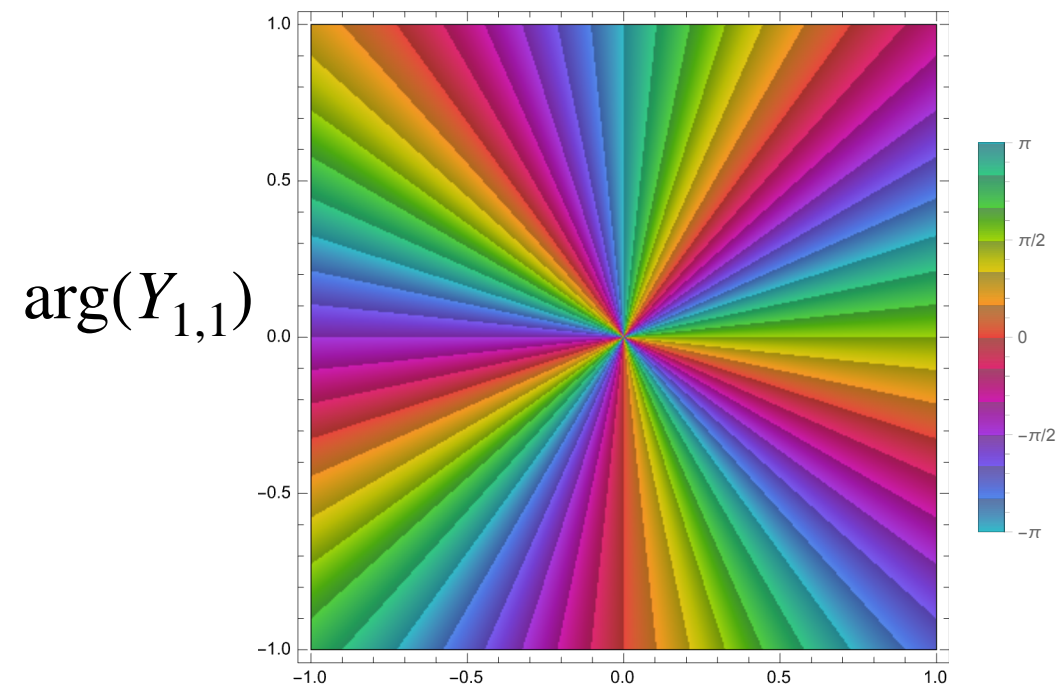
# Stokes phenomena

$$Y \sim (I + O(1/z)) \exp \left( \left( \frac{4}{5} z^5 + t z \right) \sigma_3 \right), z \rightarrow \infty$$



# Stokes phenomena

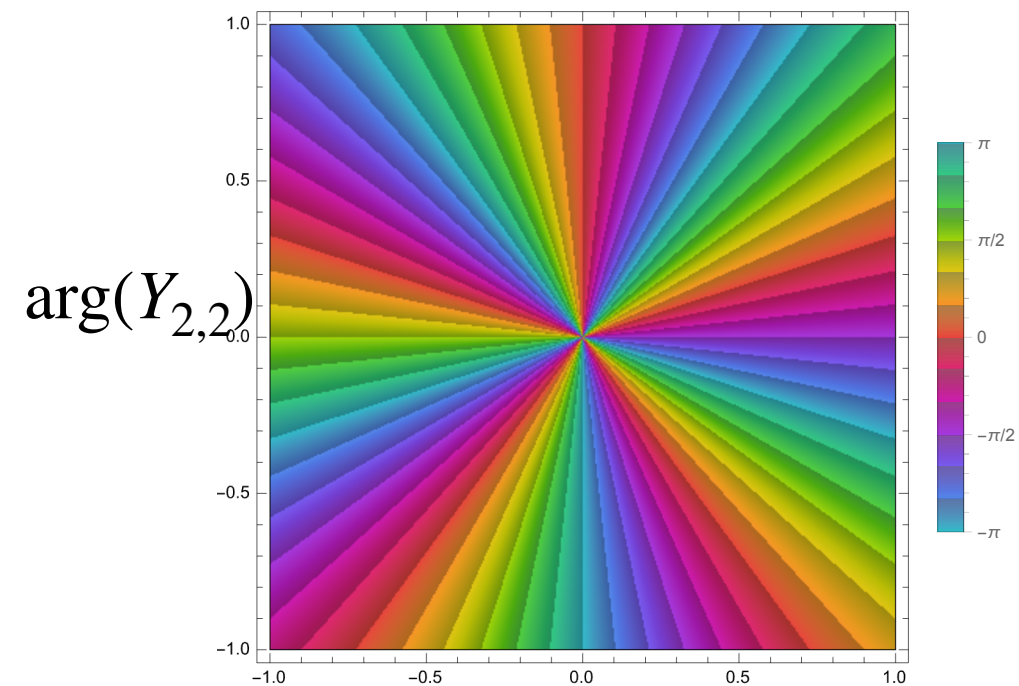
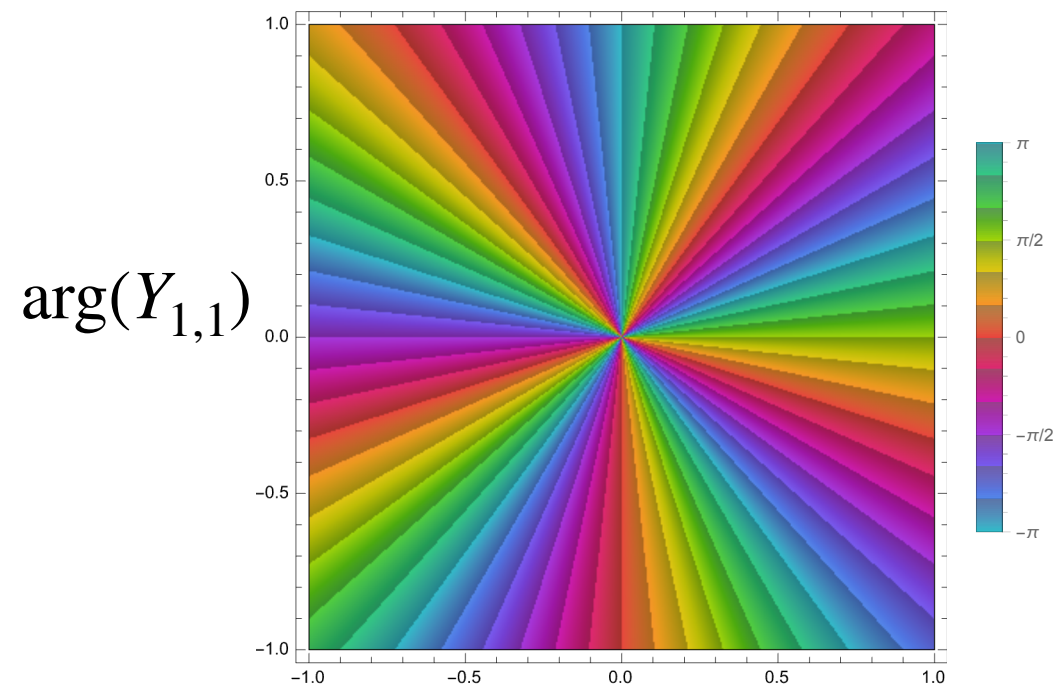
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Choose a solution  $Y_k$  in a sector  $\Omega_k$ . It must be related to the corresponding solution in a neighbouring sector by multiplication by Stokes matrices:

$$Y_{k+1} = Y_k S_k \quad S_{2l} = \begin{pmatrix} 1 & 0 \\ s_{2l} & 1 \end{pmatrix}, \quad S_{2l+1} = \begin{pmatrix} 1 & s_{2l+1} \\ 0 & 1 \end{pmatrix}$$

# Connections

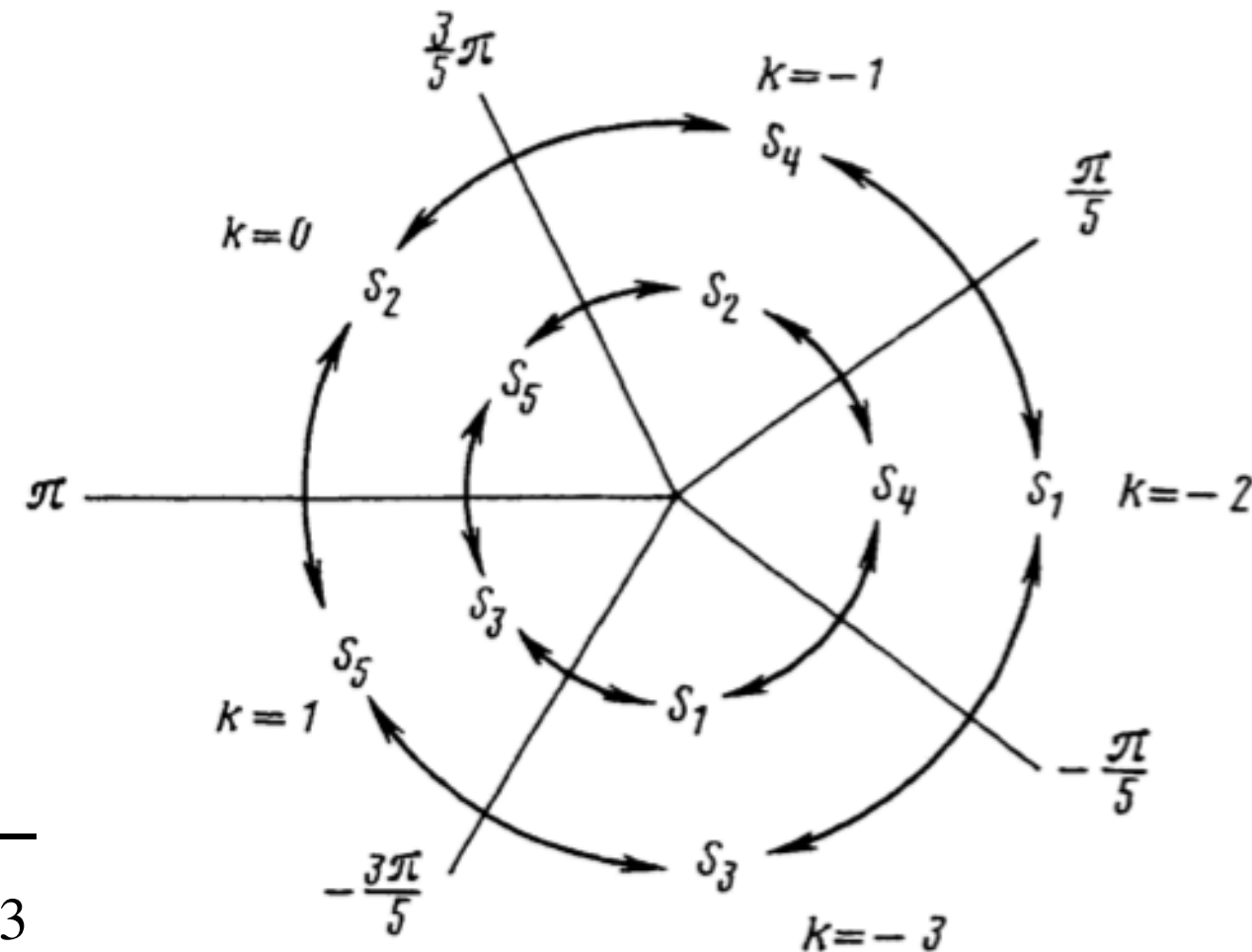
- Connection to the solutions defined around  $z = 0$ .
- Symmetry condition (related to  $P_I$ ).
- These lead to interrelationships between parameters  $\{s_k\}$ , yielding

$$s_{k+5} = s_k$$

$$s_1 = \frac{i - s_3}{1 + s_2 s_3}$$

$$s_4 = \frac{i - s_2}{1 + s_2 s_3}$$

$$s_5 = i(1 + s_2 s_3)$$



Kapaev, 1988

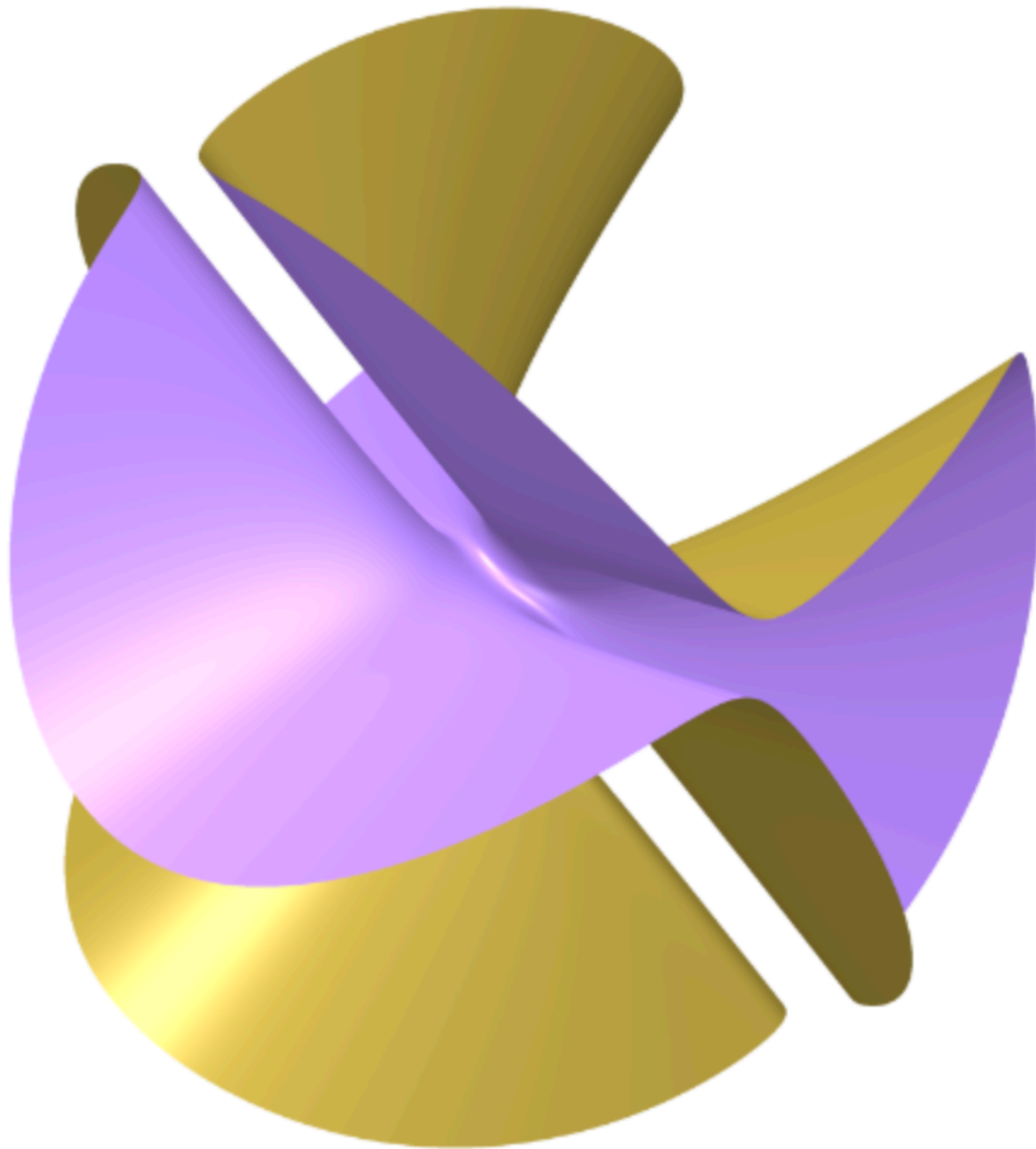
Kapev & Kitaev, 1993

# Cubic surfaces

The relations boil down to

$$s_1 s_2 s_3 + s_1 + s_3 = i$$

That is, a cubic surface.

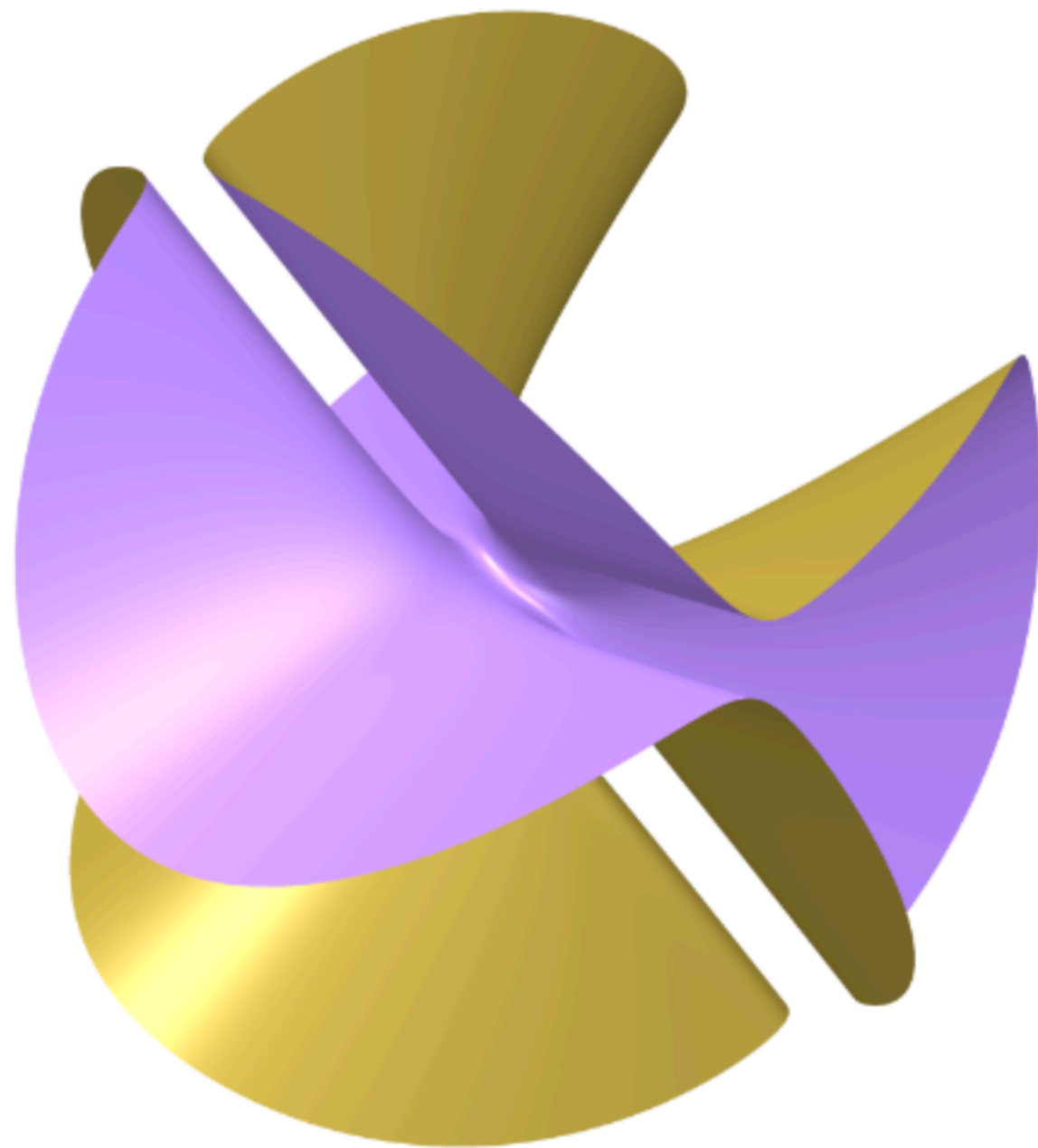


The cubic surface of  $P_1$  after scaling



$s_1 = ix, s_2 = -iy, s_3 = iz.$

# Cubic surfaces



The cubic surface of  $P_I$  after scaling



$s_1 = ix, s_2 = -iy, s_3 = iz.$

The relations boil down to

$$s_1 s_2 s_3 + s_1 + s_3 = i$$

That is, a cubic surface.

Similar cubic surfaces arise for the remaining Painlevé Equations, e.g., for  $P_{IV}$

$$s_1 s_2 s_3 + s_1^2 + as_1 - bs_2 + cs_3 + d = 0$$

where  $a, b, c, d$  are related to the two parameters of  $P_{IV}$ .

# Cubic surfaces

Cubic surfaces are celebrated in algebraic geometry, and lines on them play an important role.

The cubic surface for  $P_I$  contains 5 (affine) lines.

$$L_1 : \{s_1 = 0, s_3 = i\}$$

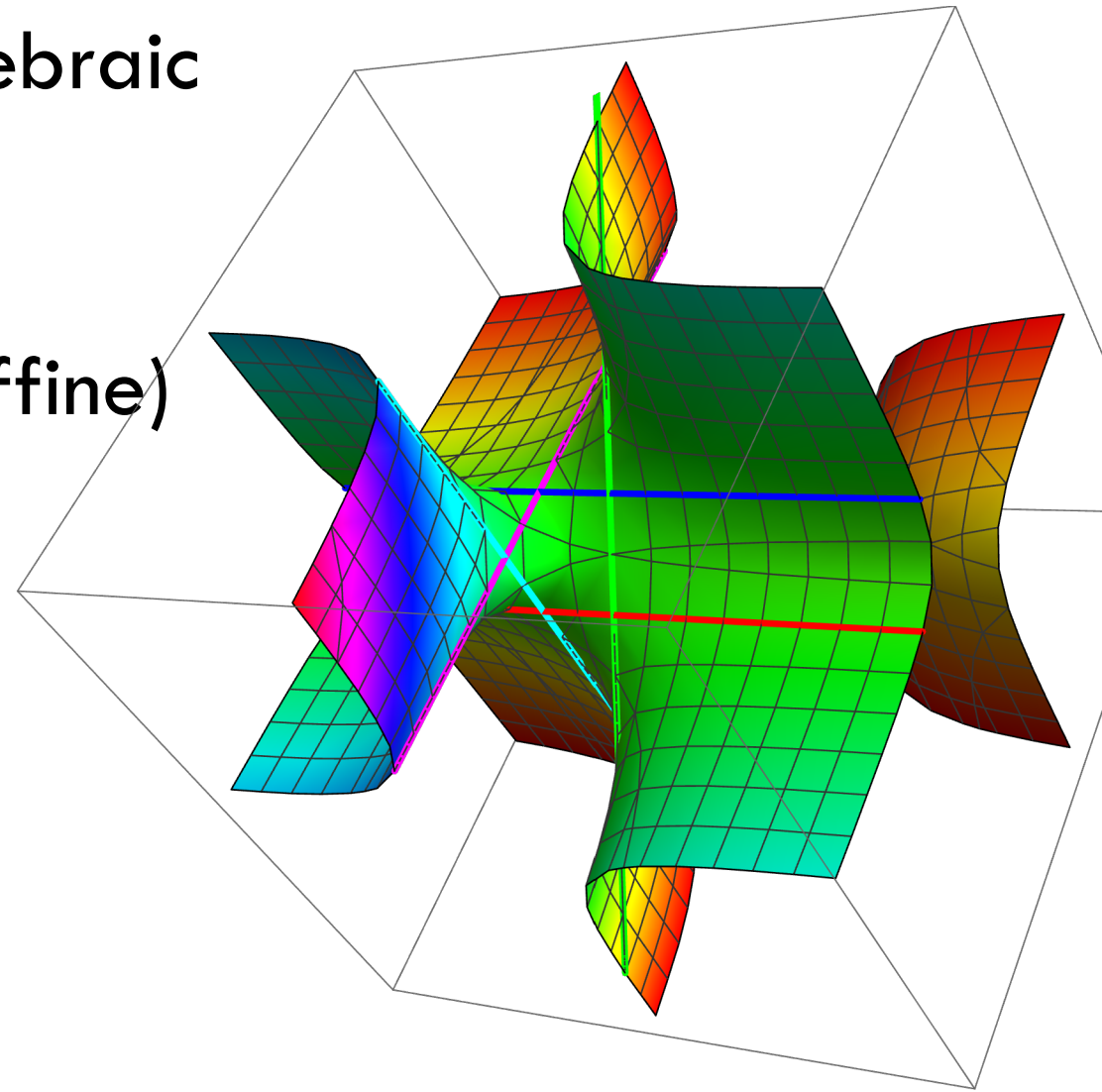
$$L_2 : \{s_1 = i, s_3 = 0\}$$

$$L_3 : \{s_2 = 0, s_1 + s_3 = i\}$$

$$L_4 : \{s_2 = i, s_3 = i\}$$

$$L_5 : \{s_1 = i, s_2 = i\}$$

Each line  $L_j$  is crucially tied to a famous one-parameter asymptotic behaviour admitted by  $P_I$ .

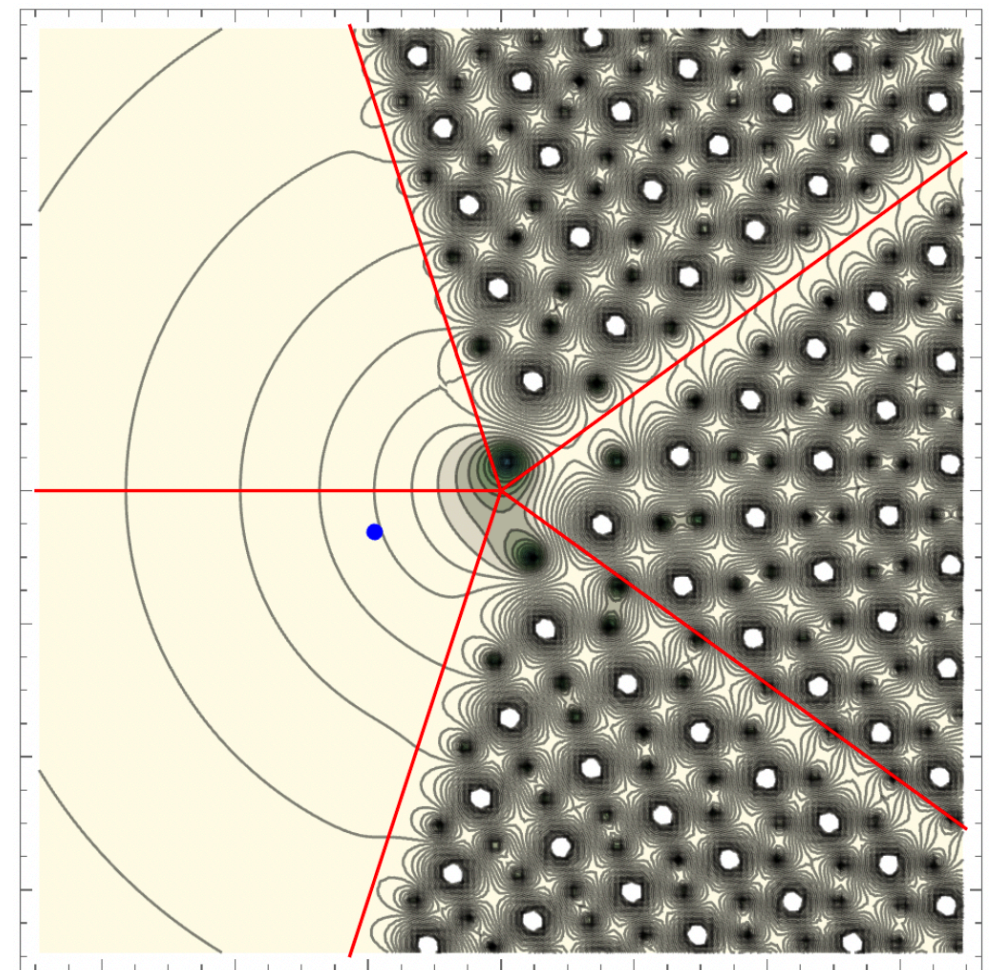




# Tronquée solutions

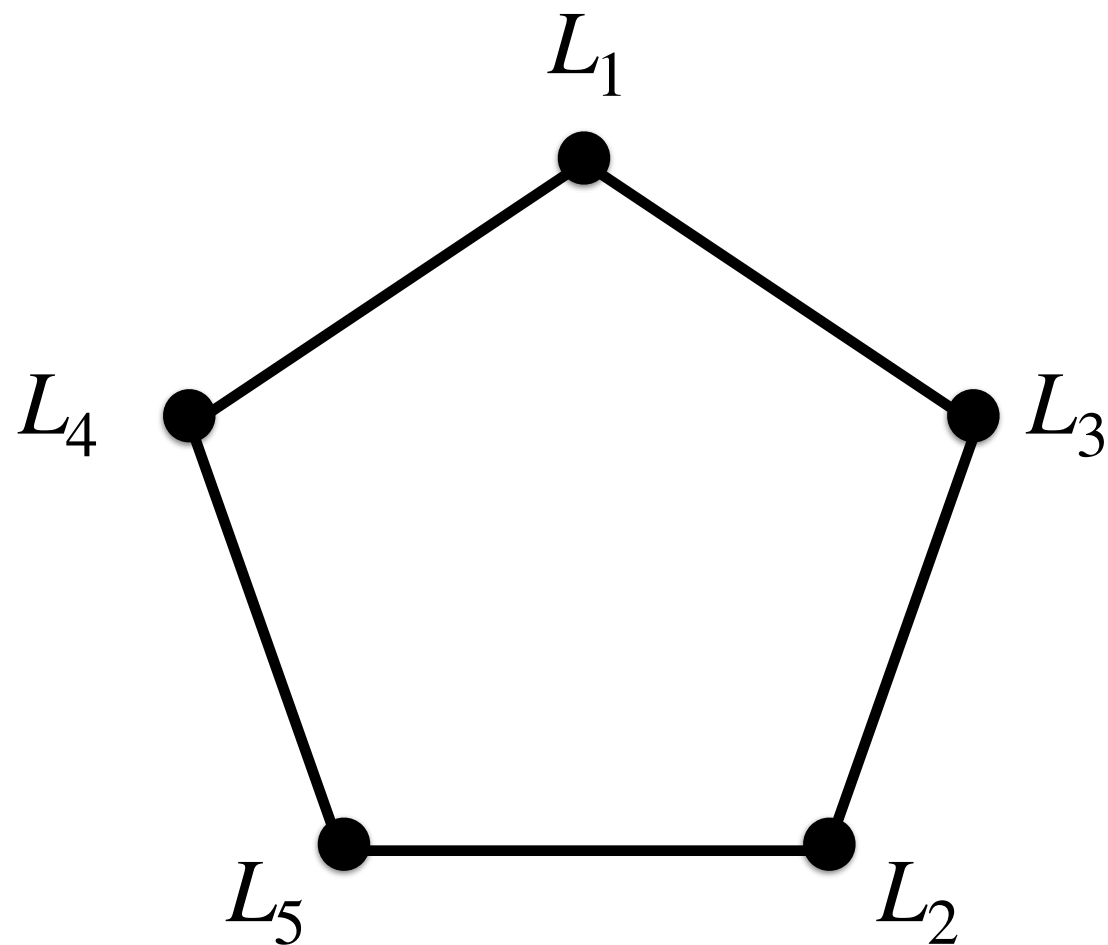
$$w(t) \sim \left( \frac{-t}{6} \right)^{1/2} \sum_{j=0}^{\infty} \frac{a_j}{t^{5j/2}}$$

$$|t| \rightarrow \infty, 3\pi/5 < \arg(t) < 7\pi/5$$



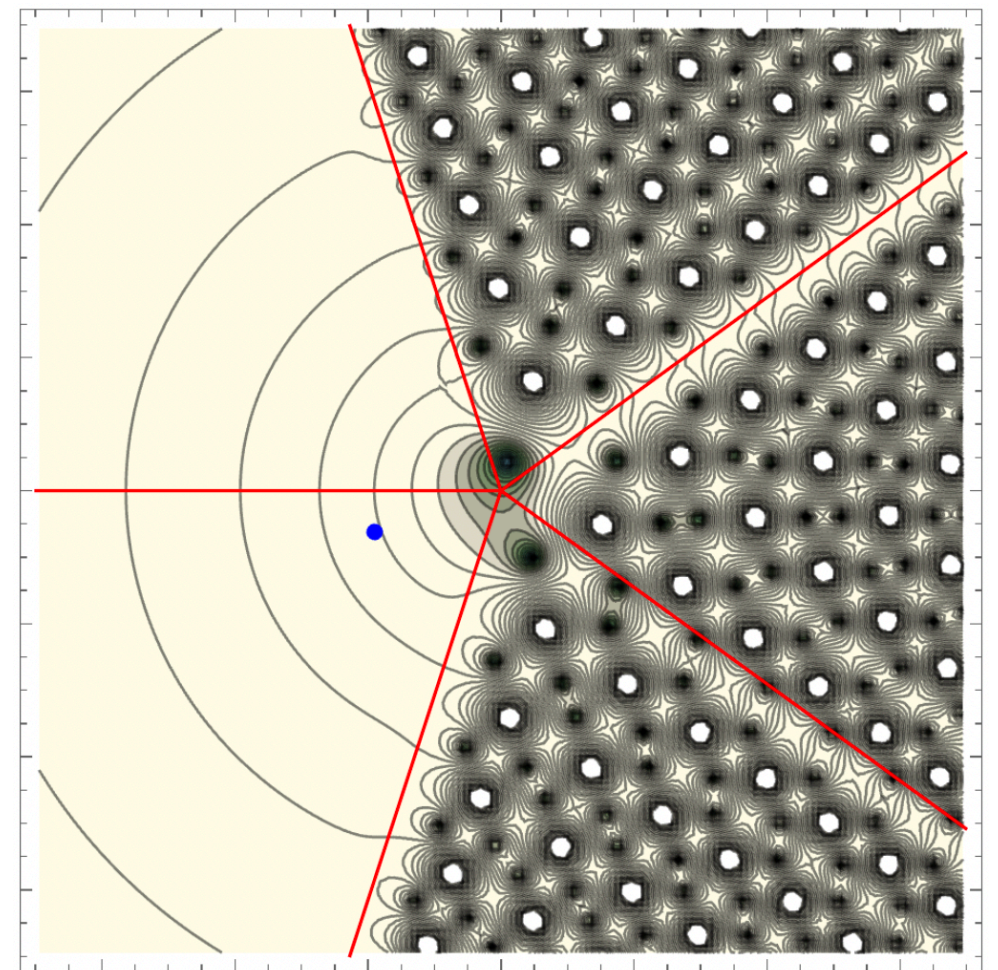
Poles of a tronqué solution of PI in  $t$ -plane from arXiv:2204.09062 Figure 1 (b) by Alexander van Spaendonck and Marcel Vonk. (Figure is reflected.)

# Tronquée solutions



$$w(t) \sim \left( \frac{-t}{6} \right)^{1/2} \sum_{j=0}^{\infty} \frac{a_j}{t^{5j/2}}$$

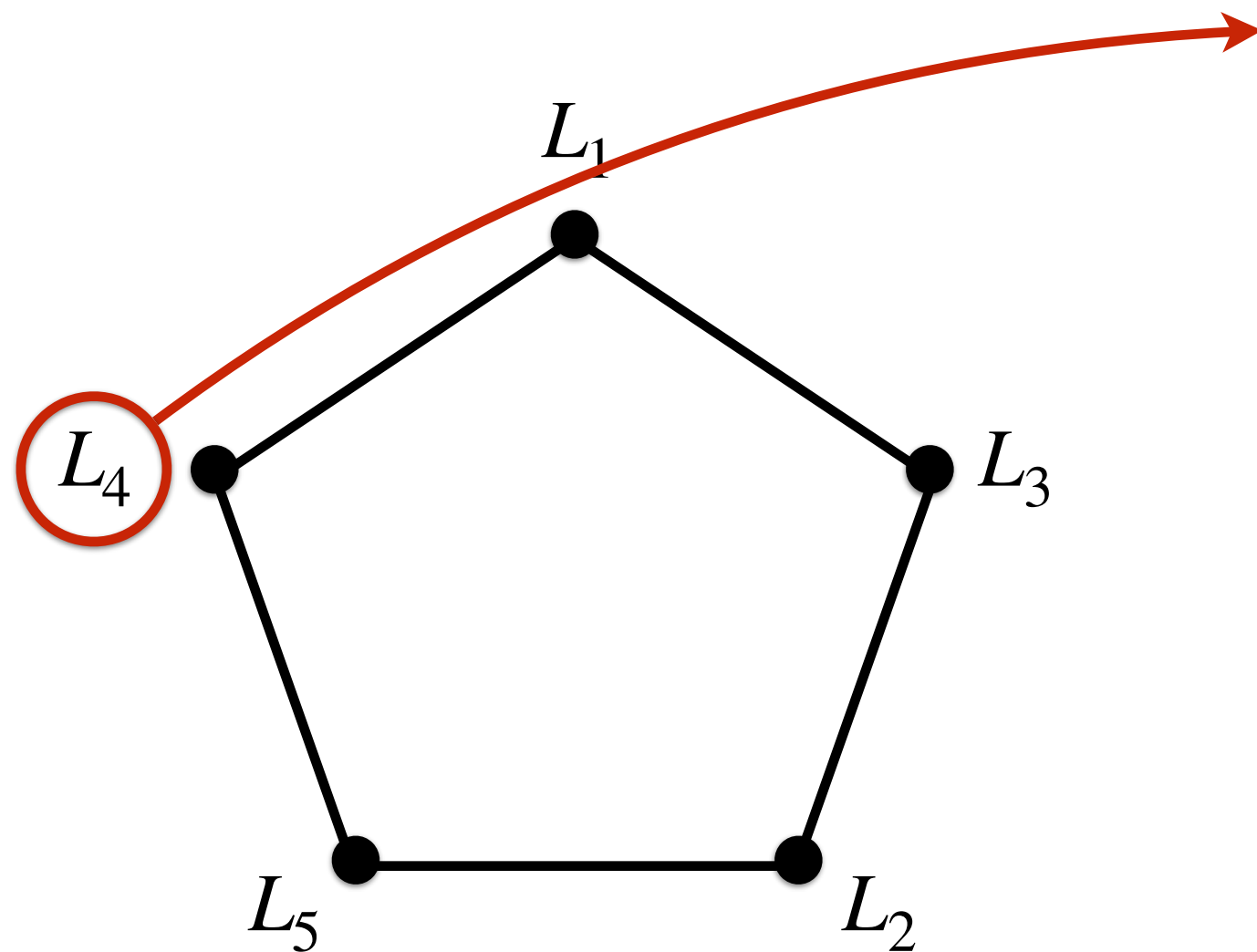
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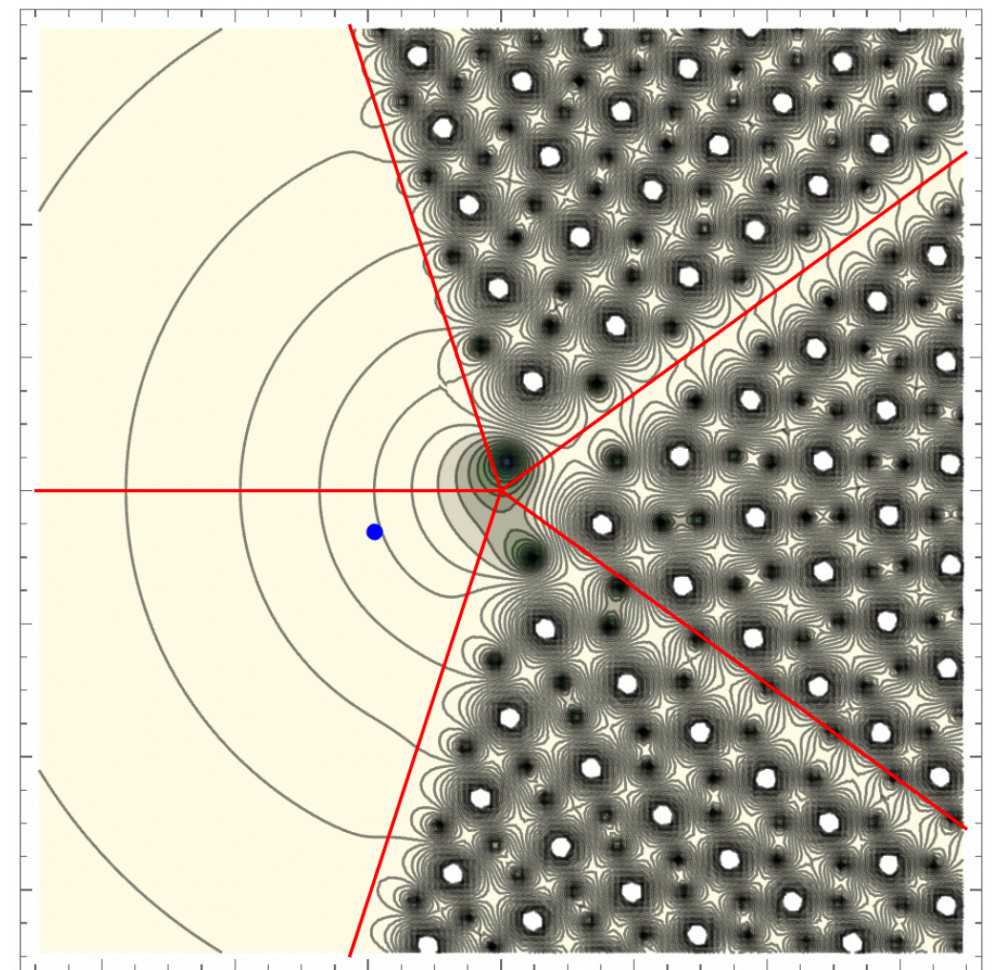


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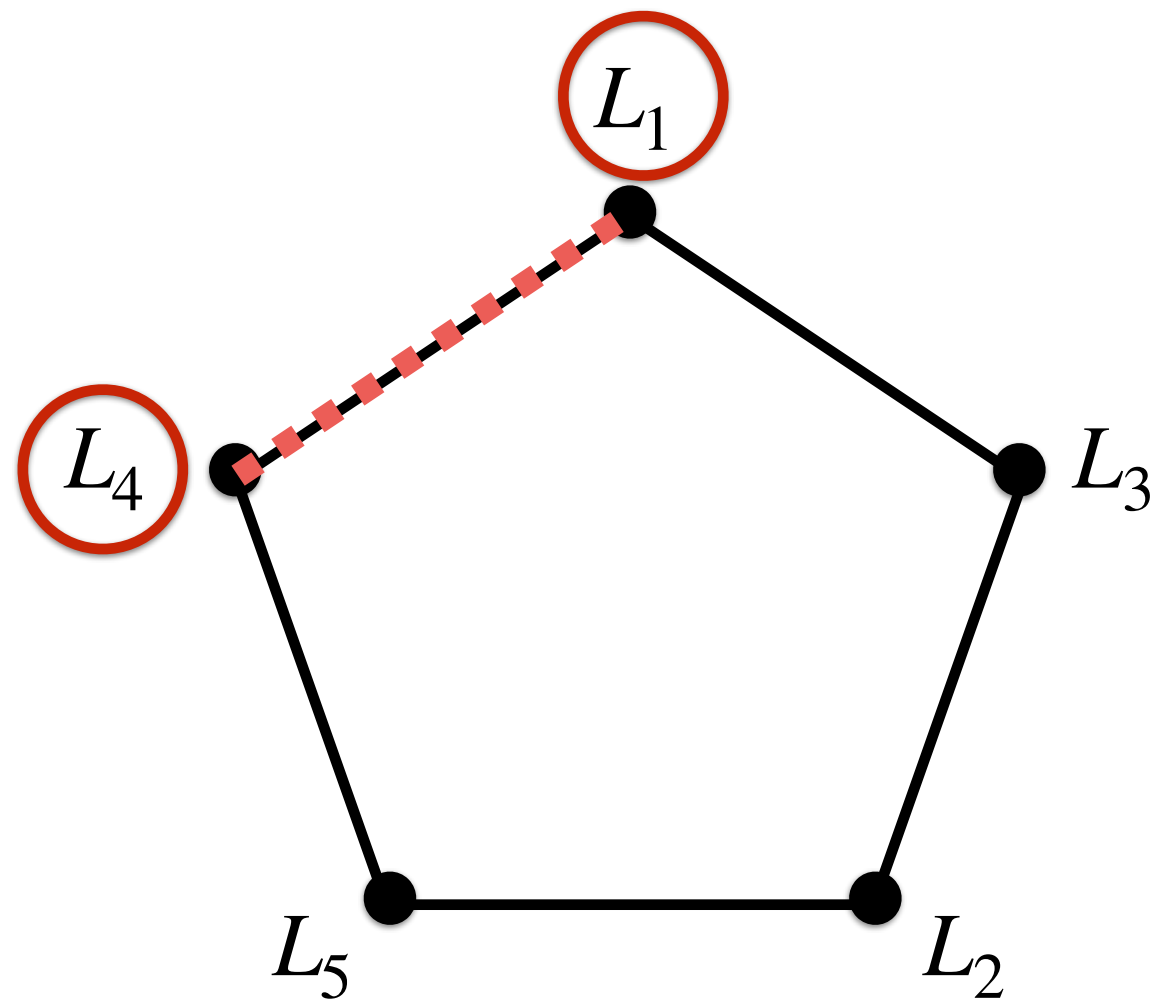
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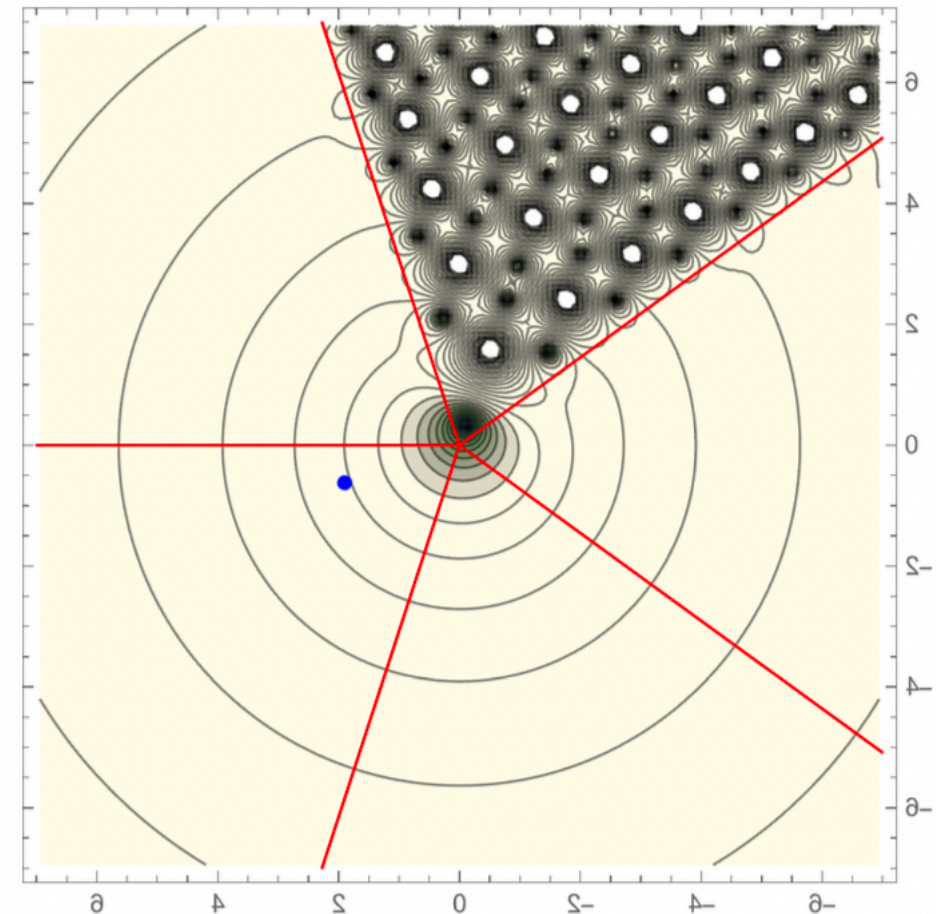


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# Tritronquée solutions



$$L_1 \cap L_4 : \{s_1 = 0, s_2 = i, s_3 = i\}$$



Poles of a tritronquée solution of PI in  $t$ -plane from arXiv:2204.09062 Figure 1(a) by Alexander van Spaendonck and Marcel Vonk. (Figure is reflected.)

# Symmetric solutions

The monodromy surface

$$s_1 s_2 s_3 + s_1 + s_3 = i$$

contains points  $(ip, ip, ip)$ , where

$$p^3 - 2p + 1 = 0$$

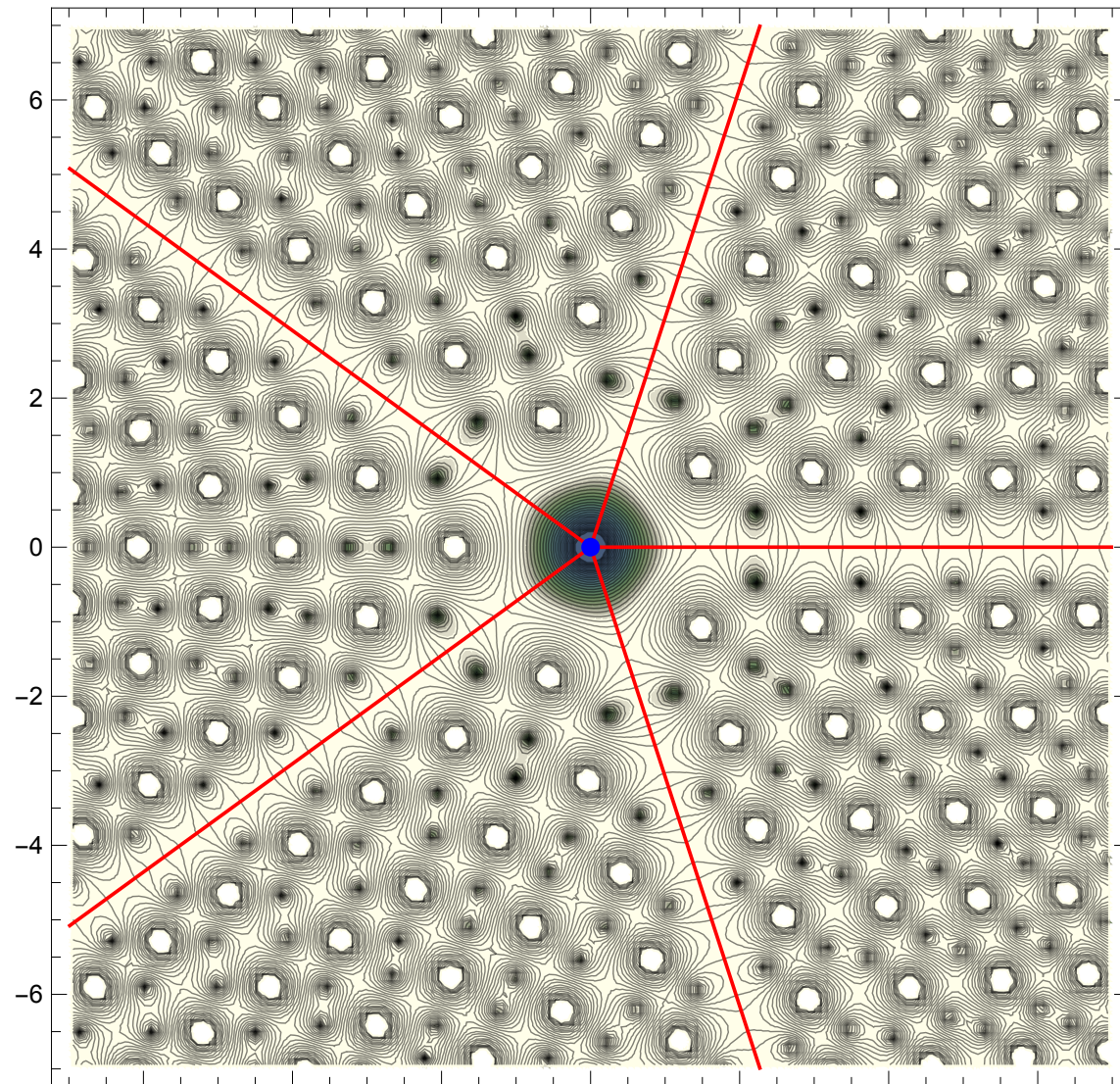
$$\Leftrightarrow (p - 1)(p^2 + p + 1) = 0$$

Two of these points corresponds to **symmetric** solutions of  $P_I$  ( $p = 1$  is *tritronquée*).

*Kitaev, 1995*



# Symmetric solutions



Poles of a symmetric solution of  $P_I$  with double zero at  $t=0$  using code supplied by Marcel Vonk.

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# What about discrete equations?



Sydney Harbour Bridge. Approaches from the Air.

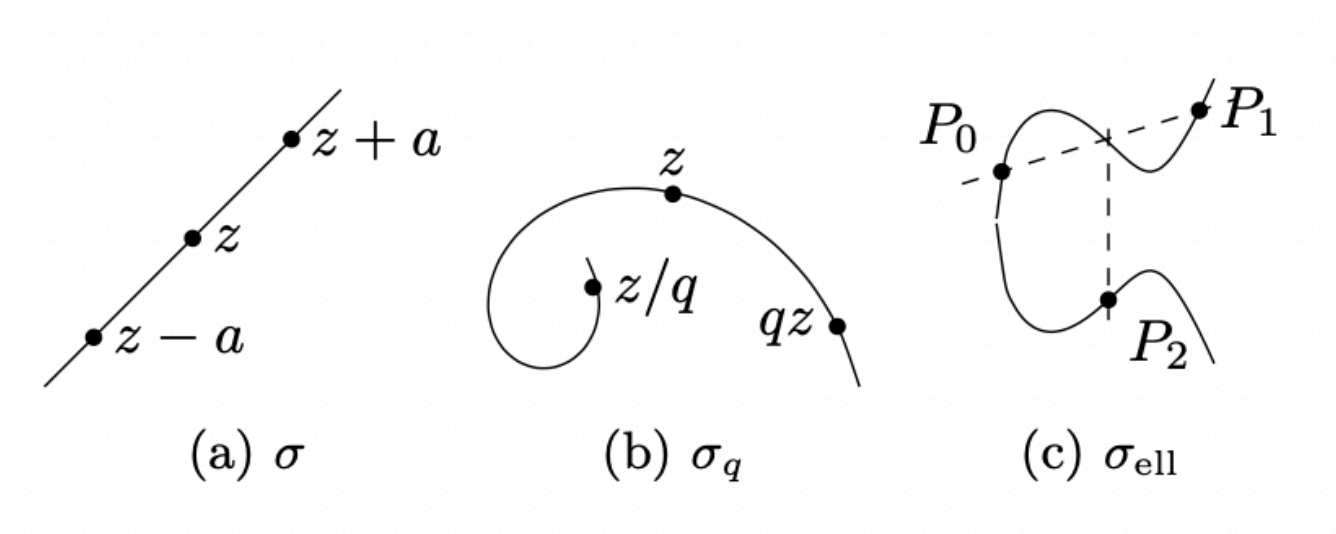
[records.nsw.gov.au](http://records.nsw.gov.au)

# Difference equations

$$F(\sigma^k(w(z)), \dots, \sigma(w(z)), w(z), z) = 0$$

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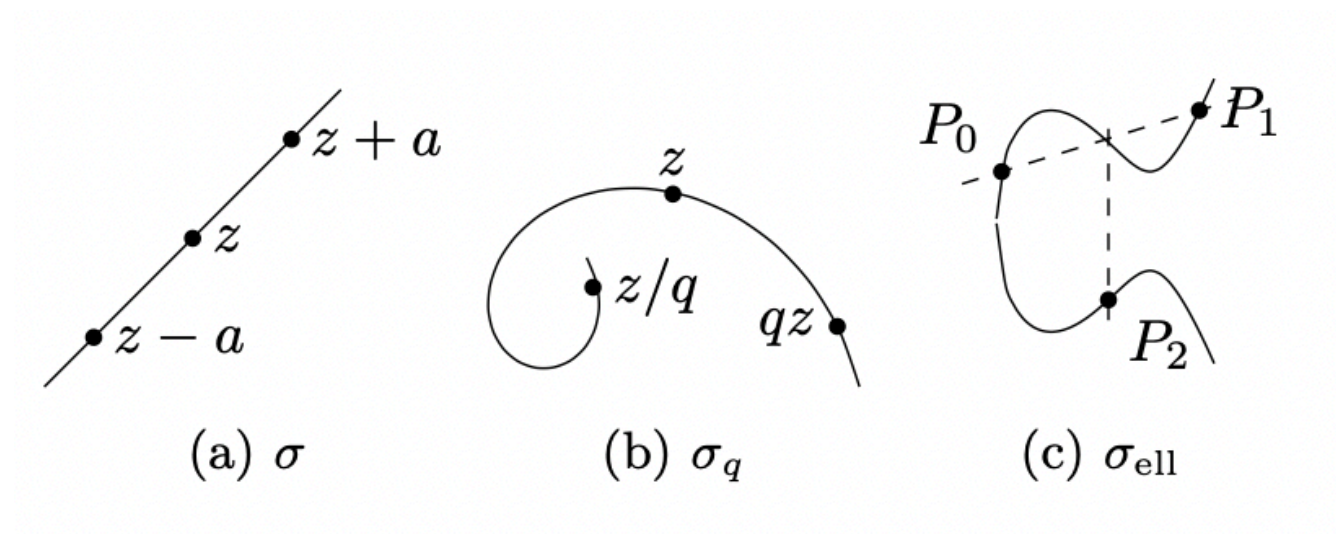


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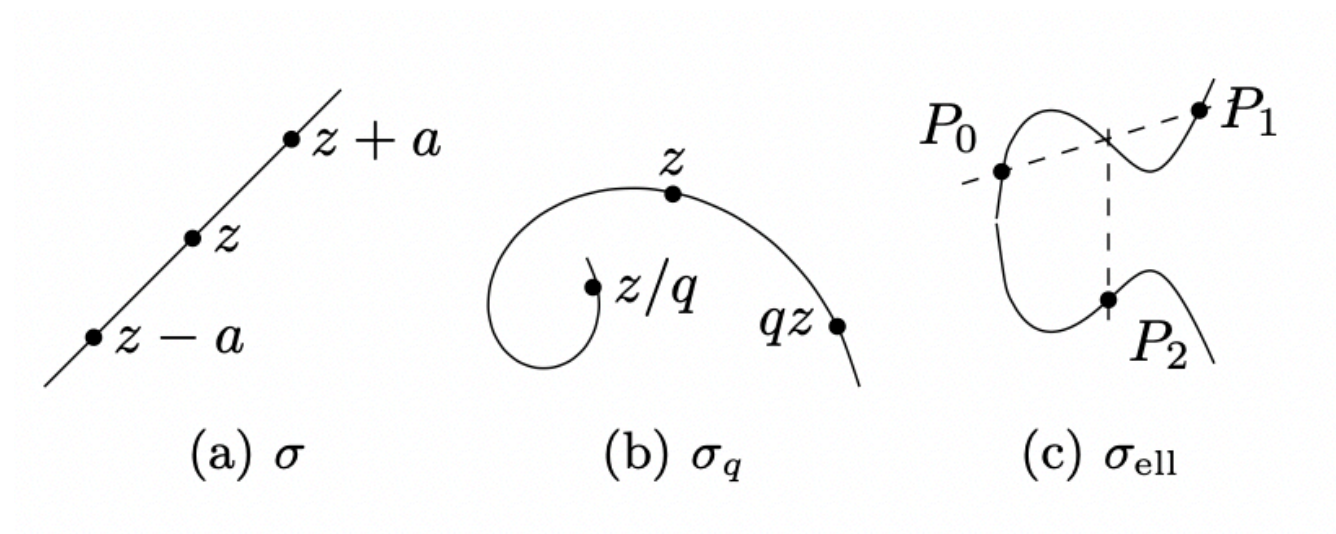


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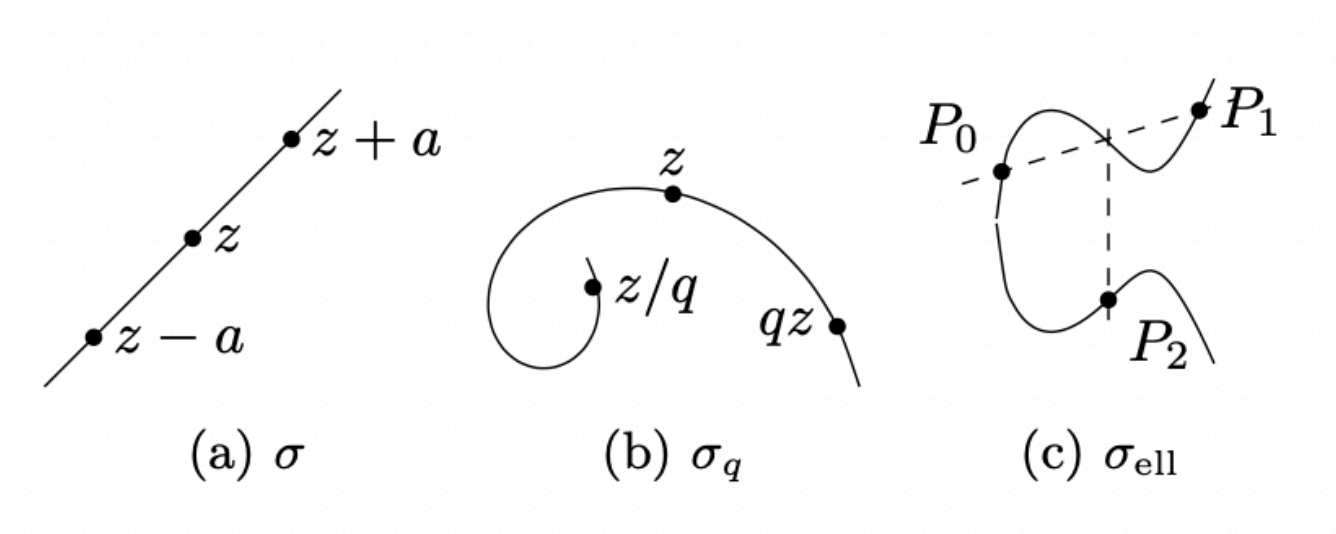


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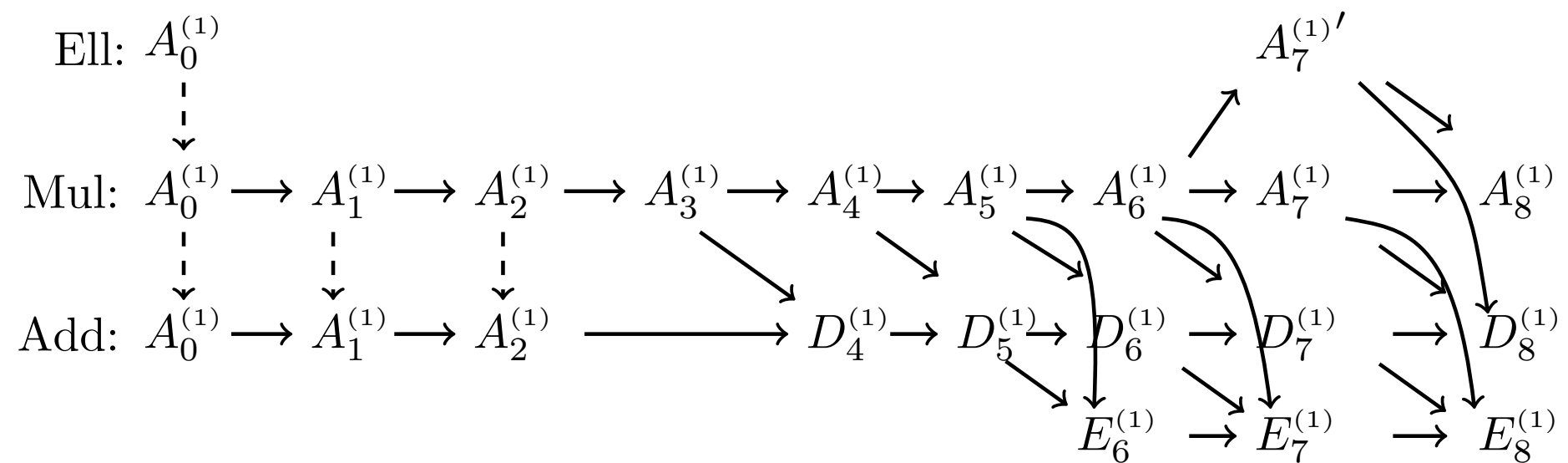
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Related to Jacobi's theta function

# Sakai's scheme

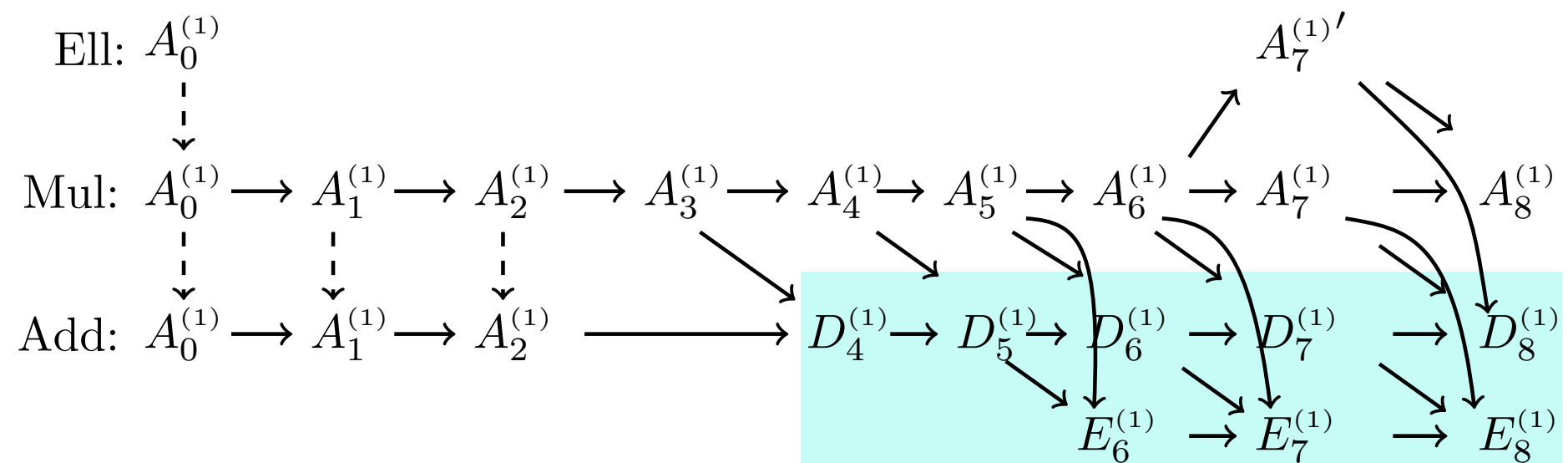
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Sakai 2001  
Rains 2016

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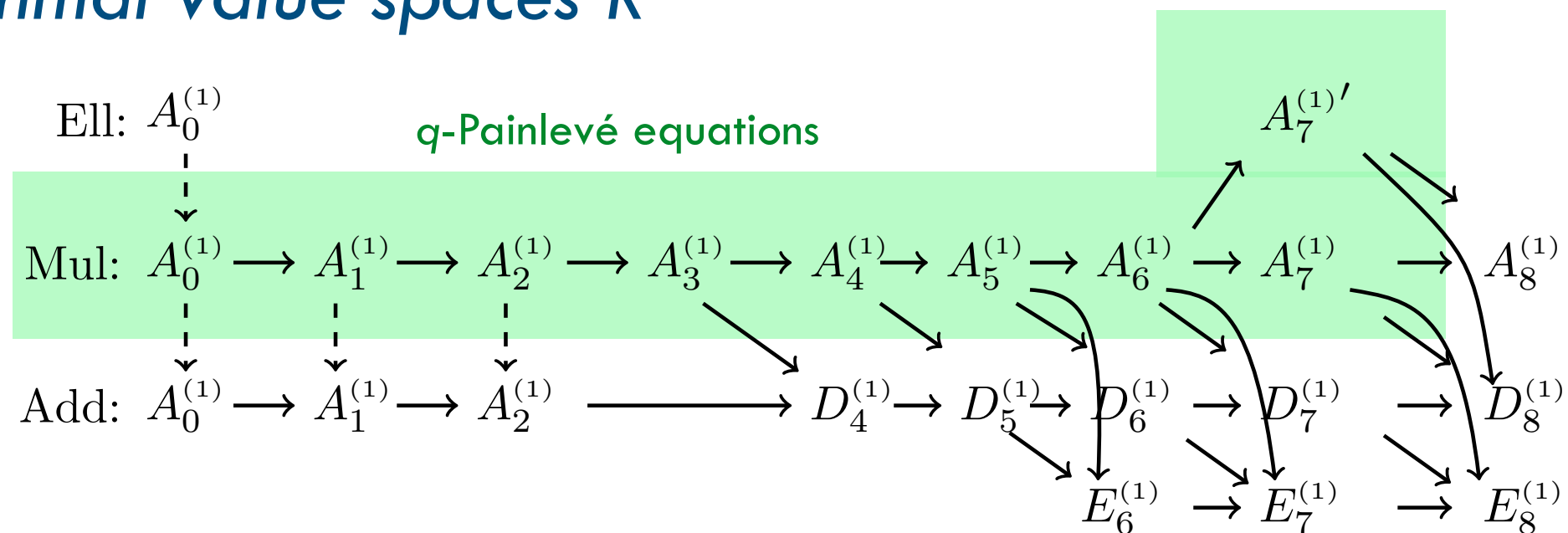


The Painlevé equations Okamoto 1979

Sakai 2001  
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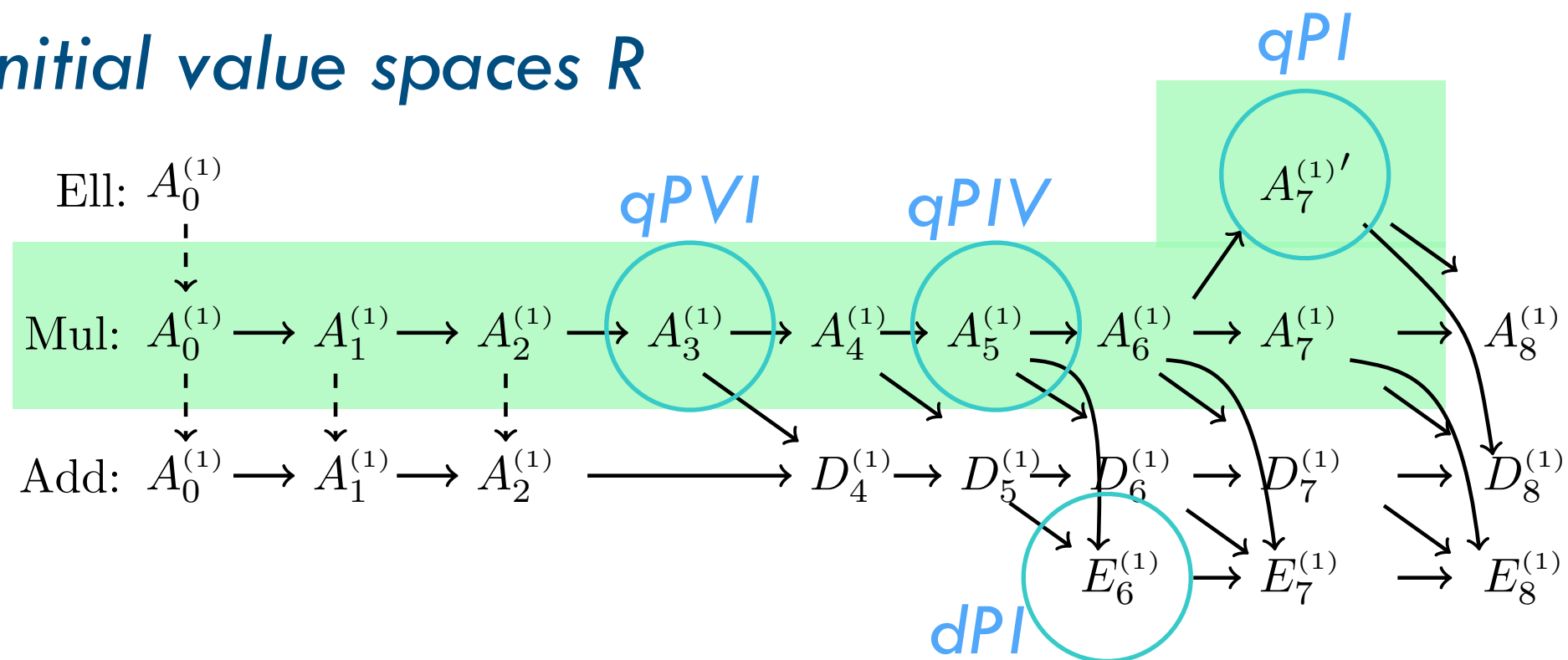
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dP<sub>i</sub>

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An additive discrete equation arising from the differential equation P<sub>IV</sub>

$$w_n'' = \frac{1}{2w_n}(w_n')^2 + \frac{3w_n^3}{2} + 4tw_n^2 + 2(t^2 - \alpha_n)w_n - \frac{\gamma_n^2}{2w_n}$$

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Bäcklund transformations of P<sub>IV</sub>

$$\alpha_n = -\frac{n}{2} + c_0 + c_1(-1)^n, \quad \gamma_n = n - 2c_0 + \frac{2c_1}{3}(-1)^n$$

$$2w_n w_{n+1} = -w_n' - w_n^2 - 2tw_n + \gamma_n$$

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Adding these  $\Rightarrow$  the first discrete Painlevé equation or dP<sub>I</sub>

$$w_n(w_{n+1} + w_n + w_{n-1}) = \gamma_n - 2tw_n$$

The case  $c_0 = 0 = c_1$  is called the *string equation*.

# dP<sub>I</sub> : Asymptotic Analysis I

$$w_n = n^{1/2} u_n$$

$$\Rightarrow u_n(u_{n+1} + u_n + u_{n-1}) = 1 + \mathcal{O}(n^{-1/2}), \quad n \rightarrow \infty$$

$K = (u_n u_{n-1} - 1)(u_{n-1} + u_n)$  is invariant to leading-order.

$$u_n \sim \frac{(3K + 6y_n)}{(6y_n - 2)}$$

gives  $y_n = \wp(n - n_0; 1/3; -2/(27) + K^2/4)$

What is the asymptotic behaviour of this solution as  $n \rightarrow -\infty$ ?

# dP<sub>I</sub> : Asymptotic Analysis II

There exist other behaviours

$$u_{n\pm 1} \sim u_n$$
$$\Rightarrow u_n = \pm \sqrt{\frac{1}{3}} + \mathcal{O}(n^{-1/2}), \quad n \rightarrow \infty$$

This expansion is divergent, hiding a free parameter  
– analogous to tronquée solutions

Late terms and Stokes phenomena were studied in  
J. & Lustri, 2015.

But, no one knows how solutions connect across Stokes sectors.

# q-PI: Asymptotic analysis

$$\overline{w} \underline{w} = \frac{w - t}{w^2}, \quad \overline{w} = w(qt), \underline{w} = w(t/q), \quad 0 < |q| < 1$$

There exists a vanishing solution,  $w(t)$  s.t.

$$w(t) \sim \sum_{n=1}^{\infty} b_n t^n, \text{ as } t \rightarrow 0$$

with late terms given by

$$b_{3p+1} = \mathcal{O}(|q|^{-3p(p-1)/2} \prod_{k=0}^{p-1} (1 + q^{3k})^2). \quad J. 2014$$

$$b_{3p+2} = 0, \quad b_{3p+3} = 0, \quad \forall p \geq 0$$

A factorially divergent series, hiding a free parameter.

There also exists a periodic behaviour, with period 3.



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- Geometric information on these surfaces give connections for “*tronquée*”-like solutions.

# $qP_{\text{IV}}$

$$qP(A_5^{(1)})$$

$$qP_{\text{IV}} : \begin{cases} \frac{\bar{f}_0}{a_0 a_1 f_1} = \frac{1 + a_2 f_2 (1 + a_0 f_0)}{1 + a_0 f_0 (1 + a_1 f_1)}, \\ \frac{\bar{f}_1}{a_1 a_2 f_2} = \frac{1 + a_0 f_0 (1 + a_1 f_1)}{1 + a_1 f_1 (1 + a_2 f_2)}, \\ \frac{\bar{f}_2}{a_2 a_0 f_0} = \frac{1 + a_1 f_1 (1 + a_2 f_2)}{1 + a_2 f_2 (1 + a_0 f_0)}, \end{cases}$$

$$\bar{f}_j = f_j(qt)$$

$$f_0 f_1 f_2 = t^2, \quad a_0 a_1 a_2 = q$$

*Kajiwara, Noumi, Yamada 2001*

# qP<sub>IV</sub>-Linear problem

- The corresponding linear problem for qP<sub>IV</sub> is

$$Y(qz, t) = A(z, t) Y(z, t)$$

$$A(z, t) = A_0(t) + A_1(t) z + A_2(t) z^2 + A_3(t) z^3$$

$A_0$  has eigenvalues  $\pm i$

$$A_3 = q a_0^2 a_2 i \begin{pmatrix} t & 0 \\ 0 & t^{-1} \end{pmatrix}$$

$$|A(z)| = (1 - a_0 z)(1 + a_0 z)(1 - a_0 a_2 z)(1 + a_0 a_2 z)(1 - q z)(1 + q z)$$

$$A(-z) = -\sigma_3 A(z) \sigma_3$$

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NJ and N. Nakazono, *PRSA* (2016)  
arXiv:1503.04515

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# qP<sub>IV</sub>-Monodromy surface

$$\begin{aligned} & \theta_q(+a_0, +a_1, +a_2) (\theta_q(\lambda_0)p_1p_2p_3 - \theta_q(-\lambda_0)) \\ & - \theta_q(-a_0, +a_1, -a_2) (\theta_q(\lambda_0)p_1 - \theta_q(-\lambda_0)p_2p_3) \\ & + \theta_q(+a_0, -a_1, -a_2) (\theta_q(\lambda_0)p_2 - \theta_q(-\lambda_0)p_1p_3) \\ & - \theta_q(-a_0, -a_1, +a_2) (\theta_q(\lambda_0)p_3 - \theta_q(-\lambda_0)p_1p_2) = 0 \end{aligned}$$

A cubic surface

Note:

$$(\xi; q)_\infty = \prod_{k=0}^{\infty} (1 - q^k \xi)$$

$$\theta_q(\xi) = (\xi; q)_\infty (q/\xi; q)_\infty$$

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N. Joshi and P.  
Roffelsen, *Commun.  
Math. Phys* (2021)  
arXiv:1911.05854

# $qP_{VI}$

$qP(A_3^{(1)})$

$$\begin{cases} f\bar{f} &= \frac{(\bar{g} - \kappa_0 t)(\bar{g} - \kappa_0^{-1} t)}{(\bar{g} - \kappa_\infty)(\bar{g} - q^{-1} \kappa_\infty^{-1})}, \\ g\bar{g} &= \frac{(f - \kappa_t t)(f - \kappa_t^{-1} t)}{q(f - \kappa_1)(f - \kappa_1^{-1})}, \end{cases}$$

$$q \in \mathbb{C}, 0 < |q| < 1, \bar{f} = f(qt), \bar{g} = g(qt)$$

*Jimbo, Sakai 1996*

# Continuum limit of $qP_{VI}$

$$q \rightarrow 1, \kappa_j = q^{k_j}, f \rightarrow u, g \rightarrow (u - t)/(u - 1)$$

$$\alpha = \frac{(2k_\infty + 1)^2}{2}, \quad \beta = -2k_0^2, \quad \gamma = 2k_1^2, \quad \delta = \frac{1 - 4k_t^2}{2}$$



$$u_{tt} = \left( \frac{1}{u} + \frac{1}{u-1} + \frac{1}{u-t} \right) \frac{u_t^2}{2} - \left( \frac{1}{t} + \frac{1}{t-1} + \frac{1}{u-t} \right) u_t$$

$$+ \frac{u(u-1)(u-t)}{t^2(t-1)^2} \left( \alpha + \frac{\beta t}{u^2} + \frac{\gamma(t-1)}{(u-1)^2} + \frac{\delta t(t-1)}{(u-t)^2} \right)$$

$P_{VI}$  the sixth Painlevé equation

# $qP_{VI}$ -monodromy surface

The  $q$ -monodromy surface for  $qP_{VI}$  is given by two equations  $T = 0$ , where one is

$$T := T_{12}p_1p_2 + T_{13}p_1p_3 + T_{14}p_1p_4 + T_{23}p_2p_3 + T_{24}p_2p_4 + T_{34}p_3p_4$$

$$T_{12} = \theta_q(\kappa_t^2, \kappa_1^2) \theta_q(\kappa_0 \kappa_\infty^{-1} t_0, \kappa_0^{-1} \kappa_\infty^{-1} t_0) \kappa_\infty^2,$$

$$T_{34} = \theta_q(\kappa_t^2, \kappa_1^2) \theta_q(\kappa_0 \kappa_\infty t_0, \kappa_0^{-1} \kappa_\infty t_0),$$

$$T_{13} = -\theta_q(\kappa_t \kappa_1^{-1} t_0, \kappa_t^{-1} \kappa_1 t_0) \theta_q(\kappa_t \kappa_1 \kappa_0^{-1} \kappa_\infty^{-1}, \kappa_0 \kappa_t \kappa_1 \kappa_\infty^{-1}) \kappa_\infty^2,$$

$$T_{24} = -\theta_q(\kappa_t \kappa_1^{-1} t_0, \kappa_t^{-1} \kappa_1 t_0) \theta_q(\kappa_0 \kappa_t \kappa_1 \kappa_\infty, \kappa_t \kappa_1 \kappa_\infty \kappa_0^{-1}),$$

$$T_{23} = \theta_q(\kappa_t \kappa_1 t_0, \kappa_t^{-1} \kappa_1^{-1} t_0) \theta_q(\kappa_t \kappa_\infty \kappa_0^{-1} \kappa_1^{-1}, \kappa_0 \kappa_t \kappa_\infty \kappa_1^{-1}) \kappa_1^2,$$

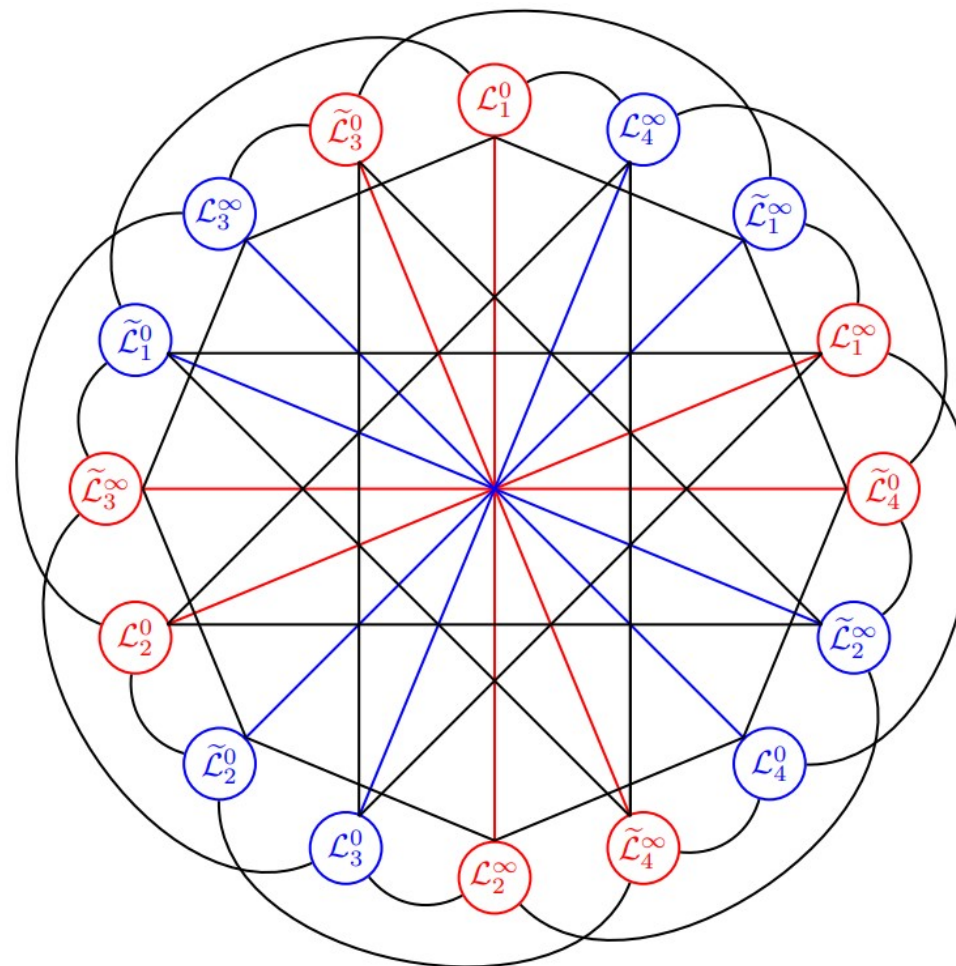
$$T_{14} = \theta_q(\kappa_t \kappa_1 t_0, \kappa_t^{-1} \kappa_1^{-1} t_0) \theta_q(\kappa_1 \kappa_\infty \kappa_0^{-1} \kappa_t^{-1}, \kappa_0 \kappa_1 \kappa_\infty \kappa_t^{-1}) \kappa_t^2.$$

This is a *Segre surface*.

N. J. and P. Roffelsen, On the monodromy manifold of  $q$ -Painlevé VI and its Riemann-Hilbert problem,  
arXiv:2202.10597

# $qP_{VI}$ -monodromy surface, ct'd

- The Segre surface contains 16 lines.

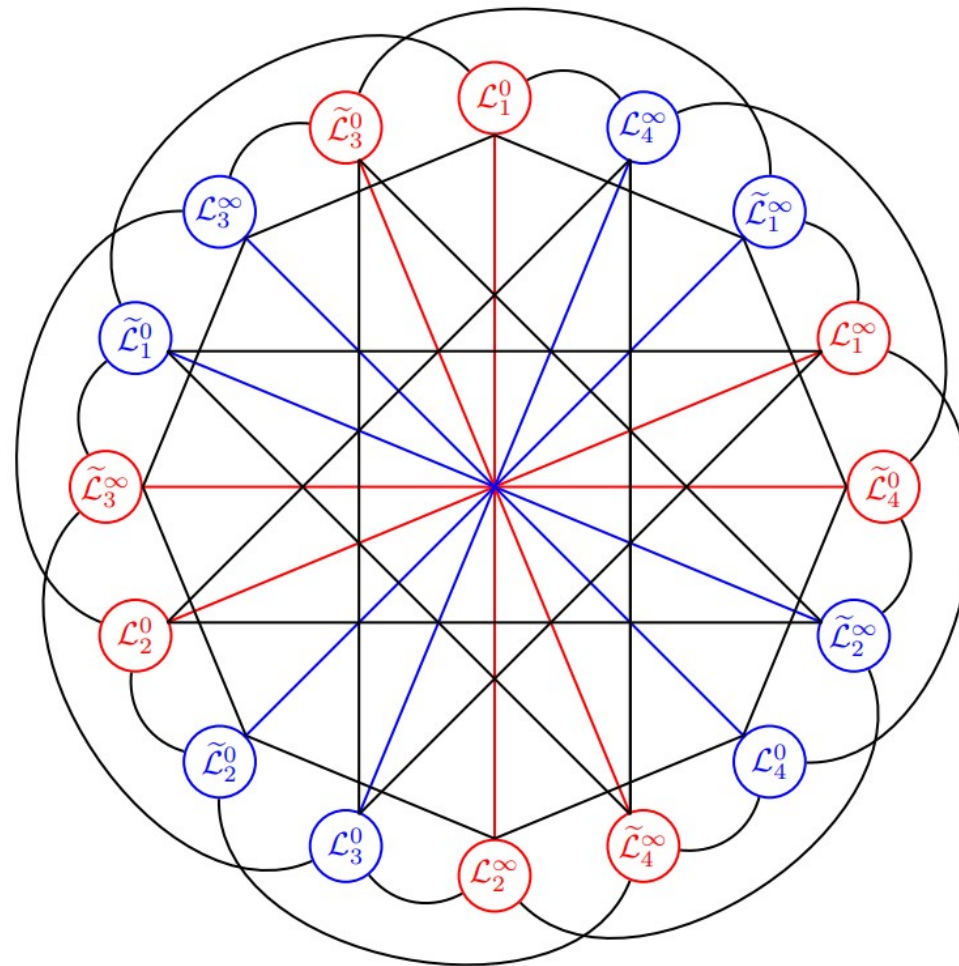


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N. Joshi and P. Roffelsen, *in preparation*.



**The journey is far from over...**



*Royal Australian Historical Society, No restrictions, via Wikimedia Commons*



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- What are the behaviours of solutions of the elliptic-difference Painlevé equation?

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